

# R&S® SGU100A

## SGMA Upconverter

### User Manual



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This document describes the R&S®SGU100A, stock no. 1418.2005.02 and its options.

- R&S®SGU-B26 (1418.3401.02)
- R&S®SGU-B120/120V (1418.2605.02/1418.2657.02)
- R&S®SGU-B140/140V (1418.2870.02/1418.2928.02 )

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The following abbreviations are used throughout this manual: R&S®SGU100A is abbreviated as R&S SGU, R&S®SGS100A is abbreviated as R&S SGS, R&S®SGMA-GUI is abbreviated as R&S SGMA-GUI, R&S®FSW is abbreviated as R&S FSW.

# Basic Safety Instructions

## Always read through and comply with the following safety instructions!

All plants and locations of the Rohde & Schwarz group of companies make every effort to keep the safety standards of our products up to date and to offer our customers the highest possible degree of safety. Our products and the auxiliary equipment they require are designed, built and tested in accordance with the safety standards that apply in each case. Compliance with these standards is continuously monitored by our quality assurance system. The product described here has been designed, built and tested in accordance with the EC Certificate of Conformity and has left the manufacturer's plant in a condition fully complying with safety standards. To maintain this condition and to ensure safe operation, you must observe all instructions and warnings provided in this manual. If you have any questions regarding these safety instructions, the Rohde & Schwarz group of companies will be happy to answer them.

Furthermore, it is your responsibility to use the product in an appropriate manner. This product is designed for use solely in industrial and laboratory environments or, if expressly permitted, also in the field and must not be used in any way that may cause personal injury or property damage. You are responsible if the product is used for any purpose other than its designated purpose or in disregard of the manufacturer's instructions. The manufacturer shall assume no responsibility for such use of the product.

The product is used for its designated purpose if it is used in accordance with its product documentation and within its performance limits (see data sheet, documentation, the following safety instructions). Using the product requires technical skills and, in some cases, a basic knowledge of English. It is therefore essential that only skilled and specialized staff or thoroughly trained personnel with the required skills be allowed to use the product. If personal safety gear is required for using Rohde & Schwarz products, this will be indicated at the appropriate place in the product documentation. Keep the basic safety instructions and the product documentation in a safe place and pass them on to the subsequent users.

Observing the safety instructions will help prevent personal injury or damage of any kind caused by dangerous situations. Therefore, carefully read through and adhere to the following safety instructions before and when using the product. It is also absolutely essential to observe the additional safety instructions on personal safety, for example, that appear in relevant parts of the product documentation. In these safety instructions, the word "product" refers to all merchandise sold and distributed by the Rohde & Schwarz group of companies, including instruments, systems and all accessories. For product-specific information, see the data sheet and the product documentation.

## Safety labels on products

The following safety labels are used on products to warn against risks and dangers.

Symbol	Meaning	Symbol	Meaning
	Notice, general danger location Observe product documentation		ON/OFF Power
	Caution when handling heavy equipment		Standby indication
	Danger of electric shock		Direct current (DC)

## Basic Safety Instructions

Symbol	Meaning	Symbol	Meaning
	Caution ! Hot surface		Alternating current (AC)
	Protective conductor terminal To identify any terminal which is intended for connection to an external conductor for protection against electric shock in case of a fault, or the terminal of a protective earth		Direct/alternating current (DC/AC)
	Earth (Ground)		Class II Equipment to identify equipment meeting the safety requirements specified for Class II equipment (device protected by double or reinforced insulation)
	Frame or chassis Ground terminal		EU labeling for batteries and accumulators For additional information, see section "Waste disposal/Environmental protection", item 1.
	Be careful when handling electrostatic sensitive devices		EU labeling for separate collection of electrical and electronic devices For additional information, see section "Waste disposal/Environmental protection", item 2.
	Warning! Laser radiation For additional information, see section "Operation", item 7.		

### Signal words and their meaning

The following signal words are used in the product documentation in order to warn the reader about risks and dangers.



Indicates a hazardous situation which, if not avoided, will result in death or serious injury.



Indicates a hazardous situation which, if not avoided, could result in death or serious injury.



Indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.



Indicates information considered important, but not hazard-related, e.g. messages relating to property damage.  
In the product documentation, the word ATTENTION is used synonymously.

These signal words are in accordance with the standard definition for civil applications in the European Economic Area. Definitions that deviate from the standard definition may also exist in other economic areas or military applications. It is therefore essential to make sure that the signal words described here are always used only in connection with the related product documentation and the related product. The use of signal words in connection with unrelated products or documentation can result in misinterpretation and in personal injury or material damage.

## Basic Safety Instructions

### Operating states and operating positions

*The product may be operated only under the operating conditions and in the positions specified by the manufacturer, without the product's ventilation being obstructed. If the manufacturer's specifications are not observed, this can result in electric shock, fire and/or serious personal injury or death. Applicable local or national safety regulations and rules for the prevention of accidents must be observed in all work performed.*

1. Unless otherwise specified, the following requirements apply to Rohde & Schwarz products: predefined operating position is always with the housing floor facing down, IP protection 2X, use only indoors, max. operating altitude 2000 m above sea level, max. transport altitude 4500 m above sea level. A tolerance of  $\pm 10\%$  shall apply to the nominal voltage and  $\pm 5\%$  to the nominal frequency, overvoltage category 2, pollution degree 2.
2. Do not place the product on surfaces, vehicles, cabinets or tables that for reasons of weight or stability are unsuitable for this purpose. Always follow the manufacturer's installation instructions when installing the product and fastening it to objects or structures (e.g. walls and shelves). An installation that is not carried out as described in the product documentation could result in personal injury or even death.
3. Do not place the product on heat-generating devices such as radiators or fan heaters. The ambient temperature must not exceed the maximum temperature specified in the product documentation or in the data sheet. Product overheating can cause electric shock, fire and/or serious personal injury or even death.

### Electrical safety

*If the information on electrical safety is not observed either at all or to the extent necessary, electric shock, fire and/or serious personal injury or death may occur.*

1. Prior to switching on the product, always ensure that the nominal voltage setting on the product matches the nominal voltage of the mains-supply network. If a different voltage is to be set, the power fuse of the product may have to be changed accordingly.
2. In the case of products of safety class I with movable power cord and connector, operation is permitted only on sockets with a protective conductor contact and protective conductor.
3. Intentionally breaking the protective conductor either in the feed line or in the product itself is not permitted. Doing so can result in the danger of an electric shock from the product. If extension cords or connector strips are implemented, they must be checked on a regular basis to ensure that they are safe to use.
4. If there is no power switch for disconnecting the product from the mains, or if the power switch is not suitable for this purpose, use the plug of the connecting cable to disconnect the product from the mains. In such cases, always ensure that the power plug is easily reachable and accessible at all times. For example, if the power plug is the disconnecting device, the length of the connecting cable must not exceed 3 m. Functional or electronic switches are not suitable for providing disconnection from the AC supply network. If products without power switches are integrated into racks or systems, the disconnecting device must be provided at the system level.
5. Never use the product if the power cable is damaged. Check the power cables on a regular basis to ensure that they are in proper operating condition. By taking appropriate safety measures and carefully laying the power cable, ensure that the cable cannot be damaged and that no one can be hurt by, for example, tripping over the cable or suffering an electric shock.

## Basic Safety Instructions

6. The product may be operated only from TN/TT supply networks fuse-protected with max. 16 A (higher fuse only after consulting with the Rohde & Schwarz group of companies).
7. Do not insert the plug into sockets that are dusty or dirty. Insert the plug firmly and all the way into the socket provided for this purpose. Otherwise, sparks that result in fire and/or injuries may occur.
8. Do not overload any sockets, extension cords or connector strips; doing so can cause fire or electric shocks.
9. For measurements in circuits with voltages  $V_{rms} > 30$  V, suitable measures (e.g. appropriate measuring equipment, fuse protection, current limiting, electrical separation, insulation) should be taken to avoid any hazards.
10. Ensure that the connections with information technology equipment, e.g. PCs or other industrial computers, comply with the IEC 60950-1 / EN 60950-1 or IEC 61010-1 / EN 61010-1 standards that apply in each case.
11. Unless expressly permitted, never remove the cover or any part of the housing while the product is in operation. Doing so will expose circuits and components and can lead to injuries, fire or damage to the product.
12. If a product is to be permanently installed, the connection between the protective conductor terminal on site and the product's protective conductor must be made first before any other connection is made. The product may be installed and connected only by a licensed electrician.
13. For permanently installed equipment without built-in fuses, circuit breakers or similar protective devices, the supply circuit must be fuse-protected in such a way that anyone who has access to the product, as well as the product itself, is adequately protected from injury or damage.
14. Use suitable overvoltage protection to ensure that no overvoltage (such as that caused by a bolt of lightning) can reach the product. Otherwise, the person operating the product will be exposed to the danger of an electric shock.
15. Any object that is not designed to be placed in the openings of the housing must not be used for this purpose. Doing so can cause short circuits inside the product and/or electric shocks, fire or injuries.
16. Unless specified otherwise, products are not liquid-proof (see also section "Operating states and operating positions", item 1). Therefore, the equipment must be protected against penetration by liquids. If the necessary precautions are not taken, the user may suffer electric shock or the product itself may be damaged, which can also lead to personal injury.
17. Never use the product under conditions in which condensation has formed or can form in or on the product, e.g. if the product has been moved from a cold to a warm environment. Penetration by water increases the risk of electric shock.
18. Prior to cleaning the product, disconnect it completely from the power supply (e.g. AC supply network or battery). Use a soft, non-linting cloth to clean the product. Never use chemical cleaning agents such as alcohol, acetone or diluents for cellulose lacquers.

## Operation

1. Operating the products requires special training and intense concentration. Make sure that persons who use the products are physically, mentally and emotionally fit enough to do so; otherwise, injuries or material damage may occur. It is the responsibility of the employer/operator to select suitable personnel for operating the products.

## Basic Safety Instructions

2. Before you move or transport the product, read and observe the section titled "Transport".
3. As with all industrially manufactured goods, the use of substances that induce an allergic reaction (allergens) such as nickel cannot be generally excluded. If you develop an allergic reaction (such as a skin rash, frequent sneezing, red eyes or respiratory difficulties) when using a Rohde & Schwarz product, consult a physician immediately to determine the cause and to prevent health problems or stress.
4. Before you start processing the product mechanically and/or thermally, or before you take it apart, be sure to read and pay special attention to the section titled "Waste disposal/Environmental protection", item 1.
5. Depending on the function, certain products such as RF radio equipment can produce an elevated level of electromagnetic radiation. Considering that unborn babies require increased protection, pregnant women must be protected by appropriate measures. Persons with pacemakers may also be exposed to risks from electromagnetic radiation. The employer/operator must evaluate workplaces where there is a special risk of exposure to radiation and, if necessary, take measures to avert the potential danger.
6. Should a fire occur, the product may release hazardous substances (gases, fluids, etc.) that can cause health problems. Therefore, suitable measures must be taken, e.g. protective masks and protective clothing must be worn.
7. Laser products are given warning labels that are standardized according to their laser class. Lasers can cause biological harm due to the properties of their radiation and due to their extremely concentrated electromagnetic power. If a laser product (e.g. a CD/DVD drive) is integrated into a Rohde & Schwarz product, absolutely no other settings or functions may be used as described in the product documentation. The objective is to prevent personal injury (e.g. due to laser beams).
8. EMC classes (in line with EN 55011/CISPR 11, and analogously with EN 55022/CISPR 22, EN 55032/CISPR 32)
  - Class A equipment:  
Equipment suitable for use in all environments except residential environments and environments that are directly connected to a low-voltage supply network that supplies residential buildings  
Note: Class A equipment is intended for use in an industrial environment. This equipment may cause radio disturbances in residential environments, due to possible conducted as well as radiated disturbances. In this case, the operator may be required to take appropriate measures to eliminate these disturbances.
  - Class B equipment:  
Equipment suitable for use in residential environments and environments that are directly connected to a low-voltage supply network that supplies residential buildings

### Repair and service

1. The product may be opened only by authorized, specially trained personnel. Before any work is performed on the product or before the product is opened, it must be disconnected from the AC supply network. Otherwise, personnel will be exposed to the risk of an electric shock.

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- Adjustments, replacement of parts, maintenance and repair may be performed only by electrical experts authorized by Rohde & Schwarz. Only original parts may be used for replacing parts relevant to safety (e.g. power switches, power transformers, fuses). A safety test must always be performed after parts relevant to safety have been replaced (visual inspection, protective conductor test, insulation resistance measurement, leakage current measurement, functional test). This helps ensure the continued safety of the product.

### Batteries and rechargeable batteries/cells

*If the information regarding batteries and rechargeable batteries/cells is not observed either at all or to the extent necessary, product users may be exposed to the risk of explosions, fire and/or serious personal injury, and, in some cases, death. Batteries and rechargeable batteries with alkaline electrolytes (e.g. lithium cells) must be handled in accordance with the EN 62133 standard.*

- Cells must not be taken apart or crushed.
- Cells or batteries must not be exposed to heat or fire. Storage in direct sunlight must be avoided. Keep cells and batteries clean and dry. Clean soiled connectors using a dry, clean cloth.
- Cells or batteries must not be short-circuited. Cells or batteries must not be stored in a box or in a drawer where they can short-circuit each other, or where they can be short-circuited by other conductive materials. Cells and batteries must not be removed from their original packaging until they are ready to be used.
- Cells and batteries must not be exposed to any mechanical shocks that are stronger than permitted.
- If a cell develops a leak, the fluid must not be allowed to come into contact with the skin or eyes. If contact occurs, wash the affected area with plenty of water and seek medical aid.
- Improperly replacing or charging cells or batteries that contain alkaline electrolytes (e.g. lithium cells) can cause explosions. Replace cells or batteries only with the matching Rohde & Schwarz type (see parts list) in order to ensure the safety of the product.
- Cells and batteries must be recycled and kept separate from residual waste. Rechargeable batteries and normal batteries that contain lead, mercury or cadmium are hazardous waste. Observe the national regulations regarding waste disposal and recycling.

### Transport

- The product may be very heavy. Therefore, the product must be handled with care. In some cases, the user may require a suitable means of lifting or moving the product (e.g. with a lift-truck) to avoid back or other physical injuries.
- Handles on the products are designed exclusively to enable personnel to transport the product. It is therefore not permissible to use handles to fasten the product to or on transport equipment such as cranes, fork lifts, wagons, etc. The user is responsible for securely fastening the products to or on the means of transport or lifting. Observe the safety regulations of the manufacturer of the means of transport or lifting. Noncompliance can result in personal injury or material damage.
- If you use the product in a vehicle, it is the sole responsibility of the driver to drive the vehicle safely and properly. The manufacturer assumes no responsibility for accidents or collisions. Never use the product in a moving vehicle if doing so could distract the driver of the vehicle. Adequately secure the product in the vehicle to prevent injuries or other damage in the event of an accident.



## Instrucciones de seguridad elementales

### Waste disposal/Environmental protection

1. Specially marked equipment has a battery or accumulator that must not be disposed of with unsorted municipal waste, but must be collected separately. It may only be disposed of at a suitable collection point or via a Rohde & Schwarz customer service center.
2. Waste electrical and electronic equipment must not be disposed of with unsorted municipal waste, but must be collected separately.  
Rohde & Schwarz GmbH & Co. KG has developed a disposal concept and takes full responsibility for take-back obligations and disposal obligations for manufacturers within the EU. Contact your Rohde & Schwarz customer service center for environmentally responsible disposal of the product.
3. If products or their components are mechanically and/or thermally processed in a manner that goes beyond their intended use, hazardous substances (heavy-metal dust such as lead, beryllium, nickel) may be released. For this reason, the product may only be disassembled by specially trained personnel. Improper disassembly may be hazardous to your health. National waste disposal regulations must be observed.
4. If handling the product releases hazardous substances or fuels that must be disposed of in a special way, e.g. coolants or engine oils that must be replenished regularly, the safety instructions of the manufacturer of the hazardous substances or fuels and the applicable regional waste disposal regulations must be observed. Also observe the relevant safety instructions in the product documentation. The improper disposal of hazardous substances or fuels can cause health problems and lead to environmental damage.

For additional information about environmental protection, visit the Rohde & Schwarz website.

## Instrucciones de seguridad elementales

### **¡Es imprescindible leer y cumplir las siguientes instrucciones e informaciones de seguridad!**

El principio del grupo de empresas Rohde & Schwarz consiste en tener nuestros productos siempre al día con los estándares de seguridad y de ofrecer a nuestros clientes el máximo grado de seguridad. Nuestros productos y todos los equipos adicionales son siempre fabricados y examinados según las normas de seguridad vigentes. Nuestro sistema de garantía de calidad controla constantemente que sean cumplidas estas normas. El presente producto ha sido fabricado y examinado según el certificado de conformidad de la UE y ha salido de nuestra planta en estado impecable según los estándares técnicos de seguridad. Para poder preservar este estado y garantizar un funcionamiento libre de peligros, el usuario deberá atenerse a todas las indicaciones, informaciones de seguridad y notas de alerta. El grupo de empresas Rohde & Schwarz está siempre a su disposición en caso de que tengan preguntas referentes a estas informaciones de seguridad.

Además queda en la responsabilidad del usuario utilizar el producto en la forma debida. Este producto está destinado exclusivamente al uso en la industria y el laboratorio o, si ha sido expresamente autorizado, para aplicaciones de campo y de ninguna manera deberá ser utilizado de modo que alguna persona/cosa pueda sufrir daño. El uso del producto fuera de sus fines definidos o sin tener en cuenta las instrucciones del fabricante queda en la responsabilidad del usuario. El fabricante no se hace en ninguna forma responsable de consecuencias a causa del mal uso del producto.















## Instrucciones de seguridad elementales

Se parte del uso correcto del producto para los fines definidos si el producto es utilizado conforme a las indicaciones de la correspondiente documentación del producto y dentro del margen de rendimiento definido (ver hoja de datos, documentación, informaciones de seguridad que siguen). El uso del producto hace necesarios conocimientos técnicos y ciertos conocimientos del idioma inglés. Por eso se debe tener en cuenta que el producto solo pueda ser operado por personal especializado o personas instruidas en profundidad con las capacidades correspondientes. Si fuera necesaria indumentaria de seguridad para el uso de productos de Rohde & Schwarz, encontraría la información debida en la documentación del producto en el capítulo correspondiente. Guarde bien las informaciones de seguridad elementales, así como la documentación del producto, y entréguelas a usuarios posteriores.

Tener en cuenta las informaciones de seguridad sirve para evitar en lo posible lesiones o daños por peligros de toda clase. Por eso es imprescindible leer detalladamente y comprender por completo las siguientes informaciones de seguridad antes de usar el producto, y respetarlas durante el uso del producto. Deberán tenerse en cuenta todas las demás informaciones de seguridad, como p. ej. las referentes a la protección de personas, que encontrarán en el capítulo correspondiente de la documentación del producto y que también son de obligado cumplimiento. En las presentes informaciones de seguridad se recogen todos los objetos que distribuye el grupo de empresas Rohde & Schwarz bajo la denominación de "producto", entre ellos también aparatos, instalaciones así como toda clase de accesorios. Los datos específicos del producto figuran en la hoja de datos y en la documentación del producto.

### Señalización de seguridad de los productos

Las siguientes señales de seguridad se utilizan en los productos para advertir sobre riesgos y peligros.

Símbolo	Significado	Símbolo	Significado
	Aviso: punto de peligro general Observar la documentación del producto		Tensión de alimentación de PUESTA EN MARCHA / PARADA
	Atención en el manejo de dispositivos de peso elevado		Indicación de estado de espera (standby)
	Peligro de choque eléctrico		Corriente continua (DC)
	Advertencia: superficie caliente		Corriente alterna (AC)
	Conexión a conductor de protección		Corriente continua / Corriente alterna (DC/AC)
	Conexión a tierra		El aparato está protegido en su totalidad por un aislamiento doble (reforzado)
	Conexión a masa		Distintivo de la UE para baterías y acumuladores Más información en la sección "Eliminación/protección del medio ambiente", punto 1.

## Instrucciones de seguridad elementales

Símbolo	Significado	Símbolo	Significado
	Aviso: Cuidado en el manejo de dispositivos sensibles a la electrostática (ESD)		Distintivo de la UE para la eliminación por separado de dispositivos eléctricos y electrónicos  Más información en la sección "Eliminación/protección del medio ambiente", punto 2.
	Advertencia: rayo láser  Más información en la sección "Funcionamiento", punto 7.		

### Palabras de señal y su significado

En la documentación del producto se utilizan las siguientes palabras de señal con el fin de advertir contra riesgos y peligros.



Indica una situación de peligro que, si no se evita, causa lesiones graves o incluso la muerte.



Indica una situación de peligro que, si no se evita, puede causar lesiones graves o incluso la muerte.



Indica una situación de peligro que, si no se evita, puede causar lesiones leves o moderadas.



Indica información que se considera importante, pero no en relación con situaciones de peligro; p. ej., avisos sobre posibles daños materiales.

En la documentación del producto se emplea de forma sinónima el término CUIDADO.

Las palabras de señal corresponden a la definición habitual para aplicaciones civiles en el área económica europea. Pueden existir definiciones diferentes a esta definición en otras áreas económicas o en aplicaciones militares. Por eso se deberá tener en cuenta que las palabras de señal aquí descritas sean utilizadas siempre solamente en combinación con la correspondiente documentación del producto y solamente en combinación con el producto correspondiente. La utilización de las palabras de señal en combinación con productos o documentaciones que no les correspondan puede llevar a interpretaciones equivocadas y tener por consecuencia daños en personas u objetos.

### Estados operativos y posiciones de funcionamiento

*El producto solamente debe ser utilizado según lo indicado por el fabricante respecto a los estados operativos y posiciones de funcionamiento sin que se obstruya la ventilación. Si no se siguen las indicaciones del fabricante, pueden producirse choques eléctricos, incendios y/o lesiones graves con posible consecuencia de muerte. En todos los trabajos deberán ser tenidas en cuenta las normas nacionales y locales de seguridad del trabajo y de prevención de accidentes.*

## Instrucciones de seguridad elementales

1. Si no se convino de otra manera, es para los productos Rohde & Schwarz válido lo que sigue: como posición de funcionamiento se define por principio la posición con el suelo de la caja para abajo, modo de protección IP 2X, uso solamente en estancias interiores, utilización hasta 2000 m sobre el nivel del mar, transporte hasta 4500 m sobre el nivel del mar. Se aplicará una tolerancia de  $\pm 10\%$  sobre el voltaje nominal y de  $\pm 5\%$  sobre la frecuencia nominal. Categoría de sobrecarga eléctrica 2, índice de suciedad 2.
2. No sitúe el producto encima de superficies, vehículos, estantes o mesas, que por sus características de peso o de estabilidad no sean aptos para él. Siga siempre las instrucciones de instalación del fabricante cuando instale y asegure el producto en objetos o estructuras (p. ej. paredes y estantes). Si se realiza la instalación de modo distinto al indicado en la documentación del producto, se pueden causar lesiones o, en determinadas circunstancias, incluso la muerte.
3. No ponga el producto sobre aparatos que generen calor (p. ej. radiadores o calefactores). La temperatura ambiente no debe superar la temperatura máxima especificada en la documentación del producto o en la hoja de datos. En caso de sobrecalentamiento del producto, pueden producirse choques eléctricos, incendios y/o lesiones graves con posible consecuencia de muerte.

### Seguridad eléctrica

*Si no se siguen (o se siguen de modo insuficiente) las indicaciones del fabricante en cuanto a seguridad eléctrica, pueden producirse choques eléctricos, incendios y/o lesiones graves con posible consecuencia de muerte.*

1. Antes de la puesta en marcha del producto se deberá comprobar siempre que la tensión preseleccionada en el producto coincida con la de la red de alimentación eléctrica. Si es necesario modificar el ajuste de tensión, también se deberán cambiar en caso dado los fusibles correspondientes del producto.
2. Los productos de la clase de protección I con alimentación móvil y enchufe individual solamente podrán enchufarse a tomas de corriente con contacto de seguridad y con conductor de protección conectado.
3. Queda prohibida la interrupción intencionada del conductor de protección, tanto en la toma de corriente como en el mismo producto. La interrupción puede tener como consecuencia el riesgo de que el producto sea fuente de choques eléctricos. Si se utilizan cables alargadores o regletas de enchufe, deberá garantizarse la realización de un examen regular de los mismos en cuanto a su estado técnico de seguridad.
4. Si el producto no está equipado con un interruptor para desconectarlo de la red, o bien si el interruptor existente no resulta apropiado para la desconexión de la red, el enchufe del cable de conexión se deberá considerar como un dispositivo de desconexión. El dispositivo de desconexión se debe poder alcanzar fácilmente y debe estar siempre bien accesible. Si, p. ej., el enchufe de conexión a la red es el dispositivo de desconexión, la longitud del cable de conexión no debe superar 3 m). Los interruptores selectores o electrónicos no son aptos para el corte de la red eléctrica. Si se integran productos sin interruptor en bastidores o instalaciones, se deberá colocar el interruptor en el nivel de la instalación.
5. No utilice nunca el producto si está dañado el cable de conexión a red. Compruebe regularmente el correcto estado de los cables de conexión a red. Asegúrese, mediante las medidas de protección y de instalación adecuadas, de que el cable de conexión a red no pueda ser dañado o de que nadie pueda ser dañado por él, p. ej. al tropezar o por un choque eléctrico.

## Instrucciones de seguridad elementales

6. Solamente está permitido el funcionamiento en redes de alimentación TN/TT aseguradas con fusibles de 16 A como máximo (utilización de fusibles de mayor amperaje solo previa consulta con el grupo de empresas Rohde & Schwarz).
7. Nunca conecte el enchufe en tomas de corriente sucias o llenas de polvo. Introduzca el enchufe por completo y fuertemente en la toma de corriente. La no observación de estas medidas puede provocar chispas, fuego y/o lesiones.
8. No sobrecargue las tomas de corriente, los cables alargadores o las regletas de enchufe ya que esto podría causar fuego o choques eléctricos.
9. En las mediciones en circuitos de corriente con una tensión  $U_{\text{eff}} > 30 \text{ V}$  se deberán tomar las medidas apropiadas para impedir cualquier peligro (p. ej. medios de medición adecuados, seguros, limitación de tensión, corte protector, aislamiento etc.).
10. Para la conexión con dispositivos informáticos como un PC o un ordenador industrial, debe comprobarse que éstos cumplan los estándares IEC60950-1/EN60950-1 o IEC61010-1/EN 61010-1 válidos en cada caso.
11. A menos que esté permitido expresamente, no retire nunca la tapa ni componentes de la carcasa mientras el producto esté en servicio. Esto pone a descubierto los cables y componentes eléctricos y puede causar lesiones, fuego o daños en el producto.
12. Si un producto se instala en un lugar fijo, se deberá primero conectar el conductor de protección fijo con el conductor de protección del producto antes de hacer cualquier otra conexión. La instalación y la conexión deberán ser efectuadas por un electricista especializado.
13. En el caso de dispositivos fijos que no estén provistos de fusibles, interruptor automático ni otros mecanismos de seguridad similares, el circuito de alimentación debe estar protegido de modo que todas las personas que puedan acceder al producto, así como el producto mismo, estén a salvo de posibles daños.
14. Todo producto debe estar protegido contra sobretensión (debida p. ej. a una caída del rayo) mediante los correspondientes sistemas de protección. Si no, el personal que lo utilice quedará expuesto al peligro de choque eléctrico.
15. No debe introducirse en los orificios de la caja del aparato ningún objeto que no esté destinado a ello. Esto puede producir cortocircuitos en el producto y/o puede causar choques eléctricos, fuego o lesiones.
16. Salvo indicación contraria, los productos no están impermeabilizados (ver también el capítulo "Estados operativos y posiciones de funcionamiento", punto 1). Por eso es necesario tomar las medidas necesarias para evitar la entrada de líquidos. En caso contrario, existe peligro de choque eléctrico para el usuario o de daños en el producto, que también pueden redundar en peligro para las personas.
17. No utilice el producto en condiciones en las que pueda producirse o ya se hayan producido condensaciones sobre el producto o en el interior de éste, como p. ej. al desplazarlo de un lugar frío a otro caliente. La entrada de agua aumenta el riesgo de choque eléctrico.
18. Antes de la limpieza, desconecte por completo el producto de la alimentación de tensión (p. ej. red de alimentación o batería). Realice la limpieza de los aparatos con un paño suave, que no se deshilache. No utilice bajo ningún concepto productos de limpieza químicos como alcohol, acetona o diluyentes para lacas nitrocelulósicas.

## Instrucciones de seguridad elementales

### Funcionamiento

1. El uso del producto requiere instrucciones especiales y una alta concentración durante el manejo. Debe asegurarse que las personas que manejen el producto estén a la altura de los requerimientos necesarios en cuanto a aptitudes físicas, psíquicas y emocionales, ya que de otra manera no se pueden excluir lesiones o daños de objetos. El empresario u operador es responsable de seleccionar el personal usuario apto para el manejo del producto.
2. Antes de desplazar o transportar el producto, lea y tenga en cuenta el capítulo "Transporte".
3. Como con todo producto de fabricación industrial no puede quedar excluida en general la posibilidad de que se produzcan alergias provocadas por algunos materiales empleados —los llamados alérgenos (p. ej. el níquel)—. Si durante el manejo de productos Rohde & Schwarz se producen reacciones alérgicas, como p. ej. irritaciones cutáneas, estornudos continuos, enrojecimiento de la conjuntiva o dificultades respiratorias, debe avisarse inmediatamente a un médico para investigar las causas y evitar cualquier molestia o daño a la salud.
4. Antes de la manipulación mecánica y/o térmica o el desmontaje del producto, debe tenerse en cuenta imprescindiblemente el capítulo "Eliminación/protección del medio ambiente", punto 1.
5. Ciertos productos, como p. ej. las instalaciones de radiocomunicación RF, pueden a causa de su función natural, emitir una radiación electromagnética aumentada. Deben tomarse todas las medidas necesarias para la protección de las mujeres embarazadas. También las personas con marcapasos pueden correr peligro a causa de la radiación electromagnética. El empresario/operador tiene la obligación de evaluar y señalar las áreas de trabajo en las que exista un riesgo elevado de exposición a radiaciones.
6. Tenga en cuenta que en caso de incendio pueden desprenderse del producto sustancias tóxicas (gases, líquidos etc.) que pueden generar daños a la salud. Por eso, en caso de incendio deben usarse medidas adecuadas, como p. ej. máscaras antigás e indumentaria de protección.
7. Los productos con láser están provistos de indicaciones de advertencia normalizadas en función de la clase de láser del que se trate. Los rayos láser pueden provocar daños de tipo biológico a causa de las propiedades de su radiación y debido a su concentración extrema de potencia electromagnética. En caso de que un producto Rohde & Schwarz contenga un producto láser (p. ej. un lector de CD/DVD), no debe usarse ninguna otra configuración o función aparte de las descritas en la documentación del producto, a fin de evitar lesiones (p. ej. debidas a irradiación láser).
8. Clases de compatibilidad electromagnética (conforme a EN 55011 / CISPR 11; y en analogía con EN 55022 / CISPR 22, EN 55032 / CISPR 32)
  - Aparato de clase A:  
Aparato adecuado para su uso en todos los entornos excepto en los residenciales y en aquellos conectados directamente a una red de distribución de baja tensión que suministra corriente a edificios residenciales.  
Nota: Los aparatos de clase A están destinados al uso en entornos industriales. Estos aparatos pueden causar perturbaciones radioeléctricas en entornos residenciales debido a posibles perturbaciones guiadas o radiadas. En este caso, se le podrá solicitar al operador que tome las medidas adecuadas para eliminar estas perturbaciones.
  - Aparato de clase B:  
Aparato adecuado para su uso en entornos residenciales, así como en aquellos conectados directamente a una red de distribución de baja tensión que suministra corriente a edificios residenciales.

## Instrucciones de seguridad elementales

### Reparación y mantenimiento

1. El producto solamente debe ser abierto por personal especializado con autorización para ello. Antes de manipular el producto o abrirlo, es obligatorio desconectarlo de la tensión de alimentación, para evitar toda posibilidad de choque eléctrico.
2. El ajuste, el cambio de partes, el mantenimiento y la reparación deberán ser efectuadas solamente por electricistas autorizados por Rohde & Schwarz. Si se reponen partes con importancia para los aspectos de seguridad (p. ej. el enchufe, los transformadores o los fusibles), solamente podrán ser sustituidos por partes originales. Después de cada cambio de partes relevantes para la seguridad deberá realizarse un control de seguridad (control a primera vista, control del conductor de protección, medición de resistencia de aislamiento, medición de la corriente de fuga, control de funcionamiento). Con esto queda garantizada la seguridad del producto.

### Baterías y acumuladores o celdas

*Si no se siguen (o se siguen de modo insuficiente) las indicaciones en cuanto a las baterías y acumuladores o celdas, pueden producirse explosiones, incendios y/o lesiones graves con posible consecuencia de muerte. El manejo de baterías y acumuladores con electrolitos alcalinos (p. ej. celdas de litio) debe seguir el estándar EN 62133.*

1. No deben desmontarse, abrirse ni triturarse las celdas.
2. Las celdas o baterías no deben someterse a calor ni fuego. Debe evitarse el almacenamiento a la luz directa del sol. Las celdas y baterías deben mantenerse limpias y secas. Limpiar las conexiones sucias con un paño seco y limpio.
3. Las celdas o baterías no deben cortocircuitarse. Es peligroso almacenar las celdas o baterías en estuches o cajones en cuyo interior puedan cortocircuitarse por contacto recíproco o por contacto con otros materiales conductores. No deben extraerse las celdas o baterías de sus embalajes originales hasta el momento en que vayan a utilizarse.
4. Las celdas o baterías no deben someterse a impactos mecánicos fuertes indebidos.
5. En caso de falta de estanqueidad de una celda, el líquido vertido no debe entrar en contacto con la piel ni los ojos. Si se produce contacto, lavar con agua abundante la zona afectada y avisar a un médico.
6. En caso de cambio o recarga inadecuados, las celdas o baterías que contienen electrolitos alcalinos (p. ej. las celdas de litio) pueden explotar. Para garantizar la seguridad del producto, las celdas o baterías solo deben ser sustituidas por el tipo Rohde & Schwarz correspondiente (ver lista de recambios).
7. Las baterías y celdas deben reciclarse y no deben tirarse a la basura doméstica. Las baterías o acumuladores que contienen plomo, mercurio o cadmio deben tratarse como residuos especiales. Respete en esta relación las normas nacionales de eliminación y reciclaje.

### Transporte

1. El producto puede tener un peso elevado. Por eso es necesario desplazarlo o transportarlo con precaución y, si es necesario, usando un sistema de elevación adecuado (p. ej. una carretilla elevadora), a fin de evitar lesiones en la espalda u otros daños personales.

## Instrucciones de seguridad elementales

2. Las asas instaladas en los productos sirven solamente de ayuda para el transporte del producto por personas. Por eso no está permitido utilizar las asas para la sujeción en o sobre medios de transporte como p. ej. grúas, carretillas elevadoras de horquilla, carros etc. Es responsabilidad suya fijar los productos de manera segura a los medios de transporte o elevación. Para evitar daños personales o daños en el producto, siga las instrucciones de seguridad del fabricante del medio de transporte o elevación utilizado.
3. Si se utiliza el producto dentro de un vehículo, recae de manera exclusiva en el conductor la responsabilidad de conducir el vehículo de manera segura y adecuada. El fabricante no asumirá ninguna responsabilidad por accidentes o colisiones. No utilice nunca el producto dentro de un vehículo en movimiento si esto pudiera distraer al conductor. Asegure el producto dentro del vehículo debidamente para evitar, en caso de un accidente, lesiones u otra clase de daños.

### Eliminación/protección del medio ambiente

1. Los dispositivos marcados contienen una batería o un acumulador que no se debe desechar con los residuos domésticos sin clasificar, sino que debe ser recogido por separado. La eliminación se debe efectuar exclusivamente a través de un punto de recogida apropiado o del servicio de atención al cliente de Rohde & Schwarz.
2. Los dispositivos eléctricos usados no se deben desechar con los residuos domésticos sin clasificar, sino que deben ser recogidos por separado.  
Rohde & Schwarz GmbH & Co.KG ha elaborado un concepto de eliminación de residuos y asume plenamente los deberes de recogida y eliminación para los fabricantes dentro de la UE. Para desechar el producto de manera respetuosa con el medio ambiente, dirijase a su servicio de atención al cliente de Rohde & Schwarz.
3. Si se trabaja de manera mecánica y/o térmica cualquier producto o componente más allá del funcionamiento previsto, pueden liberarse sustancias peligrosas (polvos con contenido de metales pesados como p. ej. plomo, berilio o níquel). Por eso el producto solo debe ser desmontado por personal especializado con formación adecuada. Un desmontaje inadecuado puede ocasionar daños para la salud. Se deben tener en cuenta las directivas nacionales referentes a la eliminación de residuos.
4. En caso de que durante el trato del producto se formen sustancias peligrosas o combustibles que deban tratarse como residuos especiales (p. ej. refrigerantes o aceites de motor con intervalos de cambio definidos), deben tenerse en cuenta las indicaciones de seguridad del fabricante de dichas sustancias y las normas regionales de eliminación de residuos. Tenga en cuenta también en caso necesario las indicaciones de seguridad especiales contenidas en la documentación del producto. La eliminación incorrecta de sustancias peligrosas o combustibles puede causar daños a la salud o daños al medio ambiente.

Se puede encontrar más información sobre la protección del medio ambiente en la página web de Rohde & Schwarz.



# Customer Support

## Technical support – where and when you need it

For quick, expert help with any Rohde & Schwarz equipment, contact one of our Customer Support Centers. A team of highly qualified engineers provides telephone support and will work with you to find a solution to your query on any aspect of the operation, programming or applications of Rohde & Schwarz equipment.

## Up-to-date information and upgrades

To keep your instrument up-to-date and to be informed about new application notes related to your instrument, please send an e-mail to the Customer Support Center stating your instrument and your wish. We will take care that you will get the right information.

### Europe, Africa, Middle East

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# 1 Preface

The R&S SGU is an upconverter in the frequency range of 10 MHz to 40 GHz.

Optimized for use in automated test equipment (ATE), the instrument offers very fast settling times in an exceptionally small form factor and low power consumption. The R&S SGU has LO connectors for coupling multiple generators to a common LO source and can be equipped with a mechanical step attenuator.

## 1.1 Key Features

The key features of the R&S SGU include the following:

- Compact size and low power consumption
- Remote connection via PCI Express, minimizing time for setup  
Alternatively, LAN or USB connections available
- Coherent LO input and output connectors, also usable as MIMO input/output and phase coherent I/Q demodulation
- Linux operating system
- Graphical user interface R&S SGMA-GUI to set up and control one or more R&S SGU instruments simultaneously from one remote computer, available for Windows and Linux systems

## 1.2 Documentation Overview

This section provides an overview of the R&S SGU user documentation. You find it on the product page at:

<http://www.rohde-schwarz.com/product/SGU100A.html> > "Downloads"

### Getting started manual

Introduces the R&S SGU and describes how to set up and start working with the product. Includes basic operations, typical measurement examples, and general information, e.g. safety instructions, etc. A printed version is delivered with the instrument.

### Online help

Embedded in the R&S SGMA-GUI software, it offers quick, context-sensitive access to the complete information.

### User manual

Contains the description of all instrument modes and functions. It also provides an introduction to remote control, a complete description of the remote control commands with programming examples, and information on maintenance, instrument interfaces and error messages. Includes the contents of the quick start guide manual.

The **online version** of the operating manual provides the complete contents for immediate display on the Internet.

#### **Service manual**

Describes the performance test for checking the rated specifications, module replacement and repair, firmware update, troubleshooting and fault elimination, and contains mechanical drawings and spare part lists.

#### **Instrument security procedures manual**

Deals with security issues when working with the R&S SGU in secure areas.

#### **Basic safety instructions**

Contains safety instructions, operating conditions and further important information. The printed document is delivered with the instrument.

#### **Data sheet and brochure**

The data sheet contains the technical specifications of the R&S SGU. It also lists the options and their order numbers as well as optional accessories.

The brochure provides an overview of the instrument and deals with the specific characteristics.

#### **Release notes and open source acknowledgment (OSA)**

The release notes list new features, improvements and known issues of the current firmware version, and describe the firmware installation.

The open source acknowledgment document provides verbatim license texts of the used open source software.

See <http://www.rohde-schwarz.com/product/SGU100A.html> > "Downloads" > "Firmware"

#### **Application notes, application cards, white papers, etc.**

These documents deal with special applications or background information on particular topics, see <http://www.rohde-schwarz.com/appnotes>.

## 1.3 Typographical Conventions

The following text markers are used throughout this documentation:

Convention	Description
"Graphical user interface elements"	All names of graphical user interface elements on the screen, such as dialog boxes, menus, options, buttons, and softkeys are enclosed by quotation marks.
KEYS	Key names are written in capital letters.

Convention	Description
File names, commands, program code	File names, commands, coding samples and screen output are distinguished by their font.
<i>Input</i>	Input to be entered by the user is displayed in italics.
<a href="#">Links</a>	Links that you can click are displayed in blue font.
"References"	References to other parts of the documentation are enclosed by quotation marks.

## 2 Preparing for Use

- [Putting into Operation](#)..... 14
- [Linux Operating System](#).....20
- [Connecting an External PC and Devices](#).....20

### 2.1 Putting into Operation

This section describes the basic steps to be taken when setting up the R&S SGU for the first time.

---

#### **WARNING**

##### **Risk of injury and instrument damage**

The instrument must be used in an appropriate manner to prevent electric shock, fire, personal injury, or damage.

- Do not open the instrument casing.
- Read and observe the "Basic Safety Instructions" delivered as a printed brochure with the instrument.

In addition, read and observe the safety instructions in the following sections.

Notice that the data sheet may specify additional operating conditions.

---

---

#### **NOTICE**

##### **Risk of instrument damage**

Note that the general safety instructions also contain information on operating conditions that prevent damage to the instrument. The instrument's data sheet can contain additional operating conditions.

---

---

#### **NOTICE**

##### **Risk of electrostatic discharge (ESD)**

Electrostatic discharge (ESD) can damage the electronic components of the instrument and the device under test (DUT). ESD is most likely to occur when you connect or disconnect a DUT or test fixture to the instrument's test ports. To prevent ESD, use a wrist strap and cord and connect yourself to the ground, or use a conductive floor mat and heel strap combination.

For details, refer to the basic safety instructions included at the front of the manual.

---

**NOTICE****Risk of instrument damage during operation**

An unsuitable operating site or test setup can damage the instrument and connected devices. Ensure the following operating conditions before you switch on the instrument:

- All fan openings are unobstructed and the airflow perforations are unimpeded. The minimum distance from the wall is 10 cm.
- The instrument is dry and shows no sign of condensation.
- The instrument is positioned as described in the following sections.
- The ambient temperature does not exceed the range specified in the data sheet.
- Signal levels at the input connectors are all within the specified ranges.
- Signal outputs are correctly connected and are not overloaded.

**2.1.1 EMI Suppression**

Electromagnetic interference (EMI) may affect the measurement results.

To suppress generated Electromagnetic Interference (EMI),

- Use suitable shielded cables of high quality. For example use double-shielded RF and LAN cables.  
**Note:** USB cables are of varying and often poor quality. Therefore, check the quality of each individual USB cable as described in the service manual.
- Always terminate open cable ends.
- Note the EMC classification in the data sheet

**2.1.2 Unpacking and Checking the Instrument**

Check the equipment for completeness using the delivery note and the accessory lists for the various items. Check the instrument for any damage. If there is damage, immediately contact the carrier who delivered the instrument. Make sure not to discard the box and packing material.

**Packing material**

Retain the original packing material. If the instrument needs to be transported or shipped at a later date, you can use the material to protect the control elements and connectors.

**NOTICE****Risk of damage during transportation and shipment**

Insufficient protection against mechanical and electrostatic effects during transportation and shipment can damage the instrument.

- Always make sure that sufficient mechanical and electrostatic protection is provided.
- When shipping an instrument, the original packaging should be used. If you do not have the original packaging, use sufficient padding to prevent the instrument from moving around inside the box. Pack the instrument in antistatic wrap to protect it from electrostatic charging.
- Secure the instrument to prevent any movement and other mechanical effects during transportation.

The **carrying handles** at the front and side of the casing are designed to lift or carry the instrument. Do not apply an excessive external force to the handles.

Observe the information on transporting heavy instruments in the basic safety instructions included at the front of the printed manual.

### 2.1.3 Accessory List

The instrument comes with the following accessories:

- Power cable
- Getting Started printed manual

### 2.1.4 Placing or Mounting the Instrument

The R&S SGU is designed for use under laboratory conditions, either on a bench top or in a rack using a rack adapter kit (order number see data sheet).

**Bench Top Operation**

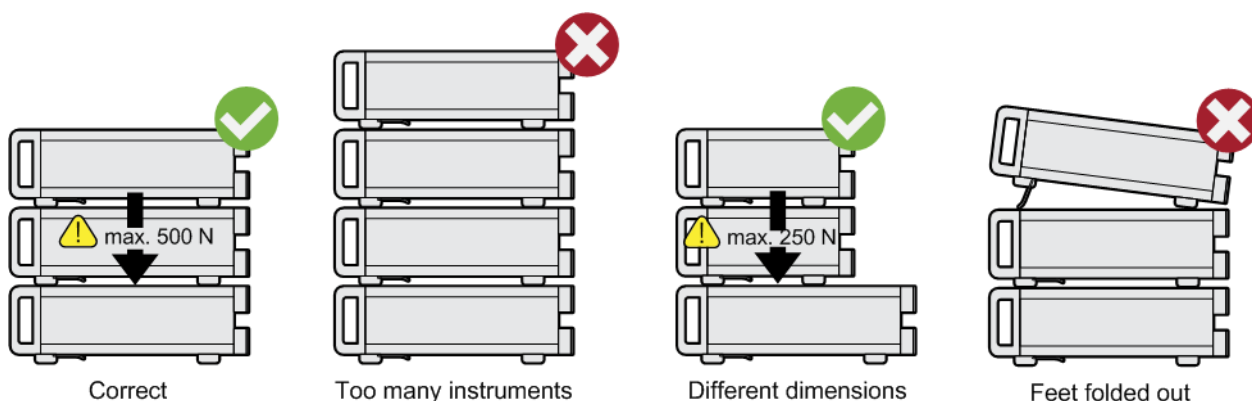
If the R&S SGU is operated on a bench top, the surface should be flat. The instrument can be used in horizontal position, standing on its feet.

**CAUTION****Risk of injury and instrument damage if stacking instruments**

A stack of instruments may tilt over and cause injury. Furthermore, the instruments at the bottom of the stack may be damaged due to the load imposed by the instruments on top.

Observe the following instructions when stacking instruments:

- Never stack more than three instruments with the same dimensions (width and length). If you need to stack more than three instruments, install them in a rack.
- The overall load imposed on the lowest instrument must not exceed 500 N.
- All instruments should have the same dimensions (width and length). If you need to stack smaller instruments on the top, the overall load imposed on the lowest instrument must not exceed 250 N.
- If the instruments have foldable feet, fold them in completely.

**Rack mounting**

The R&S SGU can be installed in a rack using a rack adapter kit (Order No. see data sheet). The installation instructions are part of the adapter kit.

**NOTICE****Risk of instrument damage in a rack**

An insufficient airflow can cause the instrument to overheat, which may disturb the operation and even cause damage.

Make sure that all fan openings are unobstructed, that the airflow perforations are unimpeded, and that the minimum distance from the wall is 10 cm.

**2.1.5 Switching the Instrument On and Off**

The R&S SGU is automatically adapted to the AC voltage supplied. There is no need to set the voltage manually or change fuses. The [AC SUPPLY AND POWER SWITCH](#) is at the rear of the unit.



### To connect the AC supply

- ▶ Connect the R&S SGU to the AC power source using the AC power cable delivered with the instrument.

**Note:** The instrument is in compliance with safety class EN61010-1. Connect the instrument only to a socket with earthing contact.

### To start up the instrument

1. [Connect the instrument to the AC supply.](#)



2. To turn on the power, press the main power switch to position I (On).

### To switch between standby and ready state

- ▶ Press the POWER ON /STAND BY key briefly to switch the instrument from the standby to ready state or vice versa.



In ready state, the button is green. The instrument is ready for operation. All modules are power-supplied and the R&S SGU initiates its startup procedure.

In standby state, the button is orange. The standby power mode keeps the power switch circuits and the remote control system active.

### Start-up and booting

The instrument boots the operating system and starts the instrument firmware. During the booting process, the green POWER ON /STAND BY key blinks. If the previous session was terminated regularly, the instrument uses the last setup with the relevant instrument settings.

Once the startup procedure has been terminated, the instrument is ready for operation.



In the R&S SGMA-GUI, select "Instrument > Preset" function to return the instrument to its defined reset/preset state, if the current setup is no longer relevant.

To customize the start settings, use the "SGMA-GUI > File > Save As/Open" function.

### To shut down the Instrument

To shut down the R&S SGU, proceed as described below.

**NOTICE****Risk of losing data**

If you switch off the running instrument using the rear panel switch or by disconnecting the power cord, the instrument loses its current settings.

Always press the POWER ON/STANDBY key first to shut down the application properly.

1. Press the POWER ON /STAND BY key to save the current setup, shut down the operating system and set the instrument to standby state.

The POWER ON /STAND BY LED must be orange.

**Tip:** If the instrument is operated manually via the R&S SGMA-GUI, select "SGMA-GUI > Instrument Name > Setup > Standby".

2. To turn the power off, press the main power switch to position 0 (Off).

None of the front-panel LEDs should be on.

### 2.1.6 Function Check

The instrument automatically monitors the main functions when it is switched on and monitors them continuously during operation.

A detected fault is indicated by an "Error" message displayed in the info line of the R&S SGMA-GUI together with a brief error description. For an in-depth identification of the error, press the "SGMA-GUI > Info" button. In response, a description of the error(s) is displayed. For more information, refer to the "Error Messages" section in the User Manual.

### 2.1.7 Default Settings

When the instrument is switched on, it is not the preset state that is active, but rather the instrument state that was set before the instrument was switched off. It is recommended that you use the "SGMA-GUI > Instrument > Preset" function to return the instrument to its defined preset state every time a new configuration is required or the current setup is no longer relevant.

The R&S SGU offers a two-stage preset concept:

- Preset the instrument to a predefined state  
The "SGMA-GUI > Instrument Name > Preset" function calls up a defined instrument setup. All parameters and switching states are preset (also those of inactive operating modes). The default instrument settings provide a reproducible initial basis for all other settings. However, functions that concern the integration of the instrument into a measurement setup are not changed.
- Preset the instrument to its factory settings

The instrument can also be forced to load its default factory settings. To access the corresponding dialog box, select the "SGMA-GUI > Instrument Name > Setup > Factory Preset" function.

For more information and an overview of the settings affected by the factory preset function, see [Chapter 8.9, "Factory Preset"](#), on page 98.



User-defined instrument states can be stored and called up using the functions "SGMA-GUI > File > Save As/Open".

## 2.2 Linux Operating System

The instrument uses an embedded Linux operating system, optimally adapted to the instrument.



### Accessing the Operating System

No access to the operating system is required for normal operation.

All necessary system settings can be made in the "Setup" dialog.

## 2.3 Connecting an External PC and Devices

As a rule, the R&S SGU is operated exclusively via remote control on a connected PC. Another way to control the instrument is the manual operation via the R&S SGMA-GUI software on the connected PC.

Both the remote control and the manual operation of the instrument require an external controller. For the prerequisites and the instructions on how to configure an external controller for remote control, refer to the User Manual. A brief introduction to the remote control capabilities is provided in [Chapter 10, "Network and Remote Control Operation"](#), on page 110.

This section gives an introduction on how to configure the external PC for manual operation (see [Chapter 2.3.1, "Installing the R&S SGMA-GUI Software on an External PC"](#), on page 21).

In addition to connecting an external controller, it may be useful to connect other external devices, e.g. a memory stick. The following interfaces are provided on the rear panel of the instrument, see also [Chapter 3.2, "Rear Panel Tour"](#), on page 28:

- PCI Express (refer to [Chapter 2.3.3, "Connecting a Controller via PCI Express"](#), on page 24)
- USB interface (refer to [Chapter 2.3.4, "Connecting a Controller or a USB Device via USB"](#), on page 24)
- LAN interface (refer to [Chapter 2.3.2, "Connecting a Remote PC via LAN"](#), on page 22)

### 2.3.1 Installing the R&S SGMA-GUI Software on an External PC

The R&S SGMA-GUI software is a graphical user interface program for one or more instruments. It runs on a remote PC.

The R&S SGMA-GUI software is provided as separate installation package for the different operating systems. The latest version of the software together with the release notes is available for download at:

<http://www.rohde-schwarz.com/product/SGU100A.html> > "Downloads" > "Software"

This page always offers the latest information on your R&S SGMA-GUI.



This description focuses on the handling of the Windows-32 version. The file naming conventions and the installation instructions for the other operating systems are analogous.

The R&S SGMA-GUI installation package for Windows-32 operating system consists of the file `SGMA-GUI_<V.VV.VVV.VVV>.exe`. The version numbers in the file names vary with each update. To install the R&S SGMA-GUI, the following hardware and software requirements have to be met.

**Table 2-1: Hardware and Software Requirements**

Requirement	Remark
One of the following operating systems: <ul style="list-style-type: none"> <li>• Windows XP SP2</li> <li>• Windows Vista</li> <li>• Windows 7</li> <li>• Windows 8/ 8.1</li> <li>• Windows 10</li> <li>• Linux</li> </ul>	R&S SGMA-GUI has to be installed on one of the supported operating systems. <b>Note:</b> Any other Windows version or other operating systems are not supported. Windows Installer Version 4.5 or higher is needed for the installation of the software on a Windows XP computer. During installation, the operation system is checked. The installation will be terminated if this requirement is not fulfilled.
R&S VISA	VISA drivers can be obtained on the Rhode & Schwarz website: <a href="http://www.rohde-schwarz.com/rsvisa">http://www.rohde-schwarz.com/rsvisa</a>
CPU	At least Pentium or compatible, as from 1 GHz (recommended).
VGA color display resolution	At least 800*600 pixels

#### Installing a new software version



Administrator rights are necessary for installation and starting.

1. Download the R&S SGMA-GUI software
2. In Windows Explorer double-click `SGMA-GUI_<V.VV.VVV.VVV>.exe` and follow the instructions.

### Uninstalling an old software version

An uninstallation of a previous version of the SW can be performed prior to the installation of the new one but is not mandatory.

- ▶ To uninstall this version, go to "Start > Settings > Control Panel > Add/Remove Programs" and select the entry `SGMA-GUI_V.VV.VVV.VVV`.

The script file identifies and removes all currently installed R&S SGMA-GUI software items.

## 2.3.2 Connecting a Remote PC via LAN

The R&S SGU is equipped with a network interface and can be connected to an Ethernet LAN (local area network). The interface can be used, for example:

- To connect an external computer for manual control of the instrument by means of the R&S SGMA-GUI software.
- To operate the device by a remote control program.  
See [Chapter 10, "Network and Remote Control Operation"](#), on page 110.

This section describes how to configure the LAN interface. It includes the following topics:

- [Chapter 2.3.2.1, "Connecting the Instrument to the Network"](#), on page 22
- [Chapter 2.3.2.2, "Assigning the IP Address"](#), on page 23
- [Chapter 2.3.2.3, "Automatically Adding Instruments to the SGMA-GUI"](#), on page 23

### 2.3.2.1 Connecting the Instrument to the Network

There are two methods to establish a LAN connection to the instrument:

- A non-dedicated network (Ethernet) connection from the instrument to an existing network.
- A dedicated network connection (Point-to-point connection) between the instrument and a single computer.

In both cases, an IP address has to be assigned to the instrument and the computer, see [Chapter 2.3.2.2, "Assigning the IP Address"](#), on page 23.

#### Setting Up a Network (LAN) Connection

---

### **NOTICE**

#### **Risk of network failure**

Before connecting the instrument to the network or configuring the network, consult your network administrator. Errors may affect the entire network.

---

- ▶ Connect the instrument to the network or to a single PC.

If the instrument is connected to the LAN, the operating system automatically detects the network connection and activates the required drivers. By default, the instrument is configured to use dynamic TCP/IP configuration and obtain all address information automatically.

### 2.3.2.2 Assigning the IP Address

Depending on the network capacities, the TCP/IP address information for the instrument can be obtained in different ways.

- If the network supports dynamic TCP/IP configuration using the Dynamic Host Configuration Protocol (DHCP), all address information can be assigned automatically.
- If the network does not support DHCP, the instrument tries to obtain the IP address via Zeroconf (APIPA) protocol. If this attempt does not succeed or if the instrument is set to use alternate TCP/IP configuration, the addresses must be set manually.



The R&S SGU uses the Zeroconf IP addresses 169.254.xxx.yyy., where xxx takes values between 1...254 and yyy the values in the value range 1...255; the subnet mask is always 255.255.0.0. The IP address of the host must be within the same address area for Zeroconf.

---

By default, the instrument is configured to use dynamic TCP/IP configuration and obtain all address information automatically. This means that it is safe to establish a physical connection to the LAN without any previous instrument configuration.

### 2.3.2.3 Automatically Adding Instruments to the SGMA-GUI



For information on how to install the R&S SGMA-GUI software, refer to [Chapter 2.3.1, "Installing the R&S SGMA-GUI Software on an External PC"](#), on page 21.

---

1. For each new instrument perform the following steps:
  - a) Connect the instrument to the network.
  - b) Press the POWER ON /STAND BY key to switch on the instrument.
  - c) Wait until the POWER ON /STAND BY LED is green and not blinking.
  - d) Press the ID key on the front panel of the instrument.
2. Start the SGMA-GUI on a computer connected to the same network.
3. Open the "Instruments" dialog and click "Scan".

**Note:** This step is performed automatically on the first start and can also be omitted for instruments with a direct LAN connection to the computer.

All instruments are added automatically to the main panel of the SIGMA-GUI.

### 2.3.3 Connecting a Controller via PCI Express

A PCI Express connector is provided on the rear panel of the instrument, see [Chapter 3.2, "Rear Panel Tour"](#), on page 28.

#### NOTICE

##### Risk of device failure

The R&S SGU is equipped with a single lane PCIe interface that supports hot plugging. Do not connect an external PC to the PCIe connector of the instrument during operation if this external PC does not support hot-plugging!

Using the PCIe interface for remote control of the instrument requires extended knowledge. Refer to [Chapter 10.3, "Advanced Remote Control Using PCIe"](#), on page 120 for detailed information.

### 2.3.4 Connecting a Controller or a USB Device via USB

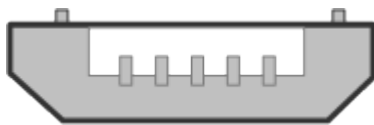
The USB interface on the rear panel of the R&S SGU allows you to connect either a USB device or use the R&S SGU as a device and connect it to a controller.

#### Connecting a controller (host PC or compatible signal generator)

If you connect a controller (host PC or compatible signal generator) to the R&S SGU, the R&S SGU acts as a USB device.

To connect the controller to the USB interface of the R&S SGU, always connect the **USB Type Micro-B** connector to the R&S SGU. Refer to the documentation of the controller to find out which USB connector type you can connect to the controller.

The [Figure 2-1](#) illustrates schematically the required connector type to emphasize on the different connector shape.



*Figure 2-1: USB Type Micro-B connectors*

An external PC with installed R&S SGMA-GUI is required for manual operation of the R&S SGU.

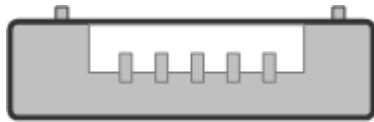
On the remote PC, perform the steps as described in [Chapter 2.3.2.3, "Automatically Adding Instruments to the SGMA-GUI"](#), on page 23.

#### Connecting a USB device

If you connect a USB device (Memory stick, CD-ROM, an instrument) to the R&S SGU, the R&S SGU acts as a host.

To connect a USB device to the interface of the R&S SGU, always connect the **USB Type Micro-A** connector to the R&S SGU. Refer to the documentation of the USB device to find out which USB connector type you can connect to the USB device.

The [Figure 2-2](#) illustrates schematically the required connector type to emphasize on the different connector shape.



*Figure 2-2: USB Type Micro-A connectors*

If you connect an R&S SGS to an R&S SGU via a USB cable, perform the steps as described in [Chapter 5.2, "Setups for Connecting an R&S SGS and an R&S SGU"](#), on page 39.



### Using a USB Adapter

You can use a USB adapter to customize the connectors of a USB cable to the requirements of the instrument.

For example, you can use a Type-A / Micro-A adapter to customize a standard USB cable with Type A and Type Micro-B connectors for the connection of an R&S SGS (acting as a host) to an R&S SGU (acting as a USB device).

In some cases, you can also use a Type-A / Micro-B adapter to establish a connection to the instrument. To check whether the adapter you have is suitable or not you can connect a USB stick with an LED through the adapter to the instrument. If the LED of the USB stick lights up after a connection to the instrument then you can use this adapter for further applications with the instrument.



## 3 Instrument Tour

The following topics will help you get familiar with the instrument and perform the first steps:

- [Front Panel Tour](#)
- [Rear Panel Tour](#)

This section explains the control elements and the connectors of the R&S SGU with the aid of the front and rear views. Specifications of interfaces can be found in the data sheet.

### 3.1 Front Panel Tour

This section provides an overview of control elements on the front panel of the R&S SGU. The connectors of the R&S SGU are placed on the rear panel and are described in [Chapter 3.2, "Rear Panel Tour"](#), on page 28. As the R&S SGU is mainly intended to be remote-controlled, the front panel of the R&S SGU contains no display but mostly LEDs to inform the user about the status of the instrument. The user interface can be displayed on a remote PC station used to manually remote control the instrument.



Figure 3-1: Front panel view

#### POWER ON /STAND BY



The POWER ON /STAND BY key switches the instrument from the standby to ready state or vice versa.

In ready state, the button is green. The instrument is ready for operation.

In standby state, the button is orange. In this state, it is safe to switch off the AC power and disconnect the instrument from the power supply.

A blinking green color indicates that a booting operation is in process.

#### RF ON



The RF ON key switches the RF signal on or off. If activated, the button is green.

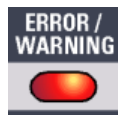
#### LO IN



The LO IN LED indicates the compatibility of the level of the LO input signal with the correct operation of the R&S SGU.

- Green indicates that the level of the LO input signal is in the range of correct operation.
- Red indicates that the level of the LO input signal is too high or too low.
- No light indicates that the instrument is in a bypass mode.

#### ERROR / WARNING



The ERROR / WARNING LED indicates the status of the R&S SGU.

- Red indicates that an error has occurred, e.g. temperature exceeded or power failure.
- Blinking orange indicates a running process (e.g. calibration, self test).
- No light indicates that no errors or warnings have occurred.

For details on errors or warnings, refer to the graphical user interface on a remote PC ("SGMA-GUI > Info").

For more information, refer to the "Error Messages" section in the User Manual.

#### LAN



Pressing the key for more than 3 s resets the LAN interface settings, i.e. the "IP Address Mode" is reset to DHCP.

#### ID



Pressing the ID key while the instrument is active, opens the "SGMA-GUI > Setup > Instruments > Configure Instruments > Edit Instrument" dialog of the corresponding instrument on the remote controller.

Pressing the ID key of an inactive instrument and starting "SGMA-GUI > Setup > Instruments > Scan", leads to an automatic activation of the instrument in the SGMA-GUI.

## 3.2 Rear Panel Tour

This section provides an overview of the connectors on the rear panel of the instrument. For technical data of the connectors, refer to the data sheet.



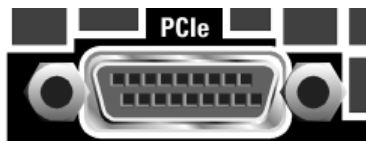
Figure 3-2: Rear panel view

### NOTICE

#### Protection of mechanical components

To avoid damage of the SMA connectors it is essential to limit the tightening torque to 60 Ncm. Use an adequate 8 mm torque wrench and not an ordinary open-end wrench.

#### PCI EXPRESS CONNECTOR



The PCIe (Peripheral Component Interconnect Express) single lane interface allows remote control with optimized speed.

For details, see [Chapter 2.3.3, "Connecting a Controller via PCI Express"](#), on page 24.

#### USB CONNECTOR

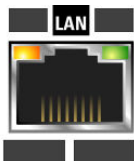


The USB (universal serial bus) interface, Type Micro, allows you to connect various external devices, e.g.:

- If the interface is configured as a device interface, a remote computer can be connected for firmware update, manual operation via the R&S SGMA-GUI software or for remote control of the instrument.
- If the interface is configured as a host interface, a memory stick for file transmission can be connected.

For details, see [Chapter 2.3.4, "Connecting a Controller or a USB Device via USB"](#), on page 24.

### LAN CONNECTOR



The LAN (Ethernet) interface allows you to connect the R&S SGU to other devices, e.g. a remote computer, for firmware update, manual operation via the R&S SGMA-GUI software or for remote control of the instrument. The connection to the remote computer can be direct or via a network.

For details, see [Chapter 2.3.2, "Connecting a Remote PC via LAN"](#), on page 22.

### RF OUT



Provides an RF 50 Ohm signal output.

**NOTICE!** Maximum Input Levels. Do not overload the RF output. The maximum permissible back-feed is specified in the data sheet.

### LO IN, LO OUT



SMA type connectors that can be used for local oscillator signals and alternatively also in MIMO setups.

Local oscillator input and output:

- LO IN: Input for external LO signals
- LO OUT: Output of internal LO signals

### TRIG



Multi purpose connector. The TRIG connector is used mainly as an input connector for an external pulse modulator source.

### I, Q IN / OUT



The I IN and Q IN SMA female type connectors are the inputs of the I/Q modulator, provided for feeding of external signal.

The I OUT and Q OUT SMA female type connectors are for direct output of the analog I/Q signal.

**NOTICE!** Maximum Input Levels. Do not overload the I and Q inputs. The maximum permissible voltage is 1V. For details, refer to the data sheet.

**Note:** The I/Q modulator requires the hardware option R&S SGU-B120V/-B140V.

#### AC SUPPLY AND POWER SWITCH



The AC supply and power switch allow you to connect the R&S SGU to the power supply and switch on the instrument.

For details, see ["To connect the AC supply"](#) on page 18.

## 4 First Steps with the Instrument

If an R&S SGU is connected to a signal generator, the instrument acts as an extension to the signal generator extending its frequency range.

This section provides an example on how to configure the instrument to convert a continuous wave (CW) signal.

### 4.1 R&S SGU as an Extension to the R&S SGS

In case the R&S SGU is connected to a compatible R&S signal generator, a controller only needs to talk to the signal generator which in turn takes care of the proper settings for the R&S SGU.

In the following example, the instrument is manually operated via the R&S SGMA-GUI software. The R&S SGU in this example is a base unit equipped with the frequency option R&S SGU-B120.

#### Configuring the R&S SGU to upconvert a CW signal generated by the R&S SGS

As a prerequisite for this example the R&S SGMA-GUI software has to be installed on a remote PC.

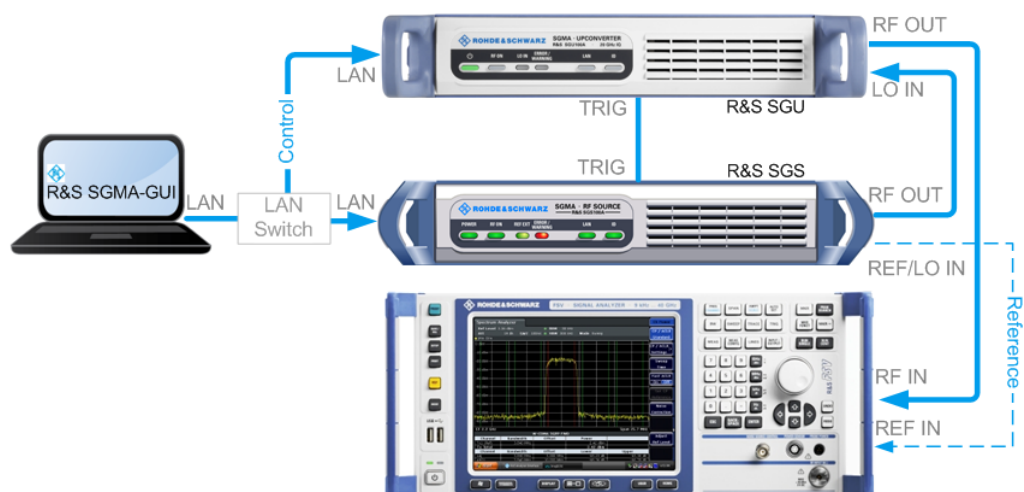


Figure 4-1: Example of a test setup for upconverting a CW signal generated by the R&S SGS



For higher setting/ measuring speeds, use a PCIe switch and PCIe connections.

1. Connect the test equipment as shown on [Figure 4-1](#):
  - a) Connect the R&S SGS, R&S SGU and the controller to a LAN switch.
  - b) Connect the RF OUT of the R&S SGS to the LO IN of the R&S SGU.
  - c) Connect the TRIG connectors of the R&S SGS and the R&S SGU.

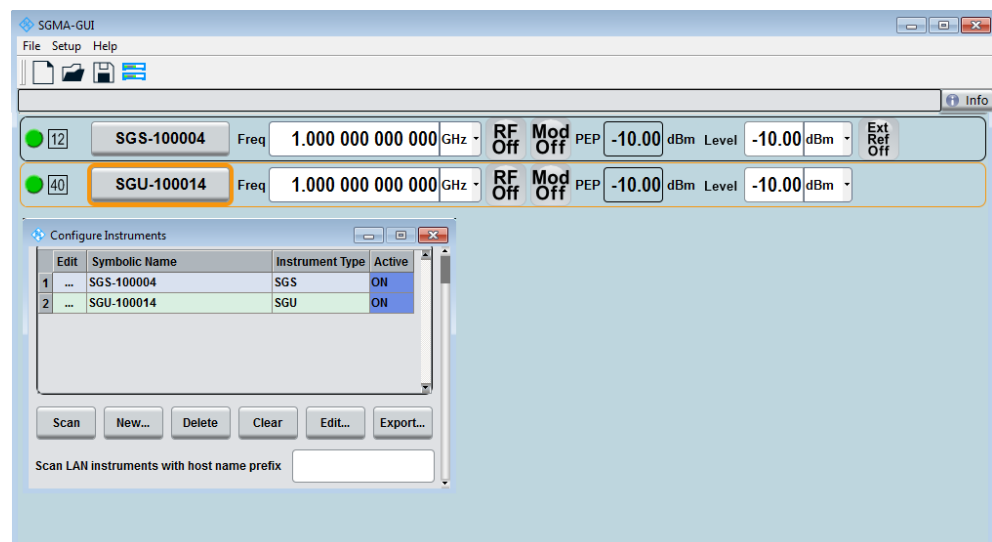
- d) Connect the RF OUT of the R&S SGU to the RF IN of the signal analyzer.
2. Switch on the R&S SGS and the R&S SGU.

The POWER ON/STANDBY keys have to be **green** and not blinking.

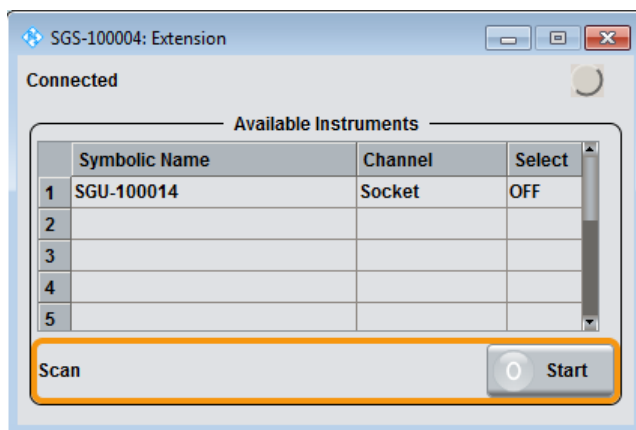
3. Press the ID keys on the front panels of the R&S SGS and the R&S SGU (only required if the components are connected via a company network).
4. On the connected remote PC, start the R&S SGMA-GUI software application.

The main panel of the application and the configure instruments dialog open. Both instruments are added automatically to the instruments list and to the main panel of the R&S SGMA-GUI software.

The main panel provides a quick access to the main settings of the configured and activated instruments. The display shows one row per instrument with the instrument specific settings. The rows comprise the instrument, the connection state, the used frequency and power level and the state of the RF output and the modulator.



5. In the R&S SGMA-GUI main panel, the green indicator in front of the instrument's name confirms that there is a connection between the instrument and the remote PC and that the instrument is recognized by the software.
6. In the R&S SGMA-GUI main panel, select the rows corresponding to the corresponding instruments to be configured and select "Instrument Name > Preset" to restore their predefined settings.
7. Select "SGMA-GUI main panel > R&S SGS > Extension".  
The "Extension" dialog opens.

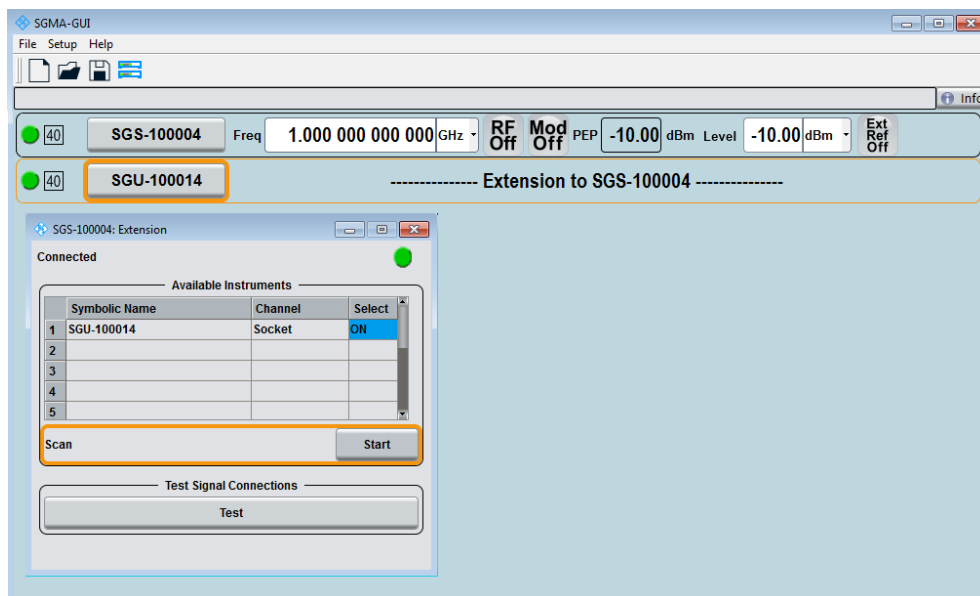


**Tip:** Instrument does not appear in the extension dialog. If the R&S SGU is not automatically shown in this dialog, press "Scan > Start" to find the instrument.

8. Select the R&S SGU from the list and set "Available Instruments > Select > On" to enable it as an extension.

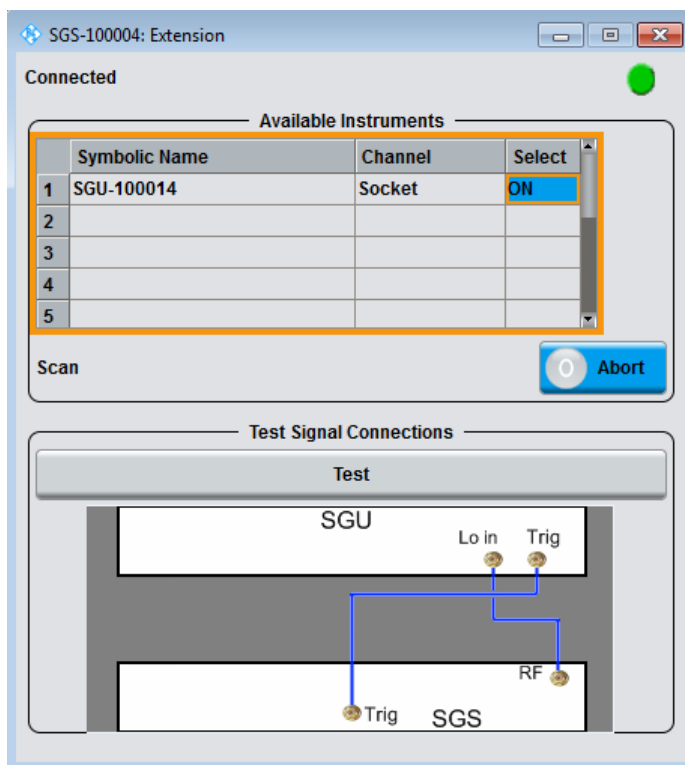
A green status indicator "Connected" indicates the successfully established remote connection between the R&S SGS and the R&S SGU.

The R&S SGMA-GUI indicates the extended frequency range of the R&S SGS and the activated extension mode.



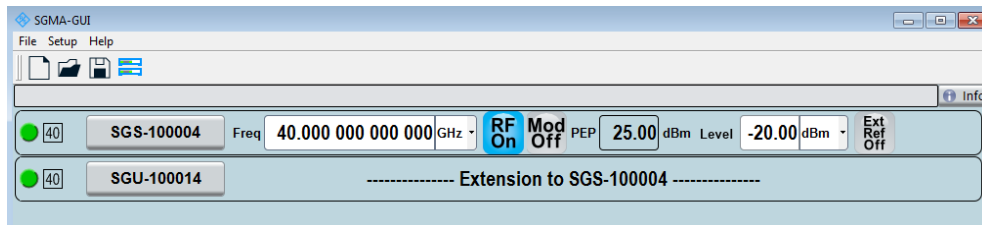
9. Select "Test Signal Connections > Test" to trigger a check of all required signal connections.





The diagram displays the connection state of the tested connections.

10. Select "SGMA-GUI > R&S SGS > Freq = 40 GHz", "Lev = -30 dBm".
11. Select "SGMA-GUI > SGS > RF > State > On" to enable the output of the CW signal.



The extension adopts these values and states automatically and generates a CW signal with RF = 40 GHz and Level = -20 dBm.

The signal is output at the RF OUT connector on the rear panel of the R&S SGU.



### Identifying a specific instrument

If several instruments are active in the R&S SGMA-GUI use one of the device identification functions to identify a specific device:

- Select "SGMA-GUI > Instrument Name > Setup > Remote > Remote Channels > Device Identify". The green LAN LED on the front panel of the instrument blinks.
- Press the ID key on the instrument's front panel. The "Edit Instrument" dialog of the respective instrument opens.

## 4.2 R&S SGU as a Standalone Upconverter

This section provides an example on how to configure the instrument to convert a continuous wave (CW) signal. The signal in this example is provided by an incompatible signal generator (local oscillator).

In the following example, the instrument is manually operated via the R&S SGMA-GUI software. The R&S SGU in this example is a base unit equipped with the frequency option R&S SGU-B120.

### Configuring the R&S SGU to convert a CW signal

As a prerequisite for this example, the R&S SGMA-GUI software has to be installed on a remote PC and the local oscillator has to be prepared for use.

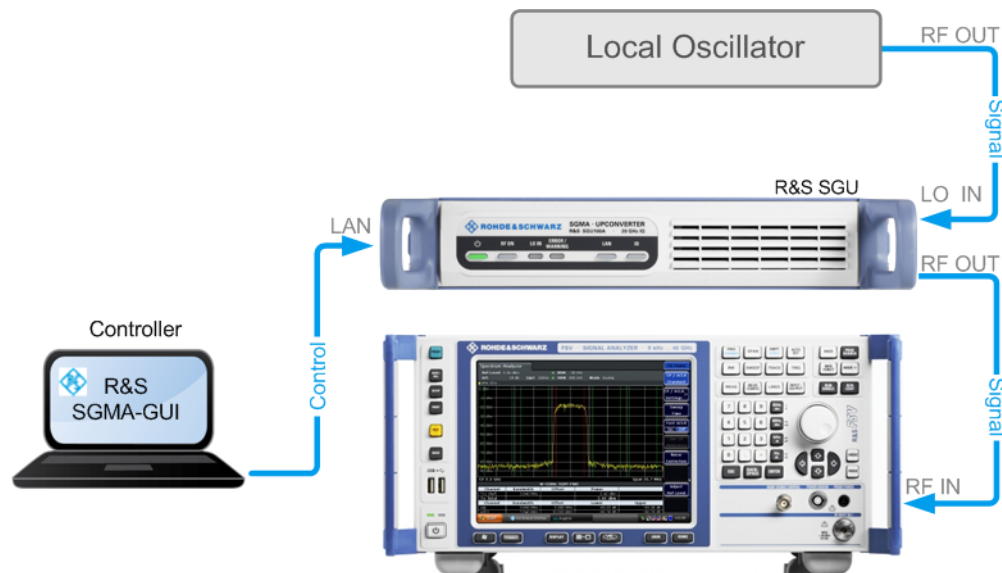


Figure 4-2: Example of a setup of the R&S SGU as an upconverter

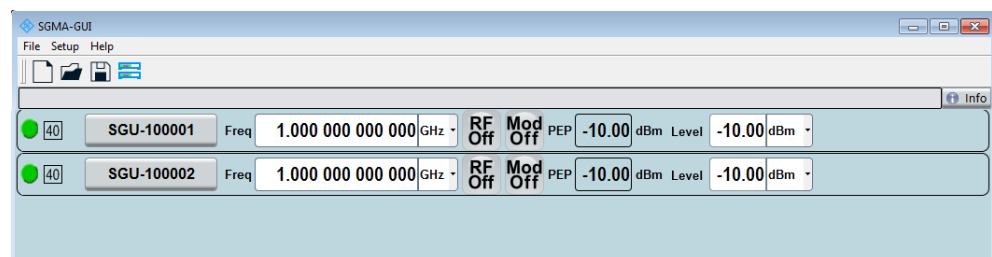
1. Connect the test equipment as shown in [Figure 4-2](#). Additional connections may be needed to fulfill the requirements of the connected local oscillator. To find out what connections are needed refer to its user manual.
2. Switch on the R&S SGU.

The POWER ON/STANDBY key has to be **green** and not blinking.

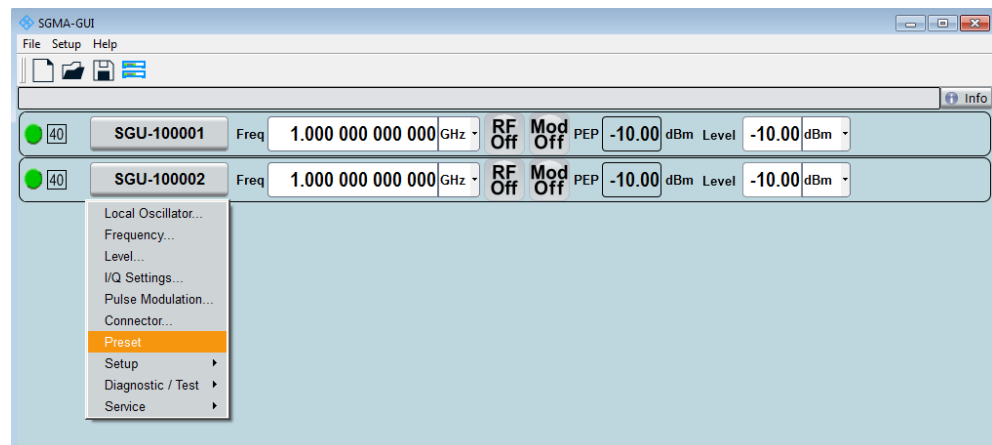
- Press the ID key on the front panel the R&S SGU (only required if the components are connected via a company network).
- On the connected remote PC, start the R&S SGMA-GUI software application.

The main panel of the application and the configure instruments dialog open. The R&S SGU is added automatically to the instruments list and to the main panel of the R&S SGMA-GUI software.

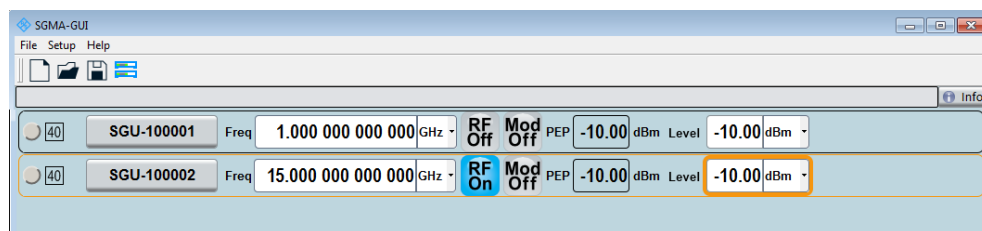
The main panel provides a quick access to the main settings of the configured and activated instruments. The display shows one row per instrument with the instrument specific settings. The rows comprise the instrument, the connection state, the used frequency and power level and the state of the RF output and the modulator.



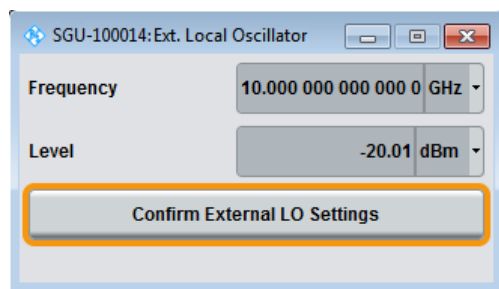
- In the R&S SGMA-GUI main panel, the green indicator in front of the instrument's name confirms that there is a connection between the instrument and the remote PC and that the instrument is recognized by the software.
- In the R&S SGMA-GUI main panel, select the row corresponding to the instrument to be configured and select "Instrument Name > Preset" to restore the predefined instrument's settings.



- Select "SGMA-GUI > R&S SGU > Freq = 15 GHz", "Lev = -10 dBm", "RF > On".



8. Select "SGMA-GUI > Instrument Name > Ext. Local Oscillator". Read the required frequency and level values for the LO.



9. Change the settings of the LO to the required values.
10. Select "SGMA-GUI > Instrument Name > Ext. Local Oscillator > Confirm External LO Settings" to apply the changes.

The 15 GHz signal is output at the LO OUT connector at the rear panel of the R&S SGU.



### Identifying a specific instrument

If several instruments are active in the R&S SGMA-GUI, use one of the device identification functions to identify a specific device:

- Select "SGMA-GUI > Instrument Name > Setup > Remote > Remote Channels > Device Identify". The green LAN LED on the front panel of the instrument blinks.
- Press the ID key on the instrument's front panel. The "Edit Instrument" dialog of the respective instrument opens.

## 5 System Overview

The R&S SGU is an instrument intended either for the modulation of IQ signals or as an upconverter in the frequency range of 10 MHz to 40 GHz.

Optimized for use in automated test equipment (ATE), the instrument offers very fast settling times in an exceptionally small formfactor and low power consumption. The R&S SGU can be equipped optionally with a mechanical step attenuator.

### 5.1 Setups for Instrument Control

The R&S SGU is an instrument designed for the automated test equipment (ATE) needs. To maintain the small size, the instrument is not equipped with a display and hence additional equipment is required to control the instrument.

This section provides an overview of the possible configuration setups for controlling the R&S SGU.

#### 5.1.1 Manual Operation from the R&S SGMA-GUI

The following example represents a basic configuration of the R&S SGU, operated manually by the configuration software R&S SGMA-GUI. The configuration software is installed on a remote PC and controls several instruments. The instruments are connected to the remote PC over different remote control interfaces. Any combination of the used interfaces is possible.

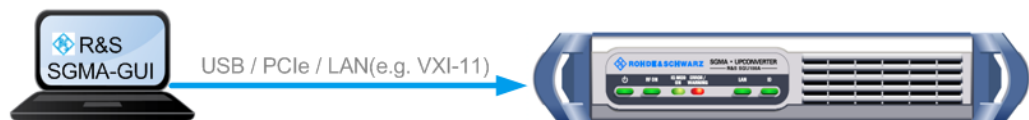


Figure 5-1: Configuration example: manual control from R&S SGMA-GUI



For information about the manual control, refer to:

- [Chapter 6, "Understanding the R&S SGMA-GUI Software"](#), on page 46
- [Chapter 7, "Upconverter Settings"](#), on page 70
- [Chapter 8, "General Instrument Settings and Instrument Setup"](#), on page 86

#### 5.1.2 Remote Control from a Controller

The remote control provides access to the instrument's settings from a remote computer (external controller) by means of remote commands. To automate often repeating settings and settings sequences, these are grouped in the remote control programs, i.e. application programs.

An instrument may be connected to the controller via any of the supported interfaces LAN, USB or PCIe.

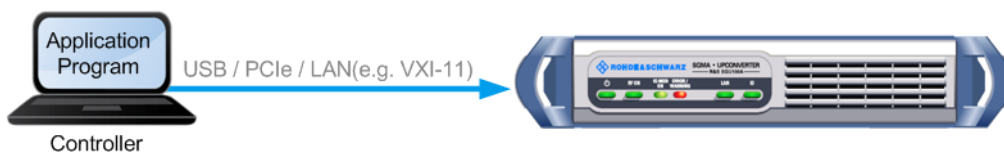


Figure 5-2: Configuration example: remote control from a controller



For information about remote control, refer to:

- [Chapter 10, "Network and Remote Control Operation"](#), on page 110
- [Chapter A, "Remote Control Basics"](#), on page 194

### 5.1.3 Control of an R&S SGU from a Compatible R&S Signal Generator

If an R&S SGU is connected to a compatible R&S Signal Generator (e.g. R&S SGS), it extends its frequency range. In this setup, a controller does not need to access the R&S SGU directly. Instead, the compatible R&S Signal Generator acts as a controller to the R&S SGU. The generator performs all required settings automatically depending on the required output signal parameters.

The [Figure 5-3](#) shows a configuration example of the R&S SGU, directly controlled by an R&S SGS. For a detailed description of the connecting possibilities, refer to [Chapter 5.2, "Setups for Connecting an R&S SGS and an R&S SGU"](#), on page 39.

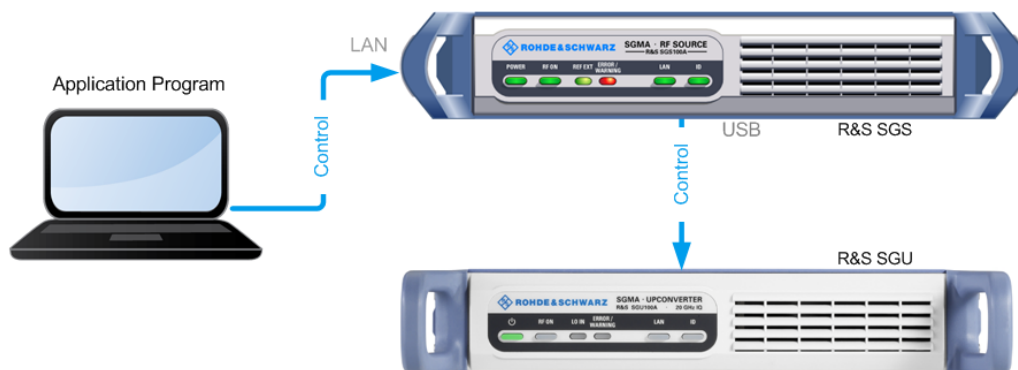


Figure 5-3: Configuration example: the R&S SGU as an extension to the R&S SGS

## 5.2 Setups for Connecting an R&S SGS and an R&S SGU

If an R&S SGU is connected to an R&S SGS, the R&S SGU acts as an extension to the R&S SGS extending its frequency range. In this setup, a controller does not need to access the R&S SGU directly. Instead, the R&S SGS acts as a controller to the R&S

SGU. The generator performs all required settings automatically depending on the required output signal parameters.

This chapter gives an overview of how to connect the instruments.

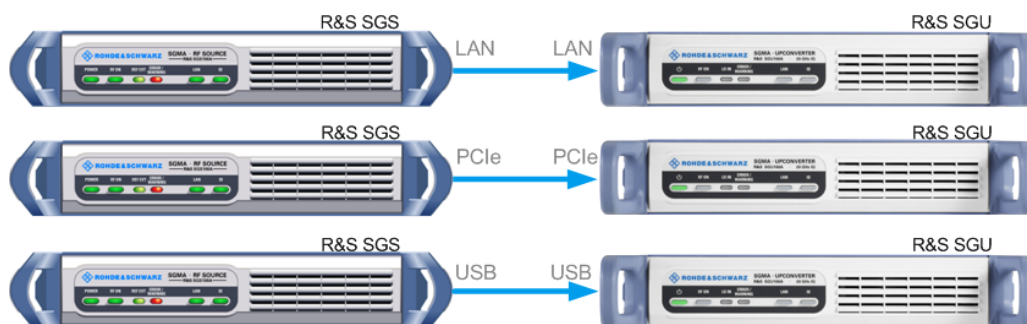
See:

- [Chapter 5.2.1, "Direct Connection"](#), on page 40
- [Chapter 5.2.2, "Connection in a Company Network"](#), on page 41
- [Chapter 5.2.3, "Connection with a PCIe Switch"](#), on page 44
- [Chapter 4.1, "R&S SGU as an Extension to the R&S SGS"](#), on page 31

## 5.2.1 Direct Connection

The R&S SGS and the R&S SGU can be connected through a direct connection as shown in [Figure 5-4](#).

### Direct connection of an R&S SGS and an R&S SGU



**Figure 5-4:** Direct connection of an R&S SGS and an R&S SGU

1. Connect the R&S SGS and the R&S SGU directly using one of the following options:
  - a) USB cable. Use a Type Micro-A connector for R&S SGS and a Type Micro-B connector for R&S SGU. See also [Chapter 2.3.4, "Connecting a Controller or a USB Device via USB"](#), on page 24.
  - b) LAN cable. No additional cable considerations are required.
  - c) PCIe cable. Refer to [Chapter 10.3.4, "Connecting the Controller and the Instrument"](#), on page 124 for cable requirements and setup information.
2. Switch on the R&S SGS and the R&S SGU.

The R&S SGS automatically identifies the connected R&S SGU as its extension and starts the extension mode.



For a direct PCIe connection, an automatic identification of the R&S SGU as an extension is only available for an R&S SGS with a "Controller > Revision" 5 or higher. For a description on how to manually set the PCIe identification, see [Chapter 9.7, "How to Manually Set a PCIe Direct Connection Between an R&S SGS and an R&S SGU"](#), on page 109.

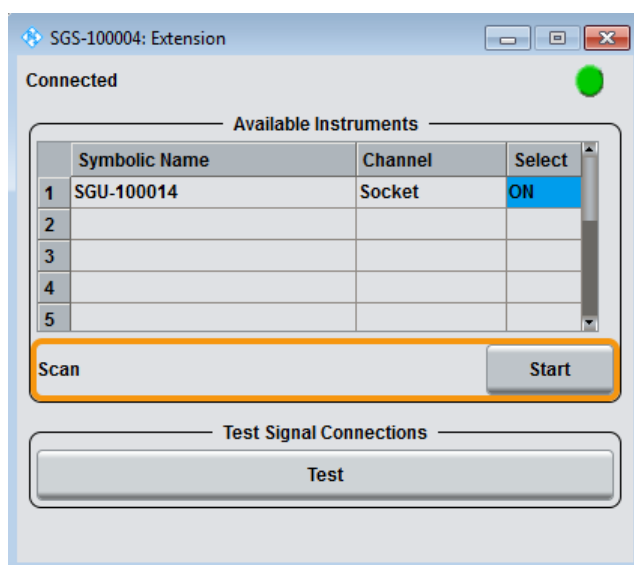
You can check the "Controller > Revision" of your instrument in the "SGMA-GUI > Instrument Name > Hardware Config" dialog.



#### If instrument is not automatically added as an extension

If the R&S SGU is not automatically added as an extension you can do that manually in the "SGMA-GUI > R&S SGS Name > Extension" dialog.

If the R&S SGU is not listed in the list of "Available Instruments", you can press "Scan > Start" to find the instrument.



## 5.2.2 Connection in a Company Network

### Connection of an R&S SGS and an R&S SGU in a Company Network

As a prerequisite for this example the R&S SGMA-GUI software has to be installed on a remote PC.

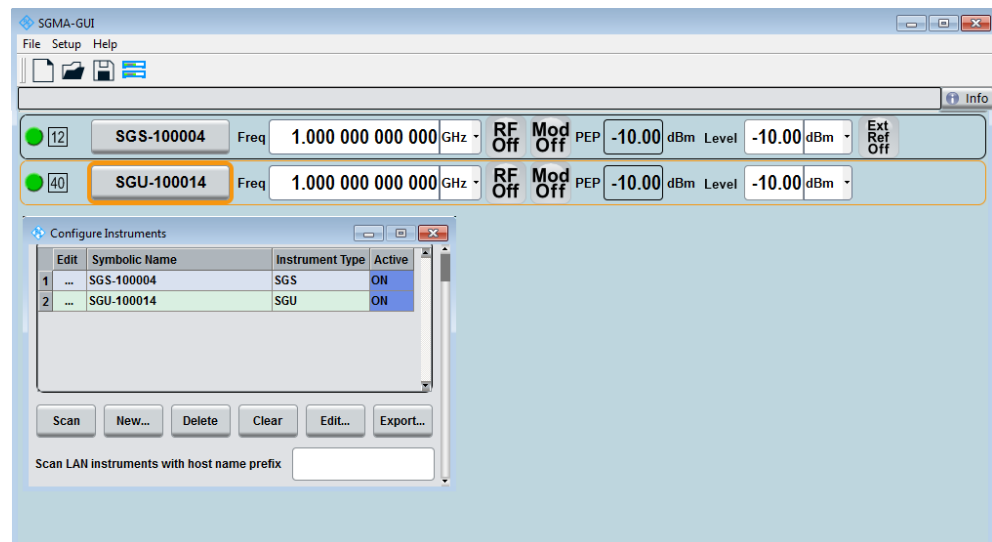


## Setups for Connecting an R&amp;S SGS and an R&amp;S SGU



Figure 5-5: Connection of an R&S SGS and an R&S SGU in a company network

1. Connect the test equipment as shown in [Figure 5-5](#):
  - a) Connect the R&S SGS, the R&S SGU and the controller to the company network.
  - b) Connect the RF OUT of the R&S SGS to the LO IN of the R&S SGU.
2. Switch on the R&S SGS and the R&S SGU.  
The POWER ON/STANDBY keys have to be **green** and not blinking.
3. Press the ID keys on the front panels of the R&S SGS and the R&S SGU.
4. On the connected remote PC, start the R&S SGMA-GUI software application.  
The main panel of the application and the configure instruments dialog open. Both instruments are added automatically to the instruments list and to the main panel of the R&S SGMA-GUI software.

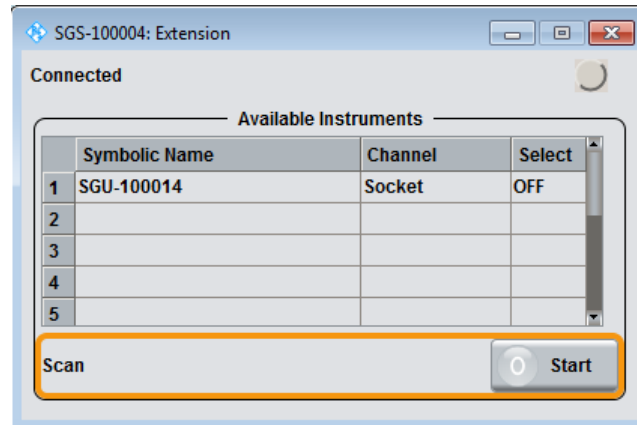


**Note:** If you connect the instruments to the company network for the first time this process may take several minutes.

- In the R&S SGMA-GUI main panel, the green indicator in front of the instrument's name confirms that there is a connection between the instrument and the remote PC and that the instrument is recognized by the software.

- Select "SGMA-GUI main panel > R&S SGS > Extension".

The "Extension" dialog opens.

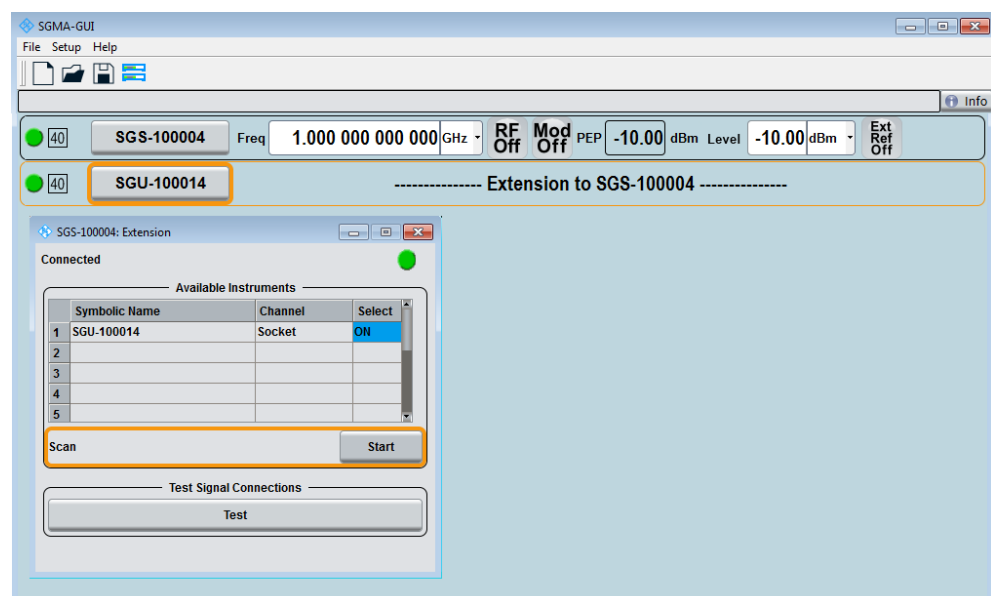


**Tip:** Instrument doesn't appear in the extension dialog. If the R&S SGU is not automatically shown in this dialog press "Scan > Start" to find the instrument.

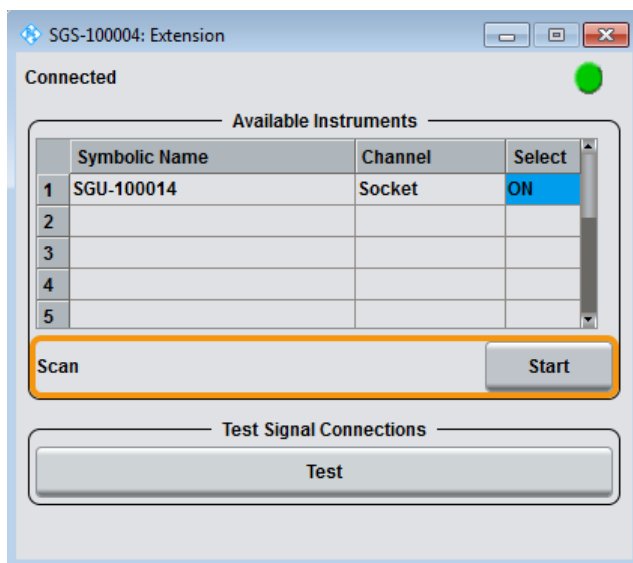
- Select the R&S SGU from the list and set "Available Instruments > Select > On" to enable it as an extension.

A green status indicator "Connected" indicates the successfully established remote connection between the R&S SGS and the R&S SGU.

The R&S SGMA-GUI indicates the extended frequency range of the R&S SGS and the activated extension mode.



- Select "Test Signal Connections > Test" to trigger a check of all required signal connections.



The diagram displays the connection state of the tested signal connections. If the test connections are correct (shown by an uninterrupted blue line), you can start using the R&S SGS and the R&S SGU in extension mode.

**Tip:** If your connection is marked as faulty- a red line is crossing the blue connection line - check whether the cables are connected properly. Check also if the connection cables are functioning properly.

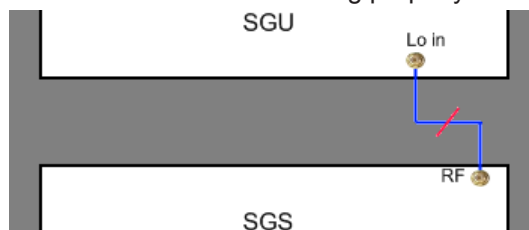
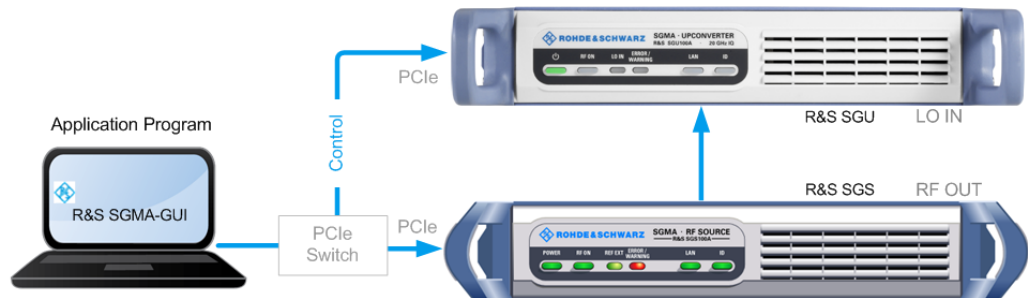


Figure 5-6: A faulty connection between an R&S SGU and an R&S SGS

### 5.2.3 Connection with a PCIe Switch

The R&S SGS and the R&S SGU can be connected through a PCIe switch as shown in Figure 5-7. This setup is recommended for achieving the highest setting/ measuring speeds.

### PCIe switch connection of an R&S SGS and an R&S SGU



**Figure 5-7: Connection of an R&S SGS and an R&S SGU through a PCIe switch**

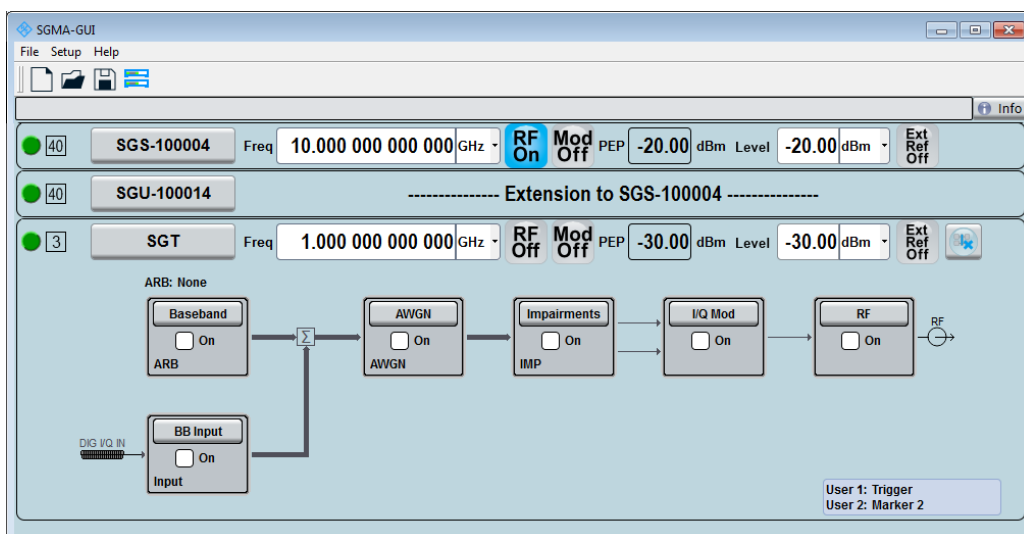
1. Connect the PCIe switch to a switched off computer with a single lane PCIe cable.
2. Connect the R&S SGS and the R&S SGU to the PCIe switch.
3. Switch on the R&S SGS and the R&S SGU.  
The POWER ON/STANDBY keys of both instruments have to be **green** and not blinking.
4. Switch on the computer.
5. On the computer start one of the following:
  - a) The R&S SGMA-GUI
  - b) An application program for remote control of the instruments
6. Manually (or remotely ) activate the R&S SGU as an extension to the R&S SGS.



The logical connection between an R&S SGS and an R&S SGU is established by the driver layer of a program (e.g. the R&S SGMA-GUI) or the library PCIeController.dll (Linux: libpciecontroller.so) of a remote control program on the PC. Such a program has to be running on the PC so that an R&S SGS is able to communicate with an R&S SGU.

## 6 Understanding the R&S SGMA-GUI Software

This section gives a detailed description of the R&S SGMA-GUI user interface and information on how to work with it. The main panel with the overview of the configured instruments is the operating and control interface for the whole program. From here, all program functions are accessible. This panel is displayed after the start of R&S SGMA-GUI. The program always loads the previously used settings so you can continue your work in the next session.



### 6.1 Operating Menu and Toolbar

On the top of the main panel, there are the menu bar, the toolbar and the info bar with the corresponding "Info" button. Some of the functions are accessible via the toolbar with its icons below the menu selection line.

The dialogs are built using elements, e.g., selection lists, checkboxes, and entry fields. A blue frame indicates that the selected item is active. In a highlighted element, entries can be made.

Table 6-1: Content of the operating menu

File	Setup	Help
New	Instruments	About
Open	Software	Contents
Save	Reset SGMA-GUI	Index
Save as		

File	Setup	Help
Exit		
Shut down instruments and exit		

### 6.1.1 File Menu

The R&S SGMA-GUI employs the standard Save/Recall file management function and allows you to store and reload settings in/to a file with a user-defined name and location (see also [Chapter 6.4.1, "Storing and Loading Settings"](#), on page 58).

In the following, the "File" menu of the R&S SGMA-GUI is described in detail. It incorporates standard functions.

#### **New**

Resets R&S SGMA-GUI and all connected instruments to their preset settings.

#### **Open**

Opens the standard file open browser for loading a saved R&S SGMA-GUI file (\*.savrc1). The file contains the user-specific settings of a session, such as instruments configured in the software, etc. The complete settings of a session can be saved and loaded.

Only files of this type are selectable.

**Note:** Instrument-specific settings, e.g. frequency and level settings, are stored locally on the particular instrument itself. These instruments settings are saved automatically in a predefined directory and loaded by default when starting the instrument again. The files with instrument settings are not accessible.

#### **Save**

Standard quick save of the settings of the current session if a filename previously has been applied. If not, the "Save As" dialog is opened.

#### **Save as**

Opens the standard file save browser for saving the settings of the current session. R&S SGMA-GUI files have the file extension .savrc1 so the name typed in is equipped with this extension. The complete settings of a session are saved.

#### **Exit**

Quits the R&S SGMA-GUI. The current settings of the instrument's session are saved and loaded by default when starting the software again.

**Note:** The instruments configured in the R&S SGMA-GUI are not shut down.

#### **Shut down instruments and exit**

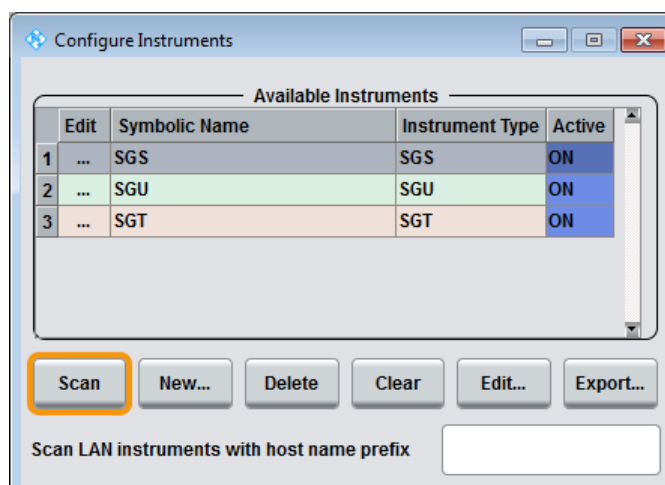
Quits the R&S SGMA-GUI and switches the connected instruments to the standby state (see also [Chapter 9.3, "How to Switch Between the Operating States"](#), on page 104 ).

## 6.1.2 Setup Menu

The setup menu provides access to dialogs for setting the general settings of the software, like dialogs for managing the connected instruments or dialogs providing information about the installed options.

### 6.1.2.1 Configure Instruments

This dialog is the central point for managing the instrument that will be configured and operated via the R&S SGMA-GUI. New instruments can be created and appended to the list of available instruments, connection settings can be edited, instruments can be removed from the list or they can be deactivated, but kept in the list for further use.



Refer to [Chapter 6.4.2, "Handling Instruments in the R&S SGMA-GUI"](#), on page 58 for information on how to configure and manage instruments in R&S SGMA-GUI.

#### Available Instruments

This section comprises a list of configured instruments. Each instrument is represented by a "Symbolic Name" which is also displayed in the main panel and an "Instrument Type". It is also displayed whether the instrument is activated in the R&S SGMA-GUI and hence displayed in the main panel or not.

Remote command:

`:INSTruments:COUNt?` on page 67

`:INSTruments:NAME` on page 67

`:INSTruments:TYPE` on page 69

`:INSTruments:ACTive[:STATe]` on page 66

#### Scan

Triggers a scan function and searches for instruments connected to the remote computer via all the available interfaces. During the scan process, a progress bar is displayed.

**Tip:** The first initialization of a newly connected instrument in a network and the instrument's request to the DHCP server for an IP address may take some time. During this time, the instrument does not respond to the query sent by the scan function. If the instrument does not appear in the list of "Available Instruments", trigger the scan function again after some minutes.

Remote command:

:INSTRUMENTS:SCAN on page 68

### New Instrument

Calls the [Add/Edit Instruments](#) dialog.

### Delete Instrument

Removes the selected instrument from the list of [Available Instruments](#).

### Edit Instrument

Calls the [Add/Edit Instruments](#) dialog.

### Clear Instrument

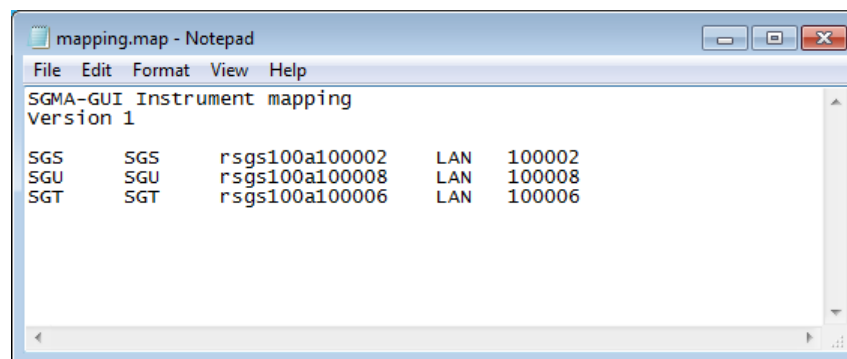
Removes all instruments from the list of [Available Instruments](#).

### Export

Opens the standard file save browser for saving the list of the available instruments in a mapping file. The mapping files have the file extension `.map` so the filename typed in is automatically equipped with this extension.

A mapping file provides a cross-reference between the instruments' symbolic names and their respective remote control parameters. The information in the mapping file is grouped in rows, where one row corresponds to one configured instrument. The rows have the following structure:

```
<InstrumentType> <SymbolicName> <IP_Address/Hostname>
<RemoteChannel> <SerialNumber>
```



**Figure 6-1:** Mapping file example

**Tip:** In a remote control application program, address the instruments by their symbolic names and retrieve the remain required settings from the mapping file. This workflow is especially useful for frequent exchange of instruments.

Remote command:

:INSTRUMENTS:MAPPING:FILE on page 67



**Scan LAN instruments with host name prefix**

Sets the prefix the searched host names begin with. Use this function to limit the amount of the searched instruments and to speed up the scan process.

For example, set this field to "RsSGS, RsSGU, RsSGT", if you want to search for all available instruments.

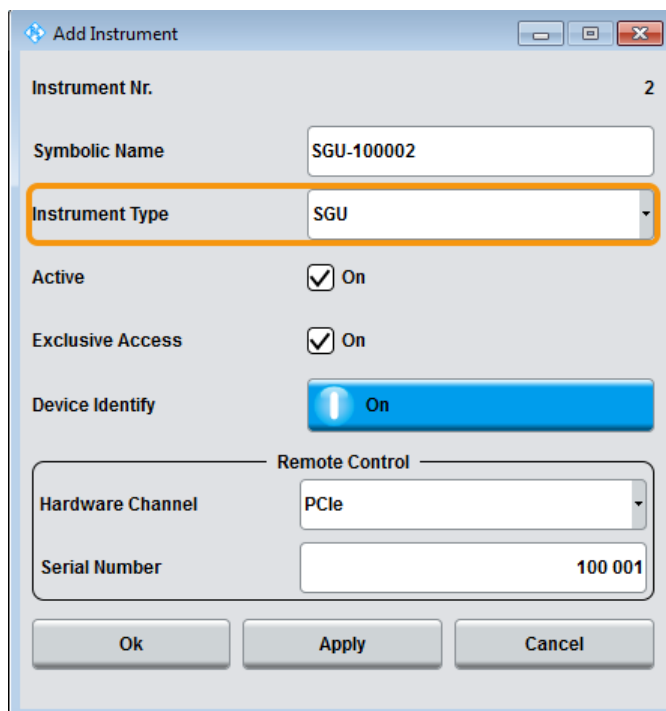
**Tip:** If you start a scan for an instrument with a set IP address and it doesn't appear in the list of available instruments it may be due to the prefixes written in this field. You can perform another scan while leaving this field empty.

Remote command:

:INSTRUMENTS:SCAN:HNPRefix on page 69

**6.1.2.2 Add/Edit Instruments**

The dialog provides access to the main instrument's settings, such as "Symbolic Name", "Instrument Type" and connection settings.



Refer to [Chapter 6.4.2, "Handling Instruments in the R&S SGMA-GUI"](#), on page 58 for information on how to configure and manage instruments in R&S SGMA-GUI.

**Instrument Nr.**

Automatically assigned number that indicates the instrument's index in the list of "Available Instruments".

**Symbolic Name**

Selects the alias name of the instrument.

Remote command:

`:INSTRUMENTS:NAME` on page 67

### Instrument Type

Selects the instrument's family.

Remote command:

`:INSTRUMENTS:TYPE` on page 69

### Active

Activates/deactivates the display of the instrument's settings in the main panel.

**Note:** Only instruments in an active state can be controlled from the R&S SGMA-GUI!

Remote command:

`:INSTRUMENTS:ACTIVE[:STATE]` on page 66

### Exclusive Access

Checks whether the instrument is locked by another user and if not locks the instrument. When an instrument is locked, it is reserved and can be operated manually or remote **exclusively** from the remote PC on which the R&S SGMA-GUI is running or from which the SCPI command is sent.

For interfaces using VISA, i.e. for LAN and USB, enabling the "Exclusive Access" triggers the standard `viLock` request. For remote control over PCIe or Socket, the lock request is performed on a higher application level.

**Note:** It is recommended to lock the instrument prior to further configuration.

Locked instruments will not be found by the scan function.

The instrument has to be unlocked to allow operation from another remote PC.

**Note:** The two functions "Exclusive Access" and monitoring are mutually exclusive. Disable "Exclusive Access" if the instrument is monitored by an external PC.

Remote command:

`:INSTRUMENTS:EACCESS[:STATE]` on page 67

`:LOCK?` on page 140

`:UNLOCK` on page 140

### Device Identity

Triggers the device identification function. The LAN LED on the front panel of the selected instrument blinks.

See also [Chapter 6.4.4, "Bidirectional Instrument Identification"](#), on page 61.

### Hardware Channel

Selects the hardware interface used by the remote channel.

Remote command:

`:INSTRUMENTS:REMOTEC:CHANNEL` on page 68

### Instrument Name / IP Address

Enters the IP address or the host name of the connected instrument.

See also [Chapter 6.4.3, "Finding Out the Default Hostname of the Instrument"](#), on page 61.

Remote command:

:INSTRuments:REMOte:NAME on page 68

### Serial Number

Enters the serial number as instrument's identification while using the USB or PCIe interfaces for remote control.

Remote command:

:INSTRuments:SERial on page 69

### OK

Confirms the settings and closes the dialog.

### Apply

Confirms the settings.

### Cancel

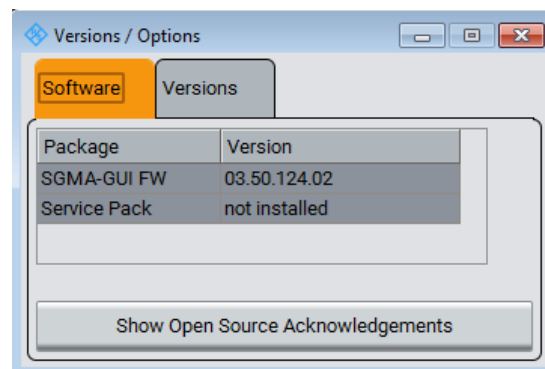
Discards settings and closes the dialog.

## 6.1.2.3 Versions/Options Dialog

### Querying information about the installed options and software version

- ▶ Select "Setup > Software".

An info dialog opens, showing program information.



### Software

Displays information on:

- "Package" Installed software packages.
- "Version" Release of the software package.

### Show Open Source Acknowledgments

Accesses the list of the used open source software packages and the corresponding verbatim license texts.

### Versions

Shows the installed software platform and its version.

### 6.1.2.4 Reset SGMA-GUI

Resets R&S SGMA-GUI to its factory preset settings.



The connected instruments are not affected by this preset.

To preset one specific instrument to its factory preset settings, select "SGMA-GUI > Instrument Name > Setup > Factory Preset". Refer to [Chapter 8.9, "Factory Preset"](#), on page 98 for an overview of the settings affected by this function.

### 6.1.3 Help

The R&S SGMA-GUI is equipped with a context-sensitive help function. A help page can be called any time during software operation.

The context-sensitive page which is opened with the F1 button is part of a comprehensive help system.

It is possible to move from this context-sensitive page to any page of the help system. An overview of the contents of the online help can be reached via the menu "SGMA-GUI > Help > Contents".

A search for keywords within the help function is available via menu item "SGMA-GUI > Help > Index".

## 6.2 Info Dialog and Messages in the Info Bar

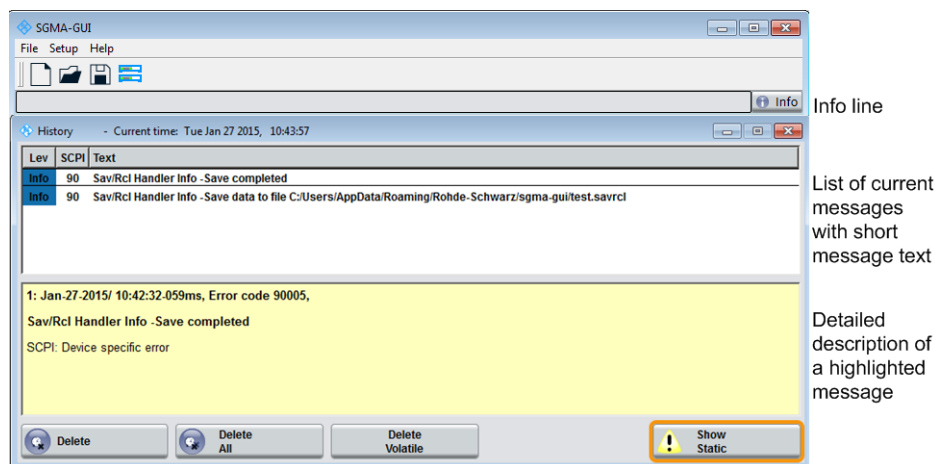
A few operating states and the current messages are displayed in the info line. For information on messages in greater detail and their management, an "Info" dialog can be opened.

### 6.2.1 Info Dialog

The "Info" dialog provides a list of currently active permanent messages and a detailed description of each message. The messages are color-coded according to their level.

#### Accessing the info dialog

- ▶ In the "R&S SGMA-GUI main panel", select the "Info" button.  
The "Info" dialog opens.



The upper part of the "Info" dialog lists the currently active permanent messages. See the following table for explanation of the displayed information.

Parameter	Description
"LEV"	Message level. Messages referring to a logical component of R&S SGMA-GUI, e.g., Unicode, are marked in red color, info messages are marked in black color. The following levels might occur: <ul style="list-style-type: none"> <li>• Err: Error message</li> <li>• Info: Information message</li> <li>• Sys: System message</li> <li>• Crit: Critical message</li> </ul> For detailed information on the message types, see <a href="#">Chapter 6.2.2, "Understanding the Messages in the Info Bar"</a> , on page 55.
"SCPI"	Indicates the SCPI error code.
Text	A list of all currently permanent messages in the order of their occurrence, i.e., the most recent message is displayed first.

The buttons in the lower part of the "Info" dialog provide quick access to some functions for managing these messages. For a detailed description on how to clear error messages or display a history of all messages, refer to [Chapter 6.4.5, "Managing Messages in the Info Dialog"](#), on page 63.

Function	Description
"Delete"	Clears the highlighted message. This button is available only if the history of the messages is displayed.
"Delete All"	Clears all messages. This button is available only if the history of the messages is displayed.
"Del. volatile"	Clears all brief messages. This button is available only if the history of the messages is displayed.
"Show History/Static"	Calls the list of all messages that have occurred since instrument switch-on. The most recent messages are displayed at the top of the list. When the button is pressed again, the list of current messages is displayed.



Refer to [Chapter 6.4.5, "Managing Messages in the Info Dialog"](#), on page 63 for information on how to manage messages.

## 6.2.2 Understanding the Messages in the Info Bar

Messages indicate information, warnings, and errors. They are displayed in the info line in different colors depending on their importance and display duration. The following messages are displayed:

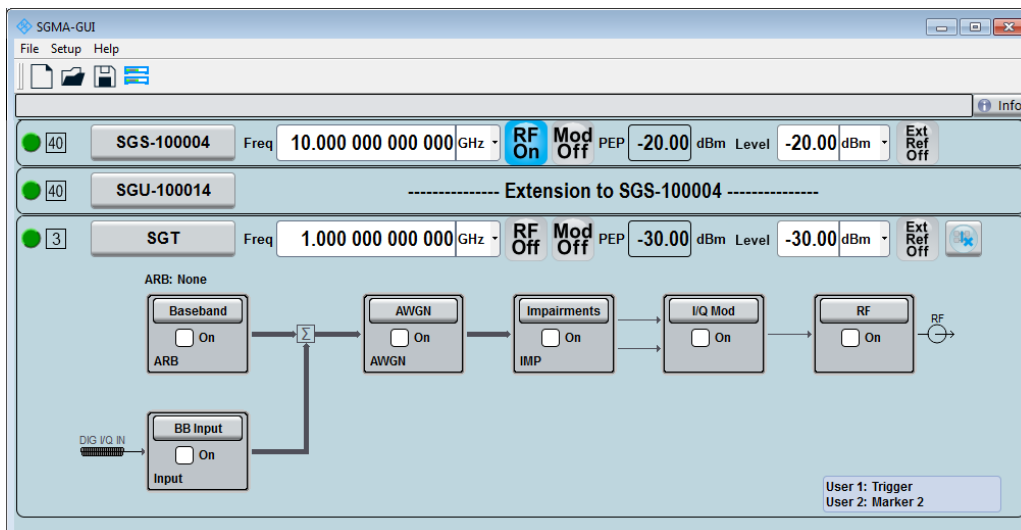
- Error  
There are two options:
  - Critical errors are errors that prevent the instrument from working, e.g. an HW failure. Critical errors are displayed in red color.
  - System errors are errors that concern the operating system, e.g., wrong file path. System errors are displayed in black color.
- Information  
The information, e.g., file not found, is displayed in black color.
- Warning  
A warning indicates a less significant error and is displayed in black color.
- Brief message  
Brief messages report automatic settings in the program, e.g. switching on illegal entries that are not accepted by the program, e.g., range violations. They are displayed in the info line on a yellow background. They are displayed on top of status information or permanent messages.  
Brief messages usually do not demand user actions and disappear automatically after a short period of time. They are stored in the history, however.
- Permanent messages  
Permanent messages are displayed if an error occurs that impairs further program operation. The error signaled by a permanent message must be eliminated before correct software operation can be ensured.  
The message is displayed until the error is eliminated. It covers the status display in the info line. After error elimination, the message automatically disappears and is also recorded in the history.

## 6.3 Main Panel

The main panel of the R&S SGMA-GUI provides quick access to the main settings of the configured instruments. The display shows one row per instrument and comprises the instrument name and state, the used frequency and power level, the states of the RF output and modulator and the used reference source.

Click one of the buttons with an instrument name on it to access the menu tree with further settings for the corresponding instrument. For a detailed description of the provided settings, see:

- [Chapter 8, "General Instrument Settings and Instrument Setup"](#), on page 86 for general settings
- [Chapter 7, "Upconverter Settings"](#), on page 70 for R&S SGU settings.



### Instrument/Connection State

The three colors of the state indicator in front of the instrument's name distinguish between the following states:

- Gray: the instrument is configured and activated in the R&S SGMA-GUI but there is no connection to the instrument.
- Green: the instrument is active, the connection is working and the instrument can be manually and remotely operated.
- Red: the instrument is in one of the following states:
  - Standby state  
To operate the instrument manually, it has to be switched to ready state (see ["To return the instrument from standby to ready state"](#) on page 105).
  - Instrument locked  
The red state indication together with the message "Instrument Locked" in the "Info" line indicates that the instrument is locked for [Exclusive Access](#) from another SGMA-GUI or controller.
  - The instrument is performing a time consuming operation, e.g. a selftest.

### Maximum Frequency

The numbers in the rectangular box **6** on the left of the instrument's name indicate the maximum frequency of the instrument.

### Pulse Modulation

A **PM** sign on the left of the instrument's name indicates that the pulse modulation is switched on.

**Instrument Name**

Displays the alias name of the instrument, as selected by the parameter "SGMA-GUI > Setup > Instruments > Add/Edit Instruments > Symbolic Name".

Click the button to access a menu tree for configuring the available instrument's settings, e.g. "Level" settings.

**Frequency**

Sets the RF frequency at the RF output connector of the selected instrument.

Remote command:

`[ :SOURce ] :FREQuency [ :CW|FIXed ]` on page 160

**RF On/Off**

Activates and deactivates the RF output signal.

The current state of the RF output (activated and deactivated) is indicated in the main panel with the different block color (blue or gray) and the status "On/Off".

Remote command:

`:OUTPut [ :STATe ]` on page 158

**Mod State**

Switches the I/Q modulation on and off.

Remote command:

`[ :SOURce ] :IQ:STATe` on page 161

**PEP**

Displays the Peak Envelope Power (PEP) of the RF signal of the selected instrument. The value is calculated as follows:

"PEP" = Level + Crest Factor

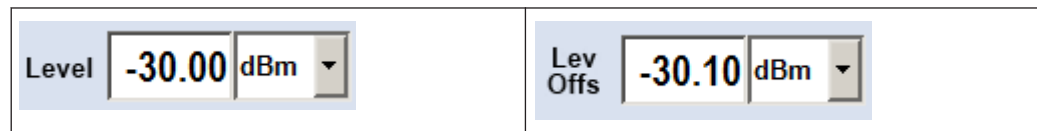
Remote command:

`[ :SOURce ] :POWer:PEP?` on page 167

**Level/Level Offset**

Sets the RF level at the RF output connector of the selected instrument.

If you set a level offset, it will be indicated in the R&S SGMA-GUI main panel by a change in the name of this parameter from "Level" to "Level Offset".



**Note:** The SCPI command `[ :SOURce ] :POWer [ :LEVel ] [ :IMMediate ] [ :AMPLitude ]` sets the level of the "Level" display, that means the level containing offset while `[ :SOURce ] :POWer:POWer` sets the level at the RF output connector.

Remote command:

`[ :SOURce ] :POWer [ :LEVel ] [ :IMMediate ] [ :AMPLitude ]` on page 166

`[ :SOURce ] :POWer:POWer` on page 168



## 6.4 Working with R&S SGMA-GUI

This section explains how to work with the R&S SGMA-GUI software and perform configuration tasks for manual operation of the instruments.

### 6.4.1 Storing and Loading Settings

To proceed work with a particular configuration of the instruments in the R&S SGMA-GUI, it is useful to save the used settings and load them again later.

#### How to store and load settings

1. Select "SGMA-GUI main panel > File > Save As".
2. Navigate to the desired directory and enter the filename.  
The extension \*.savrc1 is applied automatically.  
The current settings of the software are saved to the selected file.
3. To load settings from a file, select "SGMA-GUI main panel > File > Open"
4. Navigate to the directory the file is stored in and select the setting file.  
The saved settings are loaded to the R&S SGMA-GUI and the main panel of the software displays the saved instrument's configuration.

### 6.4.2 Handling Instruments in the R&S SGMA-GUI

This section provides information on how to configure and manage instruments in the R&S SGMA-GUI.

For reference information about all provided settings in the user interface, refer to the corresponding sections:

- [Chapter 6.1.2.1, "Configure Instruments"](#), on page 48 and [Chapter 6.1.2.2, "Add/Edit Instruments"](#), on page 50
- [Chapter 6.1.2.3, "Versions/Options Dialog"](#), on page 52  
[Chapter 6.1.2.4, "Reset SGMA-GUI"](#), on page 53

#### 6.4.2.1 How to Automatically Add New Instruments to the SGMA-GUI

1. For each new instrument perform the following steps:
  - a) Connect the instrument to the network.
  - b) Switch on the instrument.
  - c) Press the ID key on the front panel of the instrument.
2. Start the SGMA-GUI on a computer connected to the same network.  
All instruments are added automatically to the main panel of the SGMA-GUI.

### 6.4.2.2 How to Manually Add New Instruments to the SGMA-GUI

1. In the R&S SGMA-GUI main panel, select "Setup > Instruments".  
The [Configure Instruments](#) dialog opens.
2. Select the "New" button.  
The [Add Instrument](#) dialog opens to register a new instrument.
3. In the "Symbolic Name" field, enter an alias name of your choice, e.g. SGU-100021.
4. In the "Instrument Type" field, select the device family to connect to.
5. Select "Remote Control > Hardware Channel" and select the hardware interface.
6. For LAN or Socket interfaces, select "Remote Control > Instrument Name / IP Address" and enter the IP Address or the hostname of the connected instrument, e.g. rssgu100a100021.  
**Tip:** See also [Chapter 6.4.3, "Finding Out the Default Hostname of the Instrument"](#), on page 61 .
7. For USB or PCIe interfaces, select "Remote Control > Serial Number" and enter the serial number of the connected instrument , e.g. 100021.
8. Set "Active > On" to activate the instrument. Only active instruments are displayed in the R&S SGMA-GUI main panel.
9. Click "OK" to confirm the settings and to close the dialog or press the "Apply" button to confirm the settings.
10. Click the "Cancel" button to discard settings and to close the dialog.

### 6.4.2.3 How to Scan for New Instruments

1. In the R&S SGMA-GUI main panel, select "Setup > Instruments".  
The [Configure Instruments](#) dialog opens.
2. Click the "Scan" button to trigger the instrument to scan all remote channel interfaces for connected instruments.

**Tip:** To limit the amount of the searched instruments and to speed up the scan process, select "Configure Instruments > Scan LAN instruments with hostname prefix" and enter the prefix the searched hostnames begin with.  
The scan function searches only for instruments whose hostnames begin with the selected prefix.

All instruments which are connected to one of the available interfaces, are switched on and are not locked are displayed in the "Available Instruments" list.

The R&S SGMA-GUI obtains all information for connecting to the instrument, so further configuration is not necessary.

#### 6.4.2.4 How to Activate Instruments for Control from the R&S SGMA-GUI

1. In the R&S SGMA-GUI main panel, select "Setup > Instruments".  
The "Available Instruments" in the [Configure Instruments](#) dialog lists all instruments configured in the software.
2. Select the newly configured/connected or deactivated instrument and set "Active > On" to activate it.  
**Tip:** Only active instruments are displayed in the R&S SGMA-GUI main panel!

#### 6.4.2.5 How to Edit Instruments

1. In the R&S SGMA-GUI main panel, select "Setup > Instruments".  
The [Configure Instruments](#) dialog opens and lists the "Available Instruments".
2. Select the instrument to be edited and click the "Edit" button.  
The [Edit Instrument](#) dialog opens.
3. Change the settings and confirm with OK.  
The edited settings are applied.

#### 6.4.2.6 How to Delete an Instrument

1. In the R&S SGMA-GUI main panel, select "Setup > Instruments".  
The [Configure Instruments](#) dialog opens.
2. Select the instrument to be deleted and click the "Delete" button.  
The selected instrument is deleted from the list of "Available Instruments".

#### 6.4.2.7 How to Delete All Instruments

1. In the R&S SGMA-GUI main panel, select "Setup > Instruments".  
The [Configure Instruments](#) dialog opens.
2. Click the "Clear" button.  
All instruments are deleted from the list of "Available Instruments".

### 6.4.2.8 How to Reserve the Instrument for Control

1. Open the "SGMA-GUI > Setup > Instruments > Configure Instruments" dialog, select the instrument in the list of "Available Instruments" and select "Edit".
2. In the "Edit Instrument" dialog, enable "Exclusive Access".
3. Alternatively, send the SCPI command `:INSTRuments:EACcess[:STATe]` from the external PC the R&S SGMA-GUI is installed on.

The instrument is reserved for control from this external PC and cannot be accessed from any other controller. A scan function started from another controller finds the instrument but the instrument is indicated as locked.



The two functions "Exclusive Access" and monitoring are mutually exclusive!

The "Exclusive Access" must be disabled to remote control or monitor the instrument from another external PC (see [Chapter 10.5, "Using the R&S SGMA-GUI to Monitor the Remote Control Operation"](#), on page 127).

### 6.4.3 Finding Out the Default Hostname of the Instrument

The default hostname of the instrument is a non-case-sensitive string built as follows:

`hostname = <instrument name><serial number>`, where

`<serial number>` is the individual serial number of the instrument

`<instrument name>` is the complete name of the instrument, written without spaces.

#### How to query the hostname of the instrument

1. Find the individual serial number on rear of the instrument , e.g. 100021.
2. Build the default hostname.

For the R&S SGU with serial number 100021, the default hostname is `rssgu100a100021`.



For instructions on how to change the default hostname, refer to [Chapter 9.4, "How to Use Computer Names"](#), on page 106.

### 6.4.4 Bidirectional Instrument Identification

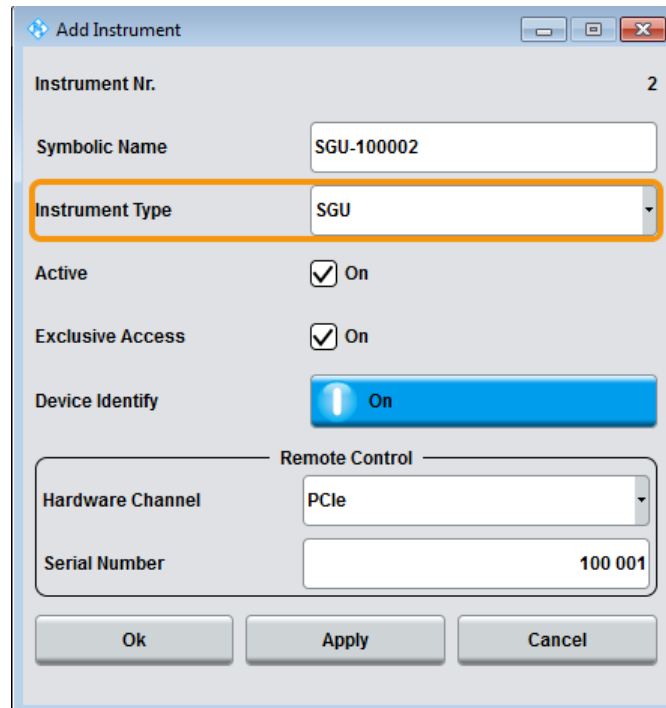
In practice, instruments are integrated into a large network or placed in racks together with several other instruments of the same kind. It might be difficult then to find out which of the instruments configured in the R&S SGMA-GUI corresponds to which physical instrument or to localize all instruments operated by the current controller.

The R&S SGMA-GUI and the instrument provide the "Device Identification" function for this purpose.

### How to find an instrument in the R&S SGMA-GUI

- ▶ If several instruments have been configured and activated in the R&S SGMA-GUI, press the ID button on the instrument's front panel to trigger device identification.

The "Edit Instrument" dialog of this instrument opens.



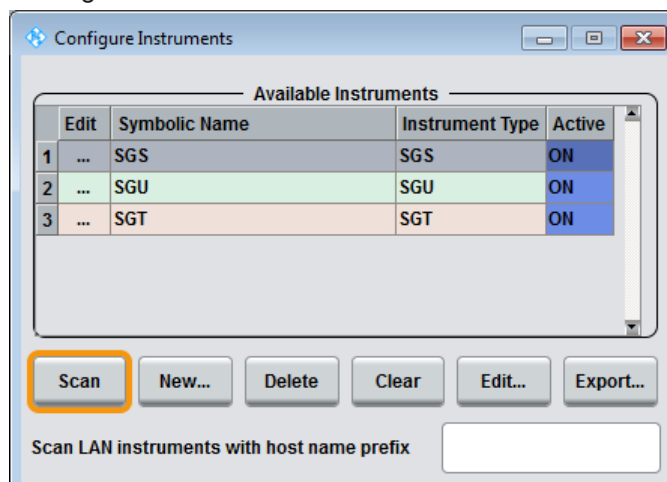
Field "Edit Instrument > Symbolic Name" displays the name of the instrument as shown in the R&S SGMA-GUI main panel.



### Dialog "Edit Instrument" does not appear

If this dialog does not open, perform the following:

- Check whether the instrument is correctly connected to the external PC on which you work with the R&S SGMA-GUI.
- Check if the instrument is configured in the R&S SGMA-GUI and perform, if necessary, the steps described in [Chapter 6.4.2, "Handling Instruments in the R&S SGMA-GUI"](#), on page 58.
- Select "SGMA-GUI > Setup > Instruments", check the state of the instrument in the "Configure Instruments > Available Instruments" table and activate it, if disabled.



### How to identify an instrument in an instrument set

- ▶ To identify the instrument in an instrument set, use one of the device identification functions:
  - a) Select "SGMA-GUI > Setup > Instruments > Available Instruments > Instrument > Edit > Edit Instrument" and trigger "Device Identify"
  - b) Select "SGMA-GUI > Instrument Name > Setup > Remote > Remote Channels" and trigger "Device Identify"

The green LAN LED on the front panel of the instrument blinks.

## 6.4.5 Managing Messages in the Info Dialog

### How to get additional information on the message

- ▶ In the "Info" dialog, click a message to select it.

In the lower section of the dialog, additional information on the highlighted message is displayed.

#### How to display all messages

- ▶ In the "Info" dialog, click the "History" button.

A history of all messages that have occurred since the R&S SGMA-GUI software was started is listed in the upper dialog pane. The most recent message is displayed first.

#### How to delete an error message

- ▶ In the "Info" dialog, select the highlighted message and click the "Delete" button.

**Tip:** This button is available only when the history of the messages is displayed.

The highlighted message is cleared.

#### How to delete all error messages

- ▶ In the "Info" dialog, click the "Delete All" button.

**Tip:** This button is available only when the history of the messages is displayed.

All messages are cleared.

#### How to delete all brief messages

- ▶ In the "Info" dialog, click the "Del. volatile" button.

**Tip:** This button is available only when the history of the messages is displayed.

All brief messages are cleared.

#### How to call the history

1. In the "Info" dialog, click the "History" button.

A list of all messages that have occurred since the instrument switch-on is displayed. The most recent messages are displayed at the top of the list.

2. Click the "History" button once more.

A list of current messages is displayed.

## 6.5 Remote Control of the R&S SGMA-GUI

This section focuses on the remote control of the R&S SGMA-GUI software.

### 6.5.1 Configuring Instruments in the R&S SGMA-GUI

This section provides an example of the automation of the R&S SGMA-GUI.

In the following example we assume that a remote PC with installed R&S SGMA-GUI on it is connected to a LAN and that the remote PC and the instruments are switched on.

For more information, refer to [Chapter 2.3, "Connecting an External PC and Devices"](#), on page 20.

```
// *****
// Trigger the scan function to search for instruments connected
// to the remote computer via all of the available interfaces.
// *****

:INSTRuments:SCAN:HNPRefix "rsvg"
// scan returns only instruments with hostname beginning with "rsvg"
:INSTRuments:SCAN 1
*OPC?

// *****
// Query the number of available instruments and the settings of each
// configured instrument: instrument type, symbolic name,
// remote channel used, serial number, hostname/IP address
// Adjust settings if required
// *****

:INSTRuments:COUNT?
// Response: 3

:INSTRuments:TYPE?
// Response: SGU,SGS,SGT

:INSTRuments:NAME?
// Response: SGU-100002,SGS-100006, SGT-100008

:INSTRuments:SERial?
// Response: 100002,100006,100008

:INSTRuments:REMOte:CHANnel?
// Response: LAN,USB, PCIE

:INSTRuments:REMOte:NAME?
// Response: rsvgu100a100002, rsvgsgs100a100006, rsvgsgt100a100008

// *****
// Check the instrument state and activate instruments if required
// *****

:INSTRuments:ACTive:STATe?
// Response: 0,1,1
:INSTRuments:ACTive:STATe ON,OFF,OFF
// Activates the first instruments in the list,
// i.e. the instruments with symbolic names SGS-100006
```



```
// *****
// Export the configuration into a mapping file
// *****

:INSTRuments:MAPPING:FILE 'd:\mapping_files\mapping.map'

// *****
// Enable exclusive access for the selected instrument
// *****

:INSTRuments:EACCESS:STATE?
// Response: 0,0,0
:INSTRuments:EACCESS:STATE ON,OFF, OFF
// Locks the first instrument
```

## 6.5.2 R&S SGMA-GUI Settings

This section comprises the SCPI commands provided to remote control the R&S SGMA-GUI.

:INSTRuments:ACTive[:STATe].....	66
:INSTRuments:COUNT?.....	67
:INSTRuments:EACCESS[:STATe].....	67
:INSTRuments:MAPPING:FILE.....	67
:INSTRuments:NAME.....	67
:INSTRuments:REMOte:CHANnel.....	68
:INSTRuments:REMOte:NAME.....	68
:INSTRuments:SCAN.....	68
:INSTRuments:SCAN:HNPRefix.....	69
:INSTRuments:SERial.....	69
:INSTRuments:TYPE.....	69

---

### :INSTRuments:ACTive[:STATe] <State>

Enables/disables the instrument for the R&S SGMA-GUI. The main panel of this software displays only activated instruments.

#### Parameters:

<State>                   List of BOOL-values  
                           <StateInstr#1>,<StateInstr#2>,...  
                           0, 1, ON, OFF

**Example:**               See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:**    See ["Available Instruments"](#) on page 48

---

**:INSTruments:COUNT?**

Queries the number of the currently available instruments.

**Return values:**

<Count> float  
Range: 0 to 12

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Usage:** Query only

**Manual operation:** See ["Available Instruments"](#) on page 48

---

**:INSTruments:EACCess[:STATe] <State>**

"Locks" the instruments, meaning the instrument is reserved and can be operated exclusively from the remote PC that sent this SCPI command.

**Tip:** It is recommended to lock the instrument prior to further configuration.

**Parameters:**

<State> List of BOOL-values  
<LockInstr#1>,<LockInstr#2>,...  
0,1,OFF,ON

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:** See ["Exclusive Access"](#) on page 51

---

**:INSTruments:MAPPing:FILE <File>**

Saves the list of the available instruments in a mapping file. Mapping files are stored with the predefined file extension `.map`; the file extension may be omitted.

The file is saved in the default directory. Use the command `MMEM:CDIRECTory` to change the default directory or specify the complete path.

**Parameters:**

<File> string

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:** See ["Export"](#) on page 49

---

**:INSTruments:NAME <Name>**

Selects the alias name of the instruments, i.e. sets the "Symbolic Name".

**Parameters:**

<Name> <SymbolicNameInstr#1>,<SymbolicNameInstr#2>,...

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:** See ["Available Instruments"](#) on page 48

**:INSTruments:REMOte:CHANnel** <Channel>

Sets the hardware interface used by the remote channel.

**Parameters:**

<Channel> List of CHAR-Data  
 <Channellnstr#1>,<Channellnstr#2>,...  
 The available interfaces are: LAN, USB, SOCKET, PCIe, GPIB, HiSLIP

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:** See ["Hardware Channel"](#) on page 51

**:INSTruments:REMOte:NAME** <Name>

Enters the IP Address or the host name of the connected instrument.

**Parameters:**

<Name> <Hostname/IP-Addresslnsr#1>,<Hostname/IP-Addresslnsr#2>,...

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:** See ["Instrument Name / IP Address"](#) on page 51

**:INSTruments:SCAN** <State>

Triggers a scan function and searches for instruments connected to the remote computer via all of the available interfaces.

**Parameters:**

<State> number  
 1 = triggers the scan function, 0 = aborts the running scan process  
 The query command returns 1 as long as scan is running; 0 indicates completed scan process.

**Example:** See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:** See ["Scan"](#) on page 48

**:INSTruments:SCAN:HNPRefix** <Prefix>

Sets the prefix the searched host names begin with.

**Parameters:**

<Prefix>                      string

**Example:**                      See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:**    See ["Scan LAN instruments with host name prefix"](#) on page 50

**:INSTruments:SERial** <Serial>

Enters the serial number as instrument's identification while using the USB interface for remote control.

**Parameters:**

<Serial>                      <SerialNumberInstr#1>, <SerialNumberInstr#2>,...

**Example:**                      See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:**    See ["Serial Number"](#) on page 52

**:INSTruments:TYPE** <Type>

Selects the instrument's family.

**Parameters:**

<Type>                      List of CHAR-Data  
<TypeInstr#1>,<TypeInstr#2>,...

**Example:**                      See [Chapter 6.5.1, "Configuring Instruments in the R&S SGMA-GUI"](#), on page 64.

**Manual operation:**    See ["Available Instruments"](#) on page 48

### 6.5.3 List of R&S SGMA-GUI Commands

:INSTruments:ACTive[:STATe].....	66
:INSTruments:COUNT?.....	67
:INSTruments:EACCess[:STATe].....	67
:INSTruments:MAPPing:FILE.....	67
:INSTruments:NAME.....	67
:INSTruments:REMOte:CHANnel.....	68
:INSTruments:REMOte:NAME.....	68
:INSTruments:SCAN.....	68
:INSTruments:SCAN:HNPRefix.....	69
:INSTruments:SERial.....	69
:INSTruments:TYPE.....	69

## 7 Upconverter Settings

This section summarizes the settings necessary to configure the instrument for signal generation. The description in this section follows the menu tree structure of the graphical user interface. Each of the discussed topics follows a common structure, providing basic background information and reference to the user interface.

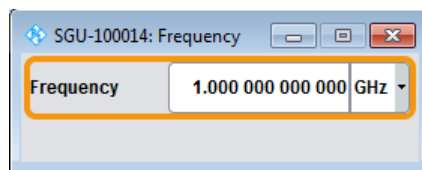
Additionally, there is a section summarizing advanced configuration tasks.

For step-by-step instructions for fulfilling typical tasks, refer to [Chapter 9, "Performing Configuration Tasks"](#), on page 101.

### 7.1 Frequency Settings

Depending on the installed options, the instrument provides an adjustable output frequency in the frequency range of 10 MHz to 40 GHz.

- ▶ To access this dialog, select "SGMA-GUI > Instrument Name > Frequency".



#### Configuring the RF Frequency

- ▶ To change the RF frequency of the selected instrument, perform one of the following:
  - Select "SGMA-GUI main panel > Freq" and enter the desired frequency.
  - Select "SGMA-GUI > Instrument Name > Frequency/Phase > Frequency" and enter the desired frequency.

You have to confirm the changes of the RF frequency in the [External Local Oscillator Settings](#) dialog for them to be applied to the signal.

#### Frequency

Sets the RF frequency at the RF output connector of the selected instrument.

Remote command:

`[ :SOURce ] :FREQuency [ :CW | FIXed ]` on page 160

### 7.2 Level and Power-On Settings

This section explains the level settings of the R&S SGU. The instrument can be equipped optionally with an active electronic step attenuator (R&S SGU-B26).

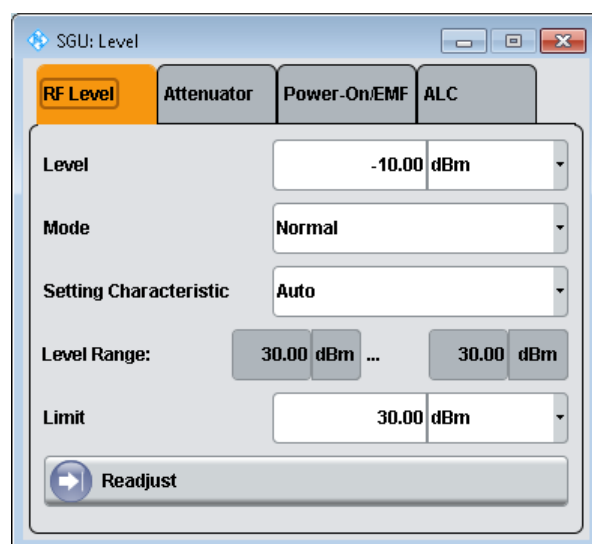
### Configuring RF Level

- ▶ To change the RF level of the selected instrument, perform one of the following:
  - a) Select "SGMA-GUI main panel > Level" and enter the desired value.
  - b) Select "SGMA-GUI > Instrument Name > Level > RF Level > Level" and enter the desired value.

You have to confirm the changes of the RF level in the [External Local Oscillator Settings](#) menu for them to be applied to the signal.

## 7.2.1 RF Level

- ▶ To access the RF level settings, select "SGMA-GUI > Instrument Name > Level > RF Level".



This dialog comprises settings like the RF level and level limit.

### Level/Level Offset

Sets the RF level at the RF output connector of the selected instrument.

If you set a level offset, it will be indicated in the R&S SGMA-GUI main panel by a change in the name of this parameter from "Level" to "Level Offset".



**Note:** The SCPI command `[ :SOURce ] :POWer [ :LEVel ] [ :IMMediate ] [ :AMPLitude ]` sets the level of the "Level" display, that means the level containing offset while `[ :SOURce ] :POWer :POWer` sets the level at the RF output connector.

Remote command:

`[ :SOURce ] :POWer [ :LEVel ] [ :IMMediate ] [ :AMPLitude ]` on page 166

`[ :SOURce ] :POWer:POWer` on page 168

### Offset

Sets a level offset.

This value represents the level shift of a downstream instrument, as for example an attenuator or an amplifier, and is indicated in the status bar of the display. It does not change the level at the RF output.

Remote command:

`[ :SOURce ] :POWer [ :LEVel ] [ :IMMediate ] :OFFSet` on page 167

### Mode

Allows you to optimize the RF output signal for applications, where improved harmonic distortion or improved wideband noise is required.

"Normal" In normal mode, the generator provides an RF output signal with high signal to noise ratio as well as low distortion, according to the data sheet.

"Low Noise" This setting forces the generator to optimize the signal to noise ratio.

"Low Distortion"

In this mode, the generator reduces distortions of the RF signal to a minimum.

Remote command:

`[ :SOURce ] :POWer:LMODE` on page 166

### Setting Characteristic

Selects the characteristic for the level setting. For some general applications, the instrument operation can be optimized by choosing one of the predefined level setting characteristics.

"Auto" The instrument provides the highest dynamic range and the fastest setting times according to the data sheet. The RF signal is shortly blanked during the moment the step attenuator is switched on.

"Uninterrupted Level setting"

Suppresses level blanking at frequency and level changes. This mode reduces the dynamic range of the instrument. The step attenuator is fixed.

"Strictly Monotone"

Provides level setting without discontinuities. All electronic switches in the RF path are clamped. The operation mode is useful for applications using level searching algorithms.

This mode further reduces the dynamic range of the instrument.

"Constant-VSWR"

Suppresses output impedance variations at the RF OUT connector due to switching of the step attenuator. The step attenuator is fixed. This mode reduces the dynamic range of the instrument.

Remote command:

`[ :SOURce ] :POWer:SCHaracteristic` on page 166

### Level Range

Displays the level range within which the level setting is expected to work properly. The range limits depend on several parameters like "Mode", "Setting Characteristic", the I/Q signal's crest factor etc.

Remote command:

`[ :SOURce ] :POWer:RANGe:LOWer?` on page 168

`[ :SOURce ] :POWer:RANGe:UPPer?` on page 168

### Limit

Sets the level limit.

The value specifies the upper limit of the level at the RF OUT connector. A message appears if an attempt is made to set a level above this limit and the level at the RF output is confined to the upper limit. However, the level indication is not influenced.

The value is not affected by an instrument preset function. This parameter is influenced only by the [Factory Preset](#) and its factory value is equal to the upper limit.

Remote command:

`[ :SOURce ] :POWer:LIMit [ :AMPLitude ]` on page 167

### Readjust

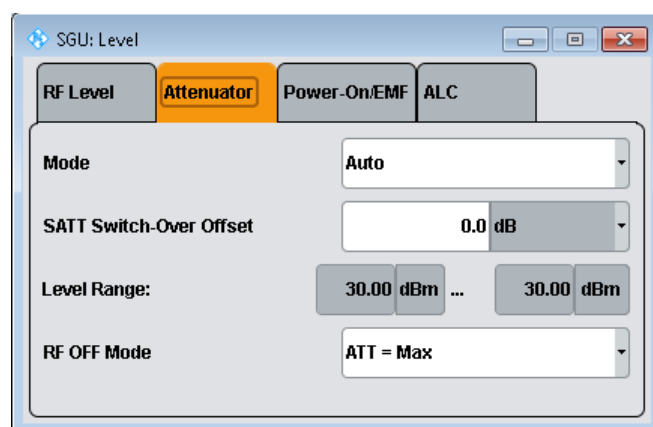
Recalculates the instrument internal settings optimized for the current level. Not required for automatic modes.

Remote command:

`[ :SOURce ] :POWer:ALC:SONCe` on page 165

## 7.2.2 Attenuator

- ▶ To access the attenuator settings, select "SGMA-GUI > Instrument Name > Level > Attenuator".



This dialog comprises the settings for the power-on behavior of the instrument.



**Mode**

Sets the attenuator mode at the RF output.

"Auto" Standard mode.  
The electronically switching attenuator switches with a ~ 6 dB step width at optimized switching points. The entire level range is available. The level setting is performed by continuous electronic level control combined with switching the step attenuator.

"Fixed" The level settings are made without switching the attenuator. When this operating mode is switched on, the attenuator is fixed in the current position to provide level settings without interruption. The resulting variation range is defined and displayed under [Level Range](#).

**Note:** The function is effective when automatic level control is activated ("ALC State = On"). If the normal variation range is overranged or underranged, level errors increase considerably and the warning "Level under/overrange" appears in the info line. The spectral purity of the output signal decreases with high attenuation.

Remote command:

[:OUTPut:AMODE](#) on page 158

**Level Range**

Displays the level range in which the level is set without interruption for the "Attenuator Mode Fixed" setting.

Remote command:

[:OUTPut:AFIXed:RANGe:LOWer?](#) on page 159

[:OUTPut:AFIXed:RANGe:UPPer?](#) on page 159

**SATT Switch-Over Offset**

Sets the switch-over offset value of the attenuator.

Remote command:

[\[:SOURce\]:POWER:ATTenuation:SOVer\[:OFFSet\]](#) on page 166

**RF-Off-Mode**

Determines the attenuator's state after the instrument is switched off.

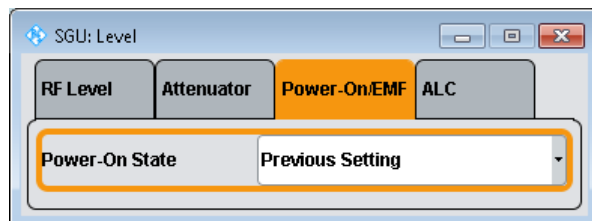
In default setting, the electronic step attenuator switches to highest attenuation when RF is off. By setting the RF-Off mode, the electronic step attenuator can be fixed to keep the output impedance constant during RF off.

Remote command:

[\[:SOURce\]:POWER:ATTenuation:RFOff:MODE](#) on page 165

### 7.2.3 Power-On/EMF

- ▶ To access the power-on/EMF settings, select "SGMA-GUI > Instrument Name > Level > Power-On/EMF".



This dialog comprises the settings for the power-on behavior of the instrument.

#### Power-On State

Selects the state which the RF output takes after the instrument is switched on.

"RF Off" The output is deactivated when the instrument is switched on.

"Previous Setting"

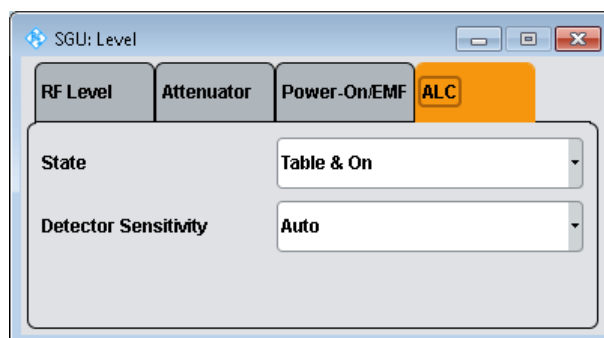
When the instrument is switched on, the output takes the same state as it had when the instrument was switched off.

Remote command:

`:OUTPut [:STATe] :PON` on page 159

### 7.2.4 ALC

- ▶ To access the automatic level control (ALC) settings, select "SGMA-GUI > Instrument Name > Level > ALC".



Automatic level control can be used with almost all applications, especially I/Q modulation. It only has to be deactivated for certain settings in the baseband and when I/Q impairments ("Impairments State On") are activated. This is indicated under the respective function.

By default, the instrument operates in "Table & On" mode to provide the highest level accuracy and fastest setting time. Level control can be switched to "Off (Table)" or "On" for particular applications. The "Off (Table)" state (level control Off) is recommended if in CW mode the signal/intermodulation ratio is to be improved for multi-transmitter measurements.

#### State

Sets the internal level control.

"Table & On"	Default mode. First sets the level to the target value using the internal level table. Then activates the level control circuit to achieve maximum level accuracy.
"On"	Internal level control is permanently activated. If "On" and "Attenuator Mode Fixed" is selected, the level is recalibrated for every level and frequency setting.
"Off (Table)"	Internal level control is performed according to the ALC table.

Remote command:

`[ :SOURce ] :POWer:ALC [ :STATe ]` on page 165

#### Detector Sensitivity

Allows you to fix the internal level detector. It is recommended to use the Auto mode (default).

"Auto"	Automatic detector selection. Recommended mode of operation.
"Low"	Low sensitivity detector selected. This setting is intended for signals with high internal electronic levels.
"Med"	Medium sensitivity detector selected. This setting corresponds to normal mode. It is intended for signals with medium internal electronic levels.
"High"	High sensitivity detector selected. Selects the detector path with high sensitivity, intended for signals with low internal electronic levels.
"Fix"	Fixes the last set sensitivity setting.

## 7.3 I/Q Modulation and Signal Impairment

The R&S SGU offers I/Q modulation with external analog I/Q signals. I/Q modulation with an external analog I/Q signal is possible for the instrument equipped with frequency options R&S SGU-B120V/-B140V. The external signal is input via the I IN and Q IN connectors and transferred to the I/Q modulator.

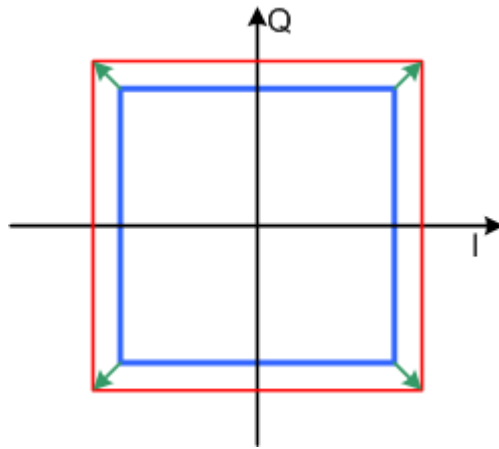
Before the signal is fed into the I/Q modulator, the signal can be impaired. Impairment at this point along the signal flow is offered to allow error correction of the supplied signal or set dedicated impairments.

### 7.3.1 I/Q Impairments

Signal impairments are well-defined arithmetic modifications of the data. Every data sample is modified in the same way. The purpose of adding impairments to the data stream is to simulate frequent sources of distortions in a real signal-processing chain in order to generate a test signal with dirty transmitter conditions.

#### 7.3.1.1 Gain and Gain Imbalance

An I/Q gain is a multiplication of all I/Q amplitudes by a common factor. The effect is equivalent to two identical I and Q gain factors. The effect of an increased gain factor in the I/Q constellation diagram is shown below.



*Figure 7-1: Effect of an increased amplitude in the I/Q constellation diagram*

An I gain multiplies the I amplitudes by a factor, leaving the Q amplitudes unchanged. A Q gain has the opposite effect. Different I and Q gain factors result in an I/Q imbalance, which is usually due to different gains of the amplifiers in the I and Q channels of the I/Q modulator. The effect of a positive and negative gain imbalance is shown below.

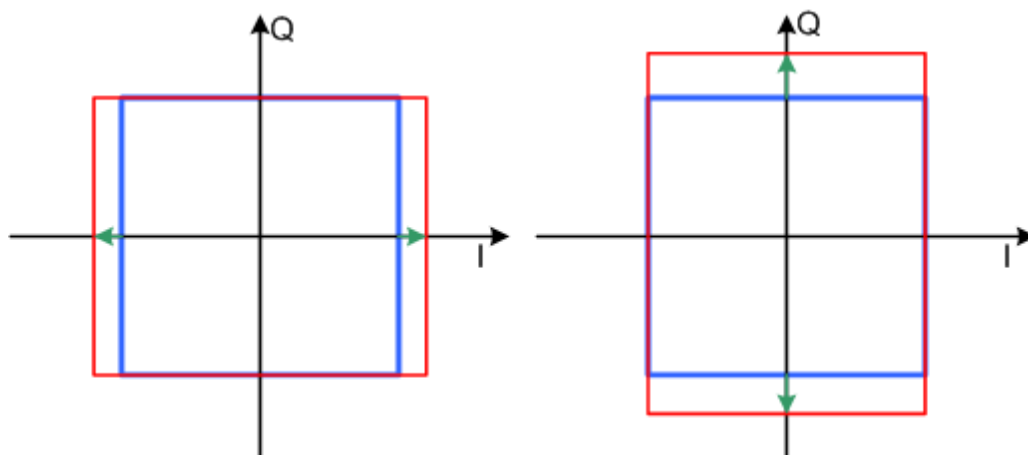


Figure 7-2: Negative gain imbalance (left) and positive (right) gain imbalance in the I/Q constellation diagram

### 7.3.1.2 I and Q Offset

An I offset adds a constant value to all I amplitudes, leaving the Q amplitudes unchanged. A Q offset has the opposite effect. A combination of I and Q values results in an I/Q offset, which is usually due to carrier feedthrough in the I/Q modulator. Possible reasons are interfering signals at the RF carrier frequency, e.g. an unsuppressed RF carrier subchannel. The effect of a positive I and Q offset in the I/Q constellation diagram is shown below.

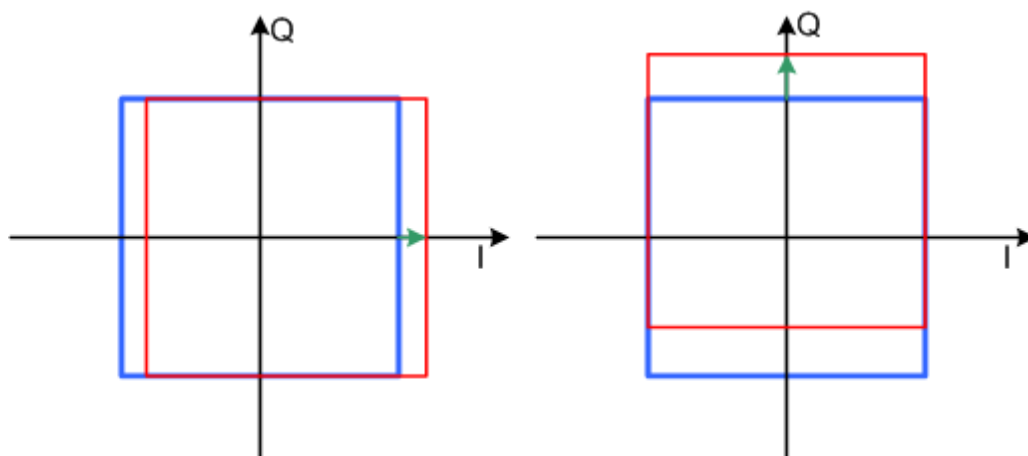


Figure 7-3: I offset (left) and Q offset (right) in the I/Q constellation diagram

### 7.3.1.3 Quadrature Offset

Changes the phase angle between the I and Q vectors from the ideal 90 degrees, while the amplitudes are maintained. A positive quadrature offset results in a phase angle greater than 90 degrees. The effect of a positive quadrature offset in the I/Q constellation diagram is shown below.

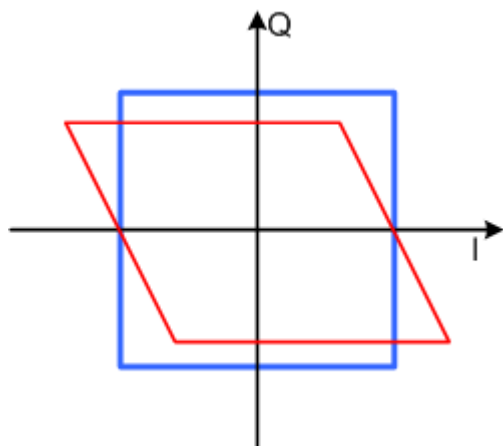
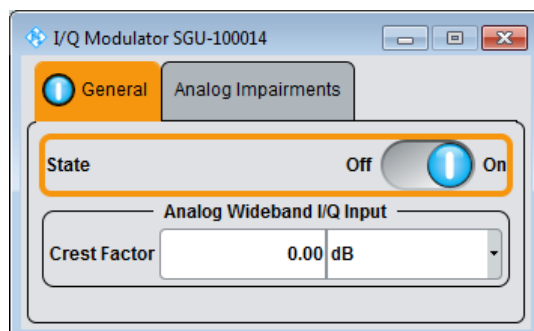


Figure 7-4: Positive quadrature offset in the I/Q constellation diagram

### 7.3.2 General I/Q Settings

- To access the settings of the I/Q modulator, select "SGMA-GUI > Instrument Name > I/Q Settings > General".



Comprises the settings for setting the state and the analog wideband I/Q input.



#### Mod State

Switches the I/Q modulation on and off.

Remote command:

`[ :SOURce ] :IQ:STATe` on page 161

#### Crest Factor

Sets the crest factor of the I/Q modulation signal.

The crest factor gives the difference in level between the peak envelope power (PEP) and average power value (RMS) in dB. This value is necessary for the generation of the correct output power at the RF output, i.e. the instrument uses the PEP value to compensate the average power.

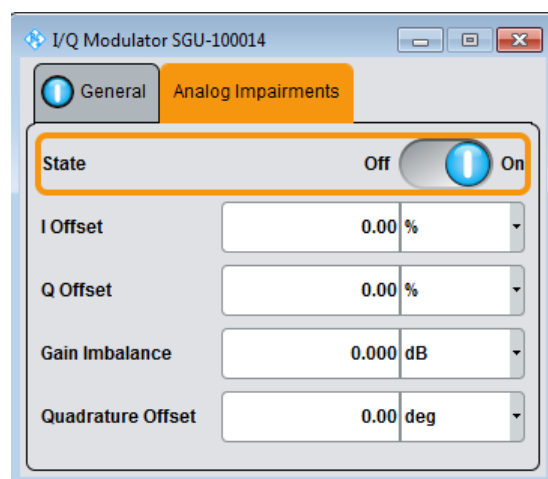
The maximum input voltage at the I/Q input is equated to the peak power and is used as the "reference" for setting the level of the output signal. Since the signal does not usually supply the peak power at a constant level and instead supplies lower average power, the crest factor specifies how many dB have to be added internally so that the correct output power is achieved.

Remote command:

`[ :SOURce ] :IQ:CREStfactor` on page 163

### 7.3.3 Analog Impairment Settings

- ▶ To access the settings of the I/Q modulator, select "SGMA-GUI > Instrument Name > I/Q Settings > Analog Impairments".



Comprises the settings like I/Q offset and quadrature offset.

#### State

Activates/deactivates I/Q impairments.

If activated, the settings for offset, gain imbalance and quadrature offset become effective.

**Note:** It is advisable to switch automatic level control to the "Off (Table)" mode, as otherwise level errors may occur.

Remote command:

`[ :SOURce ] :IQ:IMPAirment:STATe` on page 162

#### Offset

Sets the carrier offset (in percent) of the amplitudes (scaled to the peak envelope power (PEP) for the I and/or Q signal component. An ideal I/Q modulator suppresses the carrier offset completely (offset = 0 percent).

For more information, see [Chapter 7.3.1.2, "I and Q Offset"](#), on page 78.

Remote command:

`[ :SOURce ] :IQ :IMPairment :LEAKage :I` on page 162

`[ :SOURce ] :IQ :IMPairment :LEAKage :Q` on page 162

### Gain Imbalance

Sets the imbalance of the I and Q vector (see [Chapter 7.3.1.1, "Gain and Gain Imbalance"](#), on page 77).

The entry is made in dB (default) or %, where 1 dB offset is roughly 12 % according to the following:

$$\text{Imbalance [dB]} = 20 \log ( | \text{GainQ} | / | \text{GainI} | )$$

Positive values mean that the Q vector is amplified more than the I vector by the corresponding percentage. Negative values have the opposite effect.

Remote command:

`[ :SOURce ] :IQ :IMPairment :IQRatio` on page 161

### Quadrature Offset

Sets the quadrature offset (see [Chapter 7.3.1.3, "Quadrature Offset"](#), on page 78).

Remote command:

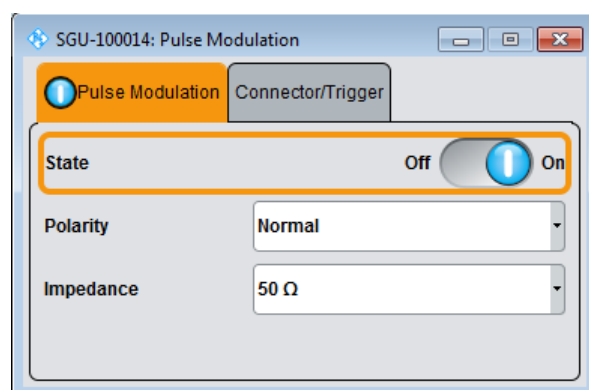
`[ :SOURce ] :IQ :IMPairment :QUADrature [ :ANGLE ]` on page 162

## 7.4 Pulse Modulation Setting

The R&S SGU offers pulse modulation using external pulse signals. The external pulse signal has to be connected to the multi purpose TRIG connector.

### 7.4.1 Pulse Modulation Settings

- ▶ To access the pulse modulation settings, select "SGMA-GUI > Instrument Name > Pulse Modulation".



The "Pulse Modulation" dialog contains all parameters required to configure pulse modulation and pulse signal generation.



**State**

Sets the state of the pulse modulator.

Remote command:

[\[:SOURce<hw>\]:PULM:STATe](#) on page 169

**Polarity**

Sets the polarity of the pulse modulator signal.

"Normal"           The RF signal is suppressed during the pulse pause.

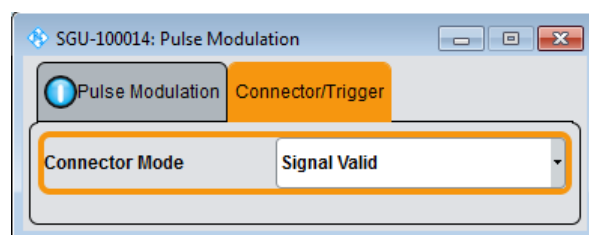
"Inverse"           The RF signal is suppressed during the pulse.

Remote command:

[\[:SOURce<hw>\]:PULM:POLarity](#) on page 169

**7.4.2 Pulse Connector/Trigger Settings**

- ▶ To access the pulse connector/trigger settings, select "SGMA-GUI > Instrument Name > Pulse Modulation > Connector/Trigger".



Comprises the settings necessary to configure the signal at the multi purpose TRIG connector in the external trigger mode.

**Trigger Connector Mode**

Determines the signal at the input/output of the multi purpose TRIG connector.

"Signal Valid"    Output of high signal to mark valid frequency and level settings.

"Not Signal Valid"    Output of high signal to mark the transition state when frequency and level change.

"Pulse Mod Ext Source"    Input for an externally provided pulse modulation signal  
Used when an external pulse modulator source is provided at the connector.

Remote command:

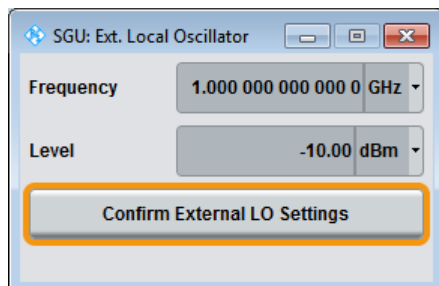
[:CONNector:TRIGger:OMODE](#) on page 146

**7.5 External Local Oscillator Settings**

In a setup where an R&S SGU is connected to an incompatible signal generator (local oscillator), the controller has to change the frequency and the level of this local oscilla-

tor (LO) in order to output the desired signal from the R&S SGU. The required settings of the local oscillator are shown in the "Local Oscillator" dialog.

- ▶ To access this dialog select "SGMA-GUI > Instrument Name >Ext. Local Oscillator".



When changing any parameters which affect the output signal of the combined system of an incompatible LO and an R&S SGU, follow these steps:

### Setting the signal of the R&S SGU

1. Set the parameters of the R&S SGU like frequency and level in the R&S SGMA-GUI as needed.
2. Open the "SGMA-GUI > Instrument Name >Ext. Local Oscillator" dialog and read the settings for "Frequency" and "Level".
3. Apply the required changes to the LO.
4. Press the "Confirm External LO Settings" button to confirm that you have made the settings on the LO.

The desired signal is output by the R&S SGU.

### Frequency

Shows the desired frequency for the LO input signal.

Remote command:

`[ :SOURce ] :LOSCillator :FREQuency?` on page 164

### Level

Shows the desired level for the LO input signal.

Remote command:

`[ :SOURce ] :LOSCillator :POWer?` on page 164

### Confirm External LO Settings

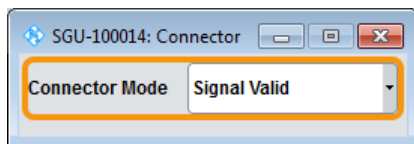
Outputs the signal.

Remote command:

`[ :SOURce ] :SETTings :APPLY [ :IMMediate ]` on page 160

## 7.6 Trigger Connector Settings

- ▶ To access this dialog select "SGMA-GUI > Instrument Name > Connector".



This dialog comprises the settings for configuring the connector.

### Trigger Connector Mode

Determines the signal at the input/output of the multi purpose TRIG connector.

"Signal Valid"	Output of high signal to mark valid frequency and level settings.
"Not Signal Valid"	Output of high signal to mark the transition state when frequency and level change.
"Pulse Mod Ext Source"	Input for an externally provided pulse modulation signal Used when an external pulse modulator source is provided at the connector.

Remote command:

`:CONNector:TRIGger:OMODE` on page 146

## 7.7 Preset

Calls up a defined instrument setup. All parameters and switching states are preset (also those of inactive operating modes). The default instrument settings provide a reproducible initial basis for all other settings. However, functions that concern the integration of the instrument into a measurement setup are not changed.

### Overview of the most important preset states

The following list gives an overview of the presets for the most important generator settings. The other presets can be found in the information accompanying the remote commands.

- "RF frequency" = 1 GHz
- "RF output" switched off
- "Modulator State" = Off

Settings that are **not affected** by the "SGMA-GUI > Instrument Name > Preset" function:

- Power on settings ("Level" dialog)
- Network settings ("Setup" dialog)
- Password and settings protected by passwords ("Setup" dialog)



To preset the R&S SGMA-GUI itself and all configured instruments to their predefined state, use the "SGMA-GUI > File > New" function.

---

SCPI command:

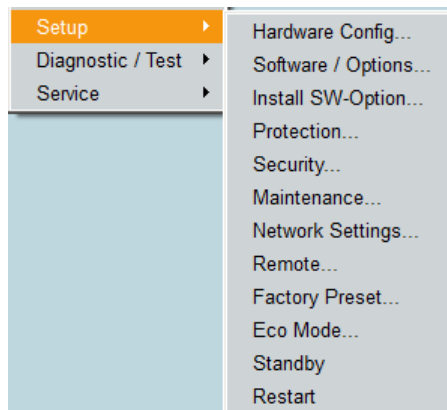
:[SYSTem:PRESet](#) on page 141

## 8 General Instrument Settings and Instrument Setup

This section describes the settings which do not directly affect signal generation.

Access:

- ▶ Select "SGMA-GUI > Instrument Name > Setup" and select the required dialog.



### 8.1 Hardware Configuration

#### Querying information about the installed assemblies

- ▶ Select "SGMA-GUI > Instrument Name > Setup > Hardware Config".

In the "Hardware Config" dialog, the installed assemblies together with their variants and revision states can be displayed for servicing purposes.

SGU-100014: Hardware Config

Counter

Common Assembly

Assembly	Part Number	Serial Number	Revision
SGU	1418.2005k02	100014	
Controller	1416.1201.02	101184	04.01
PCI FPGA			01.17.01

RF Assembly

Assembly	Part Number	Serial Number	Revision
IqUpcon FPGA			01.02.17
IqUpcon20	1418.2705.02	101376	06.02
IqUpcon40	1315.2003.02	101072	03.05
IqUpcon40 BRD	1418.3201.02	101072	06.05
IqUpcon40 uW	1315.2026.02	100032	05.00

The dialog is a table that lists the installed assemblies. It is divided into the sections:

- "Common Assembly"
- "RF Assembly"

### Assembly

The tables list the installed assemblies.

"Assembly" Name of the assembly

"Part Number" Part Number of the assembly

"Serial Number"

Serial number of the assembly

"Revision" Revision state of assembly

Remote command:

:SYSTem:HARDware:ASSEMBly<dir>:SNUMber? on page 181

## 8.2 Software / Options

### Querying information about the installed options and software version

- ▶ Select "SGMA-GUI > Instrument Name > Setup > Software/Options".

The "Software/Options" dialog shows the firmware version of the instrument software and all installed hardware and software options.

Software	
Package	Version
SGU100A Base Software	3.20.140.32 beta (2015-01-20; 06:50:06)
R&S COMPASS	3.1.19.5

Hardware			
Option	Designation	Licenses	Expiration Date
SGU-B120V	1 MHz to 20 GHz IQ		
SGU-B140V	1 MHz to 40 GHz IQ		

Software			
Option	Designation	Licenses	Expiration Date

WinIQSIM			
Option	Designation	Licenses	Expiration Date

Loaded Modules			
Path	Module	Version	Description
/ro/opt/bin	mainstartup		
/ro/opt/bin	libbusyledwrapperdll.so		
/ro/opt/bin	libcaldatahandler.so		
/ro/opt/bin	libchartdisplaycomfort.so	03.20.140.3	

The dialog is divided into the following sections:

- "Firmware"
- "Hardware"
- "Software"
- "Loaded Modules"



Software options purchased at a later stage can be activated with a keycode. The activation code is supplied with the software option. An instruction on how to install options is described in the service manual. Most hardware options need to be installed at an authorized Rohde & Schwarz service center.

### Software

Shows the software/firmware version and the version of the software platform.

**Note:** Your instrument is delivered with the latest firmware version available. Firmware updates and the Release Notes describing the improvements and modifications are provided on the Internet at the download site of the instrument's home page. This home page always offers the latest information on your instrument, e.g. also on changes of the firmware update procedure.

### Hardware / Software/WinIQSIM

The tables in the sections "Hardware" and "Software" list the installed hardware and software options.

"Option" Short name of the option

"Designation" Name of the option

"Licenses" Number of licenses

"Expiration Date"

For regular options, "Permanent" is indicated in this column. Some options are available as trial versions. This column shows their expiration date. After this date, the option is no longer available on the instrument.

### Loaded Modules

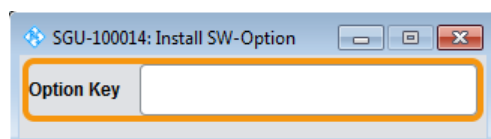
Section "Loaded Modules" is provided for service purposes. It lists all loaded software modules with their versions and offers a short description of each module.

### Show Open Source Acknowledgments

Accesses the list of the used open source software packages and the corresponding verbatim license texts.

## 8.3 Install SW-Options

Newly purchased software options are enabled in the "Install SW-Option" dialog. They are ready to operate after they are enabled by a key code supplied with the option.



Only if the instrument is equipped with an older firmware version, a firmware update before enabling the software option may be required. The information on the valid firmware versions for the purchased software option is provided together with the option.



See:

- [Chapter 9.5, "How to Install a New Firmware Version on the Instrument"](#), on page 107 for information on how to perform firmware update
- [Chapter 9.6, "How to Activate Options"](#), on page 108 for instruction on how to install new options

The firmware update is also described in the service manual.

## 8.4 Protection

The "Protection" dialog provides access to the unlocking of protected service functions (authorized personnel of R&S Service Departments only).

### Unlocking of protected service functions

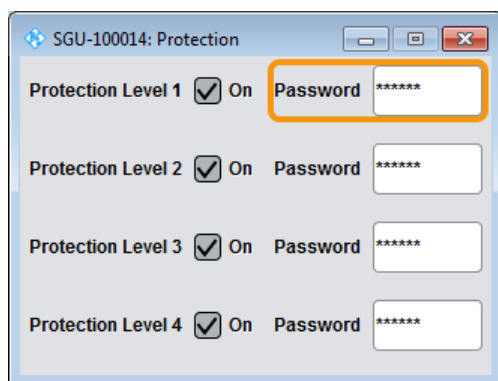
1. Select "SGMA-GUI main panel > Instrument Name > Setup > Protection".

The "Protection" dialog provides access to the unlocking of protected service functions (authorized personnel of R&S Service Departments only).

2. To deactivate the protection, the correct password has to be entered. After the instrument has been switched on, the protection levels 1 to 4 are automatically activated.

Enter "Protection Level 1 > Password > 123456".

Protection Level 1 is activated.



### Protection Level / Password

"Protection Level 1" can be activated to expand the functionality of the internal adjustment. The password is 123456.

The other protection levels 2 to 4 provide access to protected service functions. Only the authorized personnel of R&S Service Departments can access these functions.

## 8.5 Security Setting

The R&S SGU employs a security concept based on user and security password. The security password is required for changing several critical settings, like performing firm-ware updates. Access to the passwords and mass storage security settings is provided in the "Security" dialog.

- ▶ To access the "Security" dialog, select "SGMA-GUI > Instrument Name > Setup > Security"

The menu is divided into the password sections and the security settings section. In the password section, the passwords for securing a controlled access to the instrument are defined and changed.

A change of passwords for the operating system and security password requires the entry of the old and new password and the conformation of the new password. All settings are only accepted after the "Change Password" button is pressed.

SGU-100014: Security

Change User Password  
valid for VNC,FTP and SAMBA access

User Name

Old Password

New Password

Confirm Password

Change Password

Change Security Password

Old Password

New Password

Confirm Password

Change Password

Security Settings

USB Device

Lan Connections

Security Password

Accept



The settings of this dialog are not accessible over remote control (e.g. SCPI commands).

### **Change User Password**

The user name and password are required for remote access to the instrument via VNC, FTP or SAMBA.

**Note:** It is highly recommended to change the default user password before connecting the instrument to the network.

#### **User Name ← Change User Password**

Indicates the user name used for access to the Linux operating system and valid for VNC, FTP and SAMBA access.

#### **Old Password ← Change User Password**

Enter the currently used user password. The default password is "instrument".

#### **New Password ← Change User Password**

Enter the new user password.

#### **Confirm Password ← Change User Password**

Enter the new password for conformation.

The new password is only valid after the "Change Password" button is pressed.

#### **Change Password ← Change User Password**

Changes the password accordingly.

### **Change Security Password**

**Note:** It is highly recommended to change the default security password before connecting the instrument to the network.

The security password is for example required when changing the status of the USB and LAN interface.

#### **Old Password ← Change Security Password**

Enter the currently used security password. The default password is '123456'.

#### **New Password ← Change Security Password**

Enter the new security password. The security password may contain decimal characters only.

#### **Confirm Password ← Change Security Password**

Enter the new password for conformation.

The new password is only valid after the "Change Password" button is pressed.

#### **Change Password ← Change Security Password**

Changes the password accordingly.

**Security Settings**

Comprises the settings for enabling and disabling the USB and LAN interfaces. The setting requires the entry of the security password and is only accepted after the "Accept" button is pressed.

**USB Device ← Security Settings**

Enable/disable the USB interface.

**Note:** The instrument does not recognize any device connected to the USB interface when the interface is disabled.

**LAN Connection ← Security Settings**

Enable/disable the LAN interface.

**Note:** It is not possible to access the instrument via LAN while the LAN connection is disabled.

An enabled LAN connection is a prerequisite for the remote control of the instrument via VNC, FTP or SAMBA.

**Security Password ← Security Settings**

Enters the password that is required to enable or to disable the settings protected by a security password. The default is '123456'.

**Note:** It is highly recommended to change the default security password before connecting the instrument to the network. To change the security password, select "SGMA-GUI > Instrument Name > Setup > Security > Change Security Password".

The settings are only accepted after the "Accept" button is pressed.

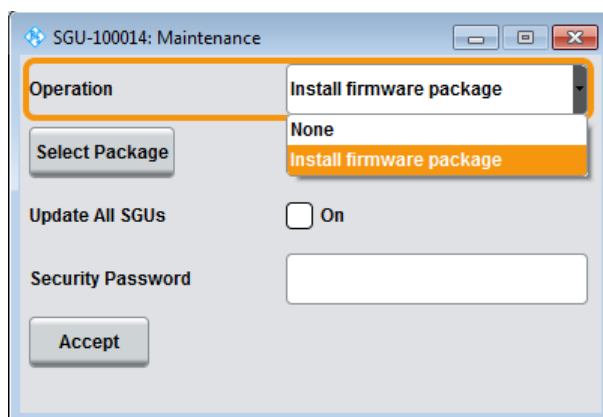
**Accept ← Security Settings**

Accept a new entry or selection and change the settings accordingly.

## 8.6 Maintenance

The R&S SGU provides a special dialog for performing some maintenance procedures, like installing firmware packages.

- ▶ To access this dialog, select "SGMA-GUI > Instrument Name > Setup > Maintenance".



### Operation

Selects the desired maintenance operation.

### Select Package

Available only for "Operation > Install Firmware Package".

Selects the firmware package to be installed, see also [Chapter 9.5, "How to Install a New Firmware Version on the Instrument"](#), on page 107.

### Update All

Available only for "Operation > Install Firmware Package".

Enable this function to perform a simultaneous firmware update on all instruments, that are in active state and are connected to this controller.

**Note:** A firmware update and the required subsequent restart and the automatically initiated internal adjustment process of the controller may be a time consuming operation. This feature accelerates the update process and the required restart of the external PC can be executed once after the update operation of all instruments is completed.

### Security Password

Enters the password that is required to enable or to disable the settings protected by a security password. The default is '123456'.

**Note:** It is highly recommended to change the default security password before connecting the instrument to the network. To change the security password, select "SGMA-GUI > Instrument Name > Setup > Security > Change Security Password". The settings are only accepted after the "Accept" button is pressed.

### Accept

Accept the selected operation and perform the required procedure.

## 8.7 Network Settings

The instrument is equipped with a network interface and can be connected to an Ethernet LAN (local area network). The "Network Settings" dialog provides access to the network settings.

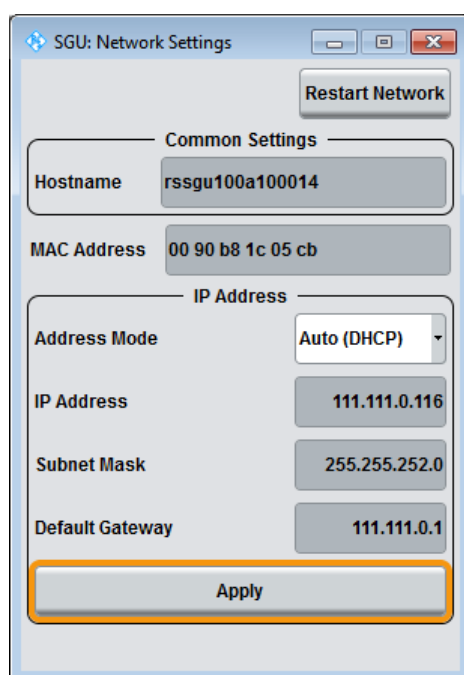
**NOTICE****Risk of network errors!**

Connection errors can affect the entire network.

If your network does not support DHCP, or if you choose to disable dynamic TCP/IP configuration, you must assign valid address information before connecting the instrument to the LAN.

Contact your network administrator to obtain a valid IP address.

- ▶ To access this dialog, select "SGMA-GUI > Instrument Name > Setup > Network Settings".



The dialog provides access to the network settings, like settings about the general network environment and specific identification of the computer in the network. The dialog also displays an indication whether the instrument is connected to the network or not.

**Restart Network**

Shuts down the network connection of the instrument and then re-establishes the connection.

This function can be used to resolve network problems.

**Note:** Only the connection of the instrument to the network restarts, the network itself is not affected.

**Hostname**

Displays the individual computer name of the instrument.

A predefined name is indicated and can be used for network connections, see [Chapter 6.4.3, "Finding Out the Default Hostname of the Instrument"](#), on page 61.

It is recommended that a connection of the instrument to the network is coordinated with the network administrator. Connection errors may affect the entire network.

Remote command:

`:SYSTem:COMMunicate:NETWork[:COMMON]:HOSTname` on page 178

### MAC Address

Indicates the MAC address of the network adapter.

### Address Mode

Selects if the IP address is assigned automatically or manually.

It is recommended that a connection of the instrument to the network is coordinated with the network administrator. Connection errors may affect the entire network.

**Note:** Lost LAN connection to an instrument.

If the connection to an instrument configured to use static IP addresses is lost, press the LAN LED on the instrument front panel for 3 seconds.

This resets the "Address Mode" to its default value ("Auto (DHCP)").

"Auto (DHCP)" The IP address is assigned automatically.

The network used must support automatic assignment of IP address via DHCP or APIPA (Zeroconf) to use this function.

"Static" The IP address is assigned manually.

Remote command:

`:SYSTem:COMMunicate:NETWork:IPAddress:MODE` on page 177

### IP Address

Displays the IP address. To enter the IP address manually, select "Address Mode > Static".

In case of manual input of the IP address, it is recommended that a connection of the instrument to the network is coordinated with the network administrator. Connection errors may affect the entire network.

Remote command:

`:SYSTem:COMMunicate:NETWork:IPAddress` on page 177

### Subnet Mask

Displays the subnet mask. To enter the subnet mask manually, select "Address Mode > Static".

This number is used together with the IP address to identify the network segment the instrument is in.

It is recommended that a connection of the instrument to the network is coordinated with the network administrator. Connection errors may affect the entire network.

Remote command:

`:SYSTem:COMMunicate:NETWork[:IPAddress]:SUBNet:MASK` on page 178

### Default Gateway

Displays the IP address of the default gateway. To enter the default gateway manually, select "Address Mode > Static".

This address identifies the router on the same network as the instrument that is used to forward traffic to destinations beyond the local network.

It is recommended that a connection of the instrument to the network is coordinated with the network administrator. Connection errors may affect the entire network.

Remote command:

`:SYSTem:COMMunicate:NETWork[:IPAddress]:GATeway` on page 178

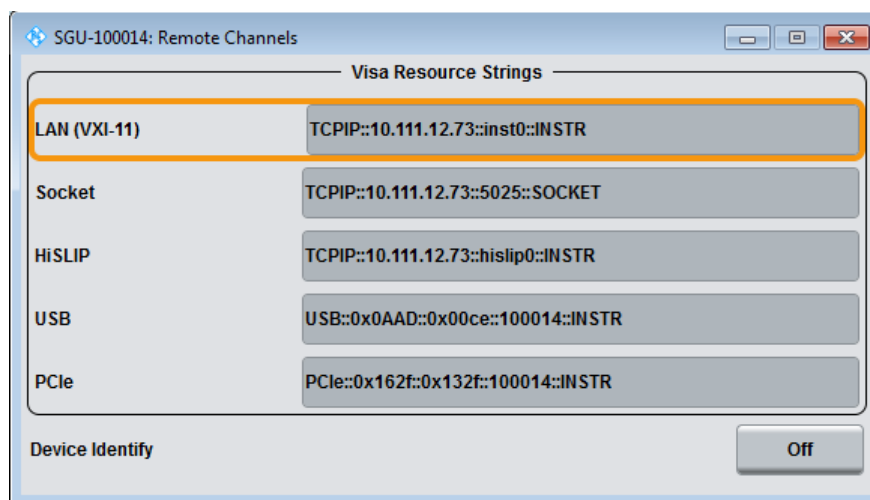
### Apply

Applies the network settings to the instrument.

## 8.8 Remote Channels

The "Remote" dialog provides access to the settings for remote control.

- To access this dialog, select "SGMA-GUI > Instrument Name > Setup > Remote".



### Visa Resource Strings

Indicates the VISA resource strings used for remote control of the instrument. A separate string is provided for remote control via the different interfaces.

**Note:** For background information and description of the syntax of the VISA resource strings, refer to the description of the corresponding interface in [Chapter 10.1, "Remote Control Interfaces and Protocols"](#), on page 110.

Remote command:

`:SYSTem:COMMunicate:HISLip:RESource?` on page 179

`:SYSTem:COMMunicate:NETWork:RESource?` on page 178

`:SYSTem:COMMunicate:SOCKet:RESource?` on page 179

`:SYSTem:COMMunicate:USB:RESource?` on page 179

`:SYSTem:COMMunicate:PCIexpress:RESource?` on page 179



### Device Identity

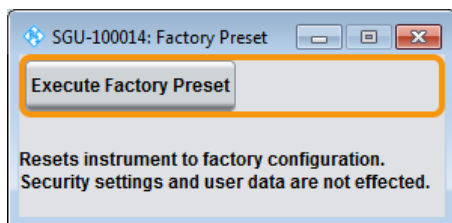
Triggers the device identification function. The LAN LED on the front panel of the selected instrument blinks.

See also [Chapter 6.4.4, "Bidirectional Instrument Identification"](#), on page 61.

## 8.9 Factory Preset

The "Factory Preset" dialog provides a function to reset the instrument's settings to their factory states

1. To access this dialog, select "SGMA-GUI > Instrument Name > Setup > Factory Preset".



2. Select "Execute Factory Preset".

The instrument's settings are reset to their factory states. Security settings and user data are not effected.

### Execute Factory Preset

Reset the instrument's settings to their factory state.

**Note:** Because "Factory Preset" resets the "Remote Channel Settings" and "Network Settings" to the default values, executing factory preset via remote control may terminate the connection to the instrument, if these settings had been configured to values different to the default ones!

The factory preset function resets nearly all instrument settings. In addition to the regular preset, a "Factory Preset" resets also the following values:

- Power on settings ("Level" dialog)
- Network settings including hostname ("Setup > Network Setting" dialog)
- Remote Channel settings ("Setup > Remote Channel" dialog)
- Eco Mode state ("Setup > Eco Mode" dialog)

To maintain security, password settings and all settings protected by these passwords like disabled USB and LAN connections are not changed.

Not affected by the "Factory Preset" are also user data, lists or instrument settings files, created for example with the "File Save As" function.

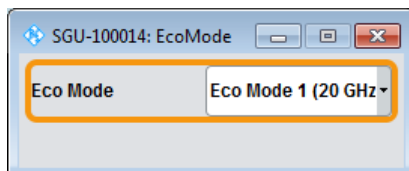
Remote command:

:SYSTem:FPReset on page 141

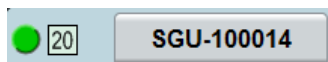
## 8.10 Eco Mode

This energy saving mode is available only for instruments equipped with option R&S SGU-B140/B140V.

- ▶ To access this dialog, select "SGMA-GUI > Instrument Name > Setup > Eco Mode".



With enabled "Eco Mode 1" the doubler stage in a 40 GHz instrument is permanently switched off to reduce power consumption and the maximum frequency is limited to 20 GHz. An enabled "Eco Mode" is indicated by a green coloring of the frequency range in the R&S SGMA-GUI.



---

### NOTICE

#### Risk of invalid adjustment after changing the Eco Mode

The switching off and on of the doubler stage changes the thermal conditions in the instrument.

In order to achieve correct adjustment of the instrument, make sure that the instrument is warm before performing adjustments. The warm-up time is 30 minutes.

---

The state of this parameter is not affected by an instrument "Preset". This parameter is influenced only by the [Factory Preset](#).

SCPI command:

## 8.11 Standby and Restart

See [Chapter 9.3, "How to Switch Between the Operating States"](#), on page 104.

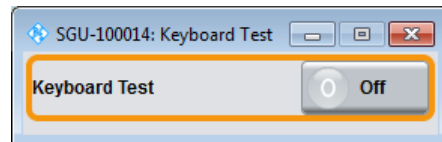
## 8.12 Diagnostic and Tests

This section describes the settings provided for diagnostic and test purposes.

### 8.12.1 Keyboard Tests

Access:

- ▶ Select "SGMA-GUI > Instrument Name > Diagnostic Tests > Keyboard Test".



Use this function to check the proper operation of all front panel elements.

If "Keyboard Test" is enabled, all front panel LEDs except the POWER ON are orange.

The exact test procedure is described in the service manual.

SCPI command:

`:TEST:KEYBoard[:STATe]` on page 183

## 9 Performing Configuration Tasks

This section provides a general explanation on how to operate the instrument manually via the R&S SGMA-GUI software.

We assume, that the R&S SGU is connected to a remote PC. The R&S SGMA-GUI software has to be installed on this remote PC and the instrument has to be added to the list of "Available Instruments".



For information on how to fulfill these requirements, refer to:

- [Chapter 2.3.2.1, "Connecting the Instrument to the Network"](#), on page 22
  - [Chapter 2.3.1, "Installing the R&S SGMA-GUI Software on an External PC"](#), on page 21
  - [Chapter 2.3.2.3, "Automatically Adding Instruments to the SGMA-GUI "](#), on page 23
- 

### 9.1 How to Generate I/Q Signals with an R&S SGS and an R&S SGU Upconverter



Options R&S SGS-B112V and R&S SGU-B120V/-B140V are required for the I/Q modulation.

---

#### To generate an I/Q modulated signal with higher frequency

In this example, the R&S SGU acts as an extension to the R&S SGS extending its frequency range to 40 GHz.

The [Figure 9-1](#) shows an example of the test setup.

## How to Generate I/Q Signals with an R&amp;S SGS and an R&amp;S SGU Upconverter

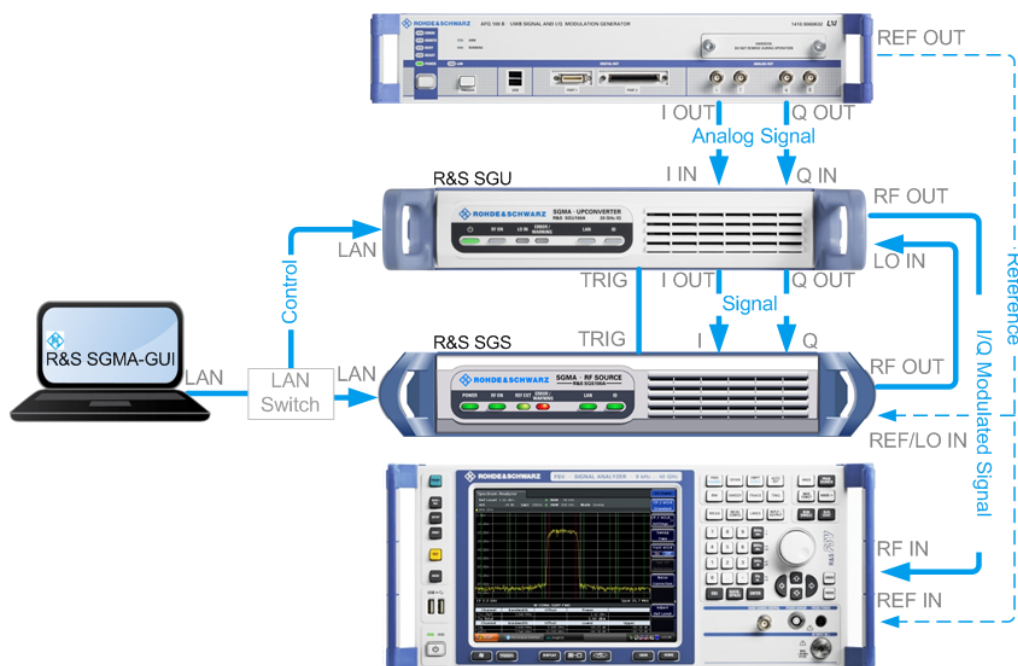


Figure 9-1: Example of the test setup



For higher setting/ measuring speeds, use a PCIe switch and PCIe connections.

If a common reference frequency is required, use the internal reference signal of the signal generator and provide it to the R&S SGU and the connected signal analyzer, e.g. the R&S FSW.

1. Connect the test equipment as shown on [Figure 9-1](#):
  - a) Connect the R&S SGS, the R&S SGU and the controller to a LAN switch.
  - b) Connect the I/Q OUT of the base band signal source to the I/Q IN of the R&S SGU.
  - c) Connect the I/Q OUT of the R&S SGS to the I and Q connectors of the R&S SGU.
  - d) Connect the RF OUT of the R&S SGS to the LO IN of the R&S SGU.
  - e) Connect the TRIG connectors of the R&S SGS and the R&S SGU.
  - f) Connect the RF OUT of the R&S SGU to the RF IN of the signal analyzer.
2. Select "SGMA-GUI main panel > R&S SGS > Extension".
 

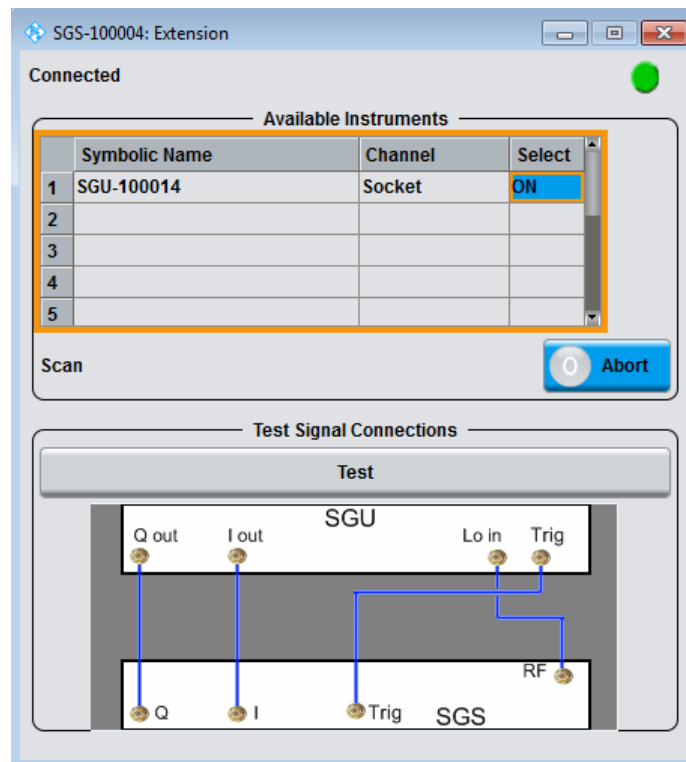
**Tip:** Steps 3 to 5 can be omitted if the R&S SGS and a single R&S SGU are connected using PCIe or USB or by a direct LAN connection because the SGS will automatically activate the SGU.
3. Press the ID key on the front panel of the R&S SGU (only required if the components are connected via a company network).
4. In the "Extension" dialog, trigger "Scan".

The scan function finds out the connected R&S SGU.

5. Select the R&S SGU from the list and set "Available Instruments > Select > On" to enable it as an extension.

A green status indicator "Connected" indicates the successfully established remote connection to the extension.

6. Select "Test Signal Connections > Test" to trigger a check of all required signal connections.



The diagram displays the connection state of the tested connections.

7. Select "SGMA-GUI > R&S SGS > Freq = 20 GHz", "Lev = -30 dBm" and enable "RF > State > On".

The extension adopts these values and states automatically. Generated is an I/Q signal with RF = 20 GHz and Level = -30 dBm.

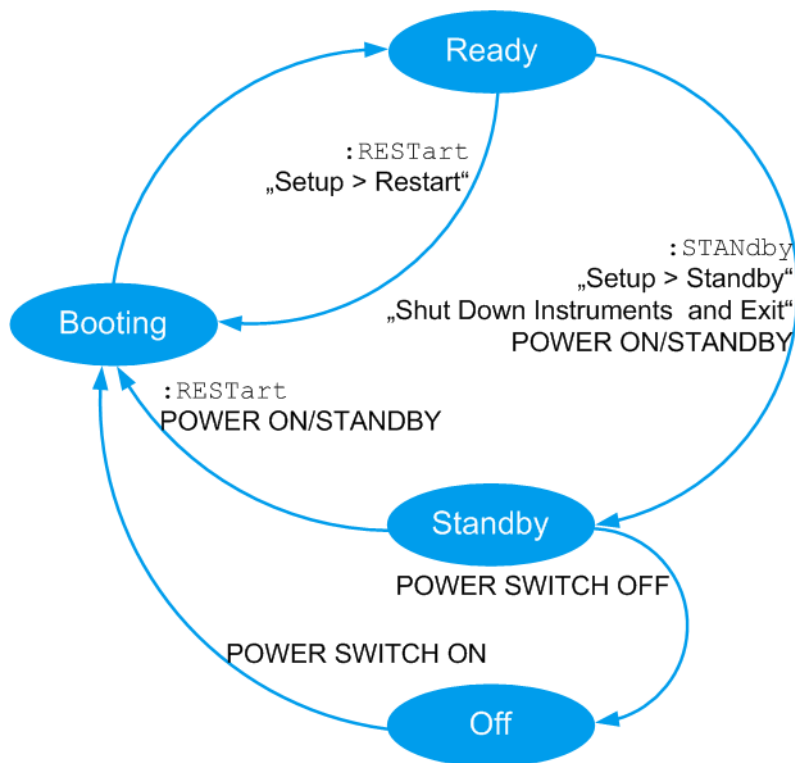
## 9.2 How to Restore the LAN Connection to an Instrument

- ▶ If the LAN connection to an instrument configured to use a static IP address is lost, press the LAN LED on the instrument's front panel for more than 3 seconds to reset the LAN settings and to set the "Address Mode" on page 96 to DHCP.

Provided the network supports automatic assignment of IP address, new IP address is automatically assigned to the instrument.

### 9.3 How to Switch Between the Operating States

The [Figure 9-2](#) gives an overview of the operating states of the instruments and how to trigger the switch-over between them.



**Figure 9-2: Operating states**

<code>:REStart</code> , <code>:STANdbY</code>	= SCPI commands
"Setup > Standby", "Setup > Restart", "Shut Down Instruments and Exit"	= R&S SGMA-GUI controls
POWER ON/STANDBY, POWER SWITCH ON/OFF	= Hardkey controls on the front/rear panel of the instrument

The [Table 9-1](#) provides a short description of the operating states and their indication.

**Table 9-1: Indication of the operating states**

Operating state	Description	Indication
Off	The instrument is shut down.	All LEDs on the front panel of the instrument are off.
Booting	The instrument boots the operating system and starts the instrument firmware. If the previous session was terminated regularly, the instrument uses the last setup with the relevant instrument settings.	The green POWER ON /STAND BY key blinks.
Standby	The standby power mode keeps the power switch circuits and the remote control system active. In this state, it is safe to switch off the AC power and disconnect the instrument from the power supply.	In the R&S SGMA-GUI, the status indicator in front of the instrument name is red. The orange POWER ON /STAND BY key is on.
Ready (normal operation)	The instrument is ready for operation. All modules are power-supplied.	In the R&S SGMA-GUI, the status indicator in front of the instrument name is green. The green POWER ON /STAND BY key is on.

**To switch the instrument to standby state**

- Use one of the following:
  - a) On the remote PC, select "SGMA-GUI > Instrument Name > Setup > Standby".
  - b) Press the POWER ON/STANDBY key on the front panel of the instrument.
  - c) Send the SCPI command:  
`:STANdby.`

The current instruments settings are automatically stored. The instrument switches to a power saving mode.

In the R&S SGMA-GUI, the standby state is indicated by the red state symbol in front of the corresponding instrument's name, on the front panel, by the orange POWER ON/STANDBY button.

The instrument can still be remote controlled.

**To return the instrument from standby to ready state**

- Use one of the following:
  - a) On the remote PC, select "SGMA-GUI > Instrument Name > Setup > Restart".
  - b) Press the orange POWER ON/STANDBY key on the front panel of the instrument.
  - c) Send the SCPI command:  
`:REStArt.`

The instrument loads the last setup with all instrument settings, switches to ready state and is ready for normal operation.

In the R&S SGMA-GUI, the ready state is indicated by the green state symbol in front of the instrument's name.

On the front panel, the ready state is indicated by the green POWER ON /STAND BY button.



### To switch all connected instruments to standby state and close the R&S SGMA-GUI

- ▶ In the R&S SGMA-GUI main panel, select "File > Shut down instruments and exit".

The R&S SGMA-GUI quits and switches the connected instruments to standby state.



For description on how to terminate work and shut down the instrument regularly, refer to [Chapter 2.1.5, "Switching the Instrument On and Off"](#), on page 17.

---

## 9.4 How to Use Computer Names

Provided that there is a name server in the network, alternatively to the IP address each PC or instrument connected in a LAN can be accessed via an unambiguous computer name. Each instrument is delivered with an assigned computer name, but this name can be changed.



For instruction on how to find out the default computer name, refer to [Chapter 6.4.3, "Finding Out the Default Hostname of the Instrument"](#), on page 61.

---

### To query and change a computer name



To avoid violations and to make use of the easy identification provided by the computer name, it is recommended to keep the default hostname unchanged.

---

1. Open "SGMA-GUI > Instrument Name > Setup > Network Settings" dialog.  
The computer name is displayed under "Hostname".
2. Select "SGMA-GUI > Instrument Name > Setup > Protection" and enable the "Protection Level 1".  
The parameter "Hostname" in the "Network Settings" dialog is now enabled for configuration.
3. Change the "Hostname".
4. Press the POWER ON /STAND BY key to restart the instrument.  
**Note:** The "Factory Preset" function restores the factory value of the parameter "Hostname".

## 9.5 How to Install a New Firmware Version on the Instrument

You can update the firmware of the R&S SGU .

### Firmware Installation through the R&S SGMA-GUI



If an update to a new firmware version is required for both the R&S SGMA-GUI and the instrument, it is mandatory that the new instrument's firmware is installed prior to the update of the R&S SGMA-GUI to the new version.

1. Select "SGMA-GUI main panel > Instrument Name > Setup > Maintenance > Operation > Install firmware package".
2. Press "Select Package" and navigate to the directory the new firmware is stored in.
3. If several instruments have to be updated to new firmware version, enable the feature "Update All " to accelerate the update process.

All instruments that are in active state and are connected to this controller are updated simultaneously.

4. Enter the "Security Password".
5. Confirm the update with "Accept".

The software transfers the firmware file and automatically starts the update procedure. During the update, the message "Updating Firmware" is displayed in the Info line. The update process is indicated by an LED running light.

**Note:** The update procedure requires a restart of the instrument. The restart is performed automatically. The instrument is not accessible during that time.

6. Wait until the message "Updating Firmware" disappears and the update is completed.

The green POWER ON /STAND BY LED is on.

7. If required, install the new R&S SGMA-GUI.

For detailed description, refer to [Chapter 2.3.1, "Installing the R&S SGMA-GUI Software on an External PC"](#), on page 21

8. If the instrument and the controller/PC are connected over the PCIe interface and the external PC does not support hot-plugging, it is required to restart the external PC.

### Firmware Update through a Session Control Protocol (SCP)



If an update to a new firmware version is required for both the R&S SGMA-GUI and the instrument, it is mandatory that the new instrument's firmware is installed prior to the update of the R&S SGMA-GUI to the new version.

1. Connect the R&S SGU and a Windows PC to the same network.
2. On the PC, open a windows explorer window.
3. To connect to the R&S SGU enter the name of the instrument or its IP address in the windows taskbar.
4. Enter the user name and password to connect to the R&S SGU. The default user name is *instrument* and the password is *instrument*.  
A folder opens, containing the `share` and the `update` folder.
5. Open the `update` folder and copy the new firmware update file in it.  
The update starts automatically.



#### Unsuccessful or Erroneous Firmware Update

An erroneous or unsuccessful installation of firmware update package is indicated by a combination of red and one orange LEDs on the front panel.

Refer to the service manual for a description of the displayed error code or contact the customer support center.

## 9.6 How to Activate Options



A firmware update before the activation of the SW option may be required.

Refer to the description of the SW option for the required firmware version.

See also [Chapter 9.5, "How to Install a New Firmware Version on the Instrument"](#), on page 107 for instruction on how to update the firmware version.

1. Select "SGMA-GUI main panel > Instrument Name > Setup > Install SW-Options".
2. Select "Option Key" and enter the key code delivered with the new option.  
The new option is now enabled and ready for operation.

## 9.7 How to Manually Set a PCIe Direct Connection Between an R&S SGS and an R&S SGU

To build a direct PCIe connection between an R&S SGU and an R&S SGS, which has a "Controller > Revision" < 5, first you have to manually set the correct PCIe interface mode. If your R&S SGS has a "Controller > Revision" 5 or higher, these settings are done automatically.



You can check the "Controller > Revision" of your instrument in the "SGMA-GUI > Instrument Name > Hardware Config" dialog.

### To manually set a PCIe direct connection between an R&S SGS and an R&S SGU

1. Connect the R&S SGS and the R&S SGU directly using a PCIe cable. Refer to [Chapter 10.3.4, "Connecting the Controller and the Instrument"](#), on page 124 for cable requirements and setup information.
2. Switch on the R&S SGS and the R&S SGU.
3. Select "SGMA-GUI main panel > Instrument Name > Setup > Maintainance".
4. Select "Operation > PCIe Interface Mode".
5. Select "PCIe Interface Mode > Root Complex".
6. Restart your instrument for the changes to take place.

The PCIe connection between the R&S SGS and the R&S SGU is established and the instruments can be used.

## 10 Network and Remote Control Operation

As an alternative to operating the R&S SGU interactively via the R&S SGMA-GUI, one can also control the R&S SGU using programmed commands from a remote PC.



The description in this section requires basic knowledge of the remote control operation. Definitions specified in the SCPI standard are not provided.

Nevertheless, you can find some basic information to the SCPI syntax, command lists, and general programming recommendations in [Chapter A, "Remote Control Basics"](#), on page 194. In addition, this chapter provides information on the status reporting system of the instrument.

### 10.1 Remote Control Interfaces and Protocols

The instrument supports several interfaces for remote control. The following table gives an overview.

**Table 10-1: Remote control interfaces and protocols**

Interface	Protocols, VISA <sup>*)</sup> address string and Library	Remarks
Local Area Network (LAN)	<ul style="list-style-type: none"> <li>• <b>HiSLIP</b> High-Speed LAN Instrument Protocol (IVI-6.1) TCPIP::host address::hislip0[::INSTR]</li> <li>• <b>VXI-11</b> TCPIP::host address::inst0[::INSTR] Library: VISA</li> <li>• <b>socket communication</b> (Raw Ethernet, simple Telnet) TCPIP::host address[::LAN device name]::&lt;port&gt;::SOCKET Library: VISA or socket controller</li> </ul>	<p>A LAN connector is located on the rear panel of the instrument.</p> <p>The interface is based on TCP/IP and supports various protocols.</p> <p>For details, see <a href="#">Chapter 10.1.2, "LAN Interface"</a>, on page 113</p>
USB	<p><b>USBTMC</b></p> <p>USB::&lt;vendor ID&gt;::&lt;product ID&gt;::&lt;serial number&gt;[::INSTR]</p> <p>Library: VISA</p>	<p>A USB connector is located on the rear panel of the instrument.</p> <p>For details, see <a href="#">Chapter 10.1.3, "USB Interface"</a>, on page 116</p>
PCIe	<p><b>Proprietary</b></p> <p>PCIe::&lt;vendor ID&gt;::&lt;product ID&gt;::&lt;serial number&gt;[::INSTR]</p> <p>Library: pcie controller</p>	<p>A PCIe connector is located on the rear panel of the instrument.</p> <p>For details, see <a href="#">Chapter 10.1.4, "PCI Express Interface"</a>, on page 117</p>

<sup>\*)</sup> VISA is a standardized software interface library providing input and output functions to communicate with instruments. A VISA installation on the controller is a prerequisite for remote control over LAN (when using VXI-11 or HiSLIP protocol) or USB. However, no VISA installation is necessary for remote control while using socket communication. For more information about VISA, refer to the user documentation.



Rohde & Schwarz provides the standardized I/O software library R&S VISA for communication via TCP/IP (LAN: HiSLIP, VXI-11 and raw socket) or USB (USBTMC) interfaces.

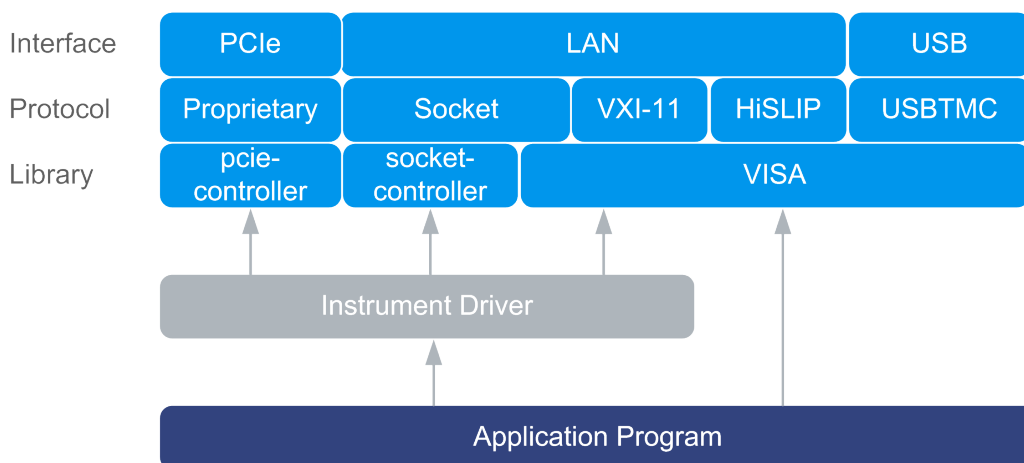
R&S VISA is available for download at the Rohde & Schwarz website <http://www.rohde-schwarz.com/rsvisa>.

### SCPI (Standard Commands for Programmable Instruments)

SCPI commands are used for remote control. Commands that are not taken from the SCPI standard follow the SCPI syntax rules. The instrument supports the SCPI version 1999. The SCPI standard is based on standard IEEE 488.2 and aims at the standardization of device-specific commands, error handling and the status registers. The tutorial "Automatic Measurement Control - A tutorial on SCPI and IEEE 488.2" from John M. Pieper (R&S order number 0002.3536.00) offers detailed information on concepts and definitions of SCPI.

## 10.1.1 Remote Control Programs and Libraries

The [Figure 10-1](#) provides a schematic illustration of the remote control capabilities of the instrument.



**Figure 10-1: Remote control interfaces, protocols and libraries**

The following examples give an overview of the dependencies between the available libraries, the possible interfaces and protocols, and whether an instrument driver is provided. The involved parts are **highlighted**.

- Remote control program using VISA

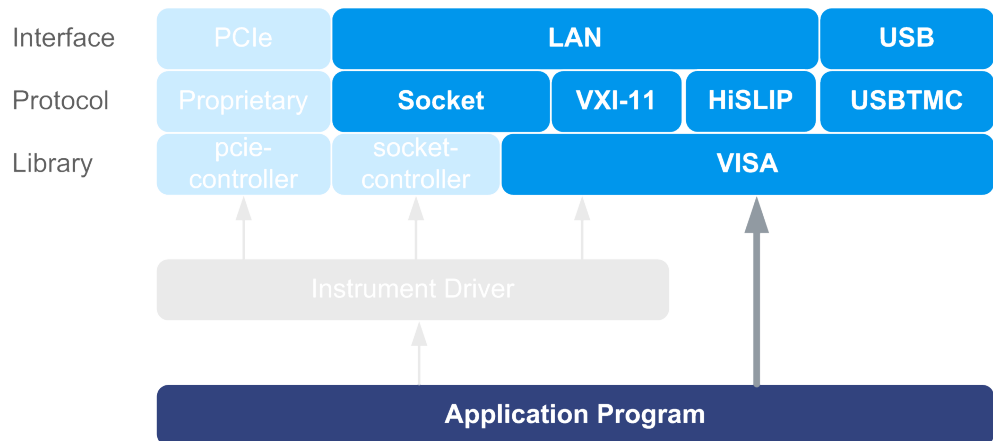


Figure 10-2: Remote control program using VISA

Protocol	Remote Control Program
Socket	<code>viOpen (... , "TCPIP:rssgu100a100010::5025::SOCKET", ...)</code> <code>viPrintf (... , "SOUR:FREQ 2GHz\n")</code>
VXI-11	<code>viOpen (... , "TCPIP:rssgu100a100010::inst0::INSTR", ...)</code> <code>viPrintf (... , "SOUR:FREQ 2GHz\n")</code>
HiSLIP	<code>viOpen (... , "TCPIP:rssgu100a100010::hislip0::INSTR", ...)</code> <code>viPrintf (... , "SOUR:FREQ 2GHz\n")</code>
USBTMC	<code>viOpen (... , "USB::0x0aad::0x00ce::1000010::INSTR", ...)</code> <code>viPrintf (... , "SOUR:FREQ 2GHz\n")</code>

- Remote control program using instrument driver (VISA available)

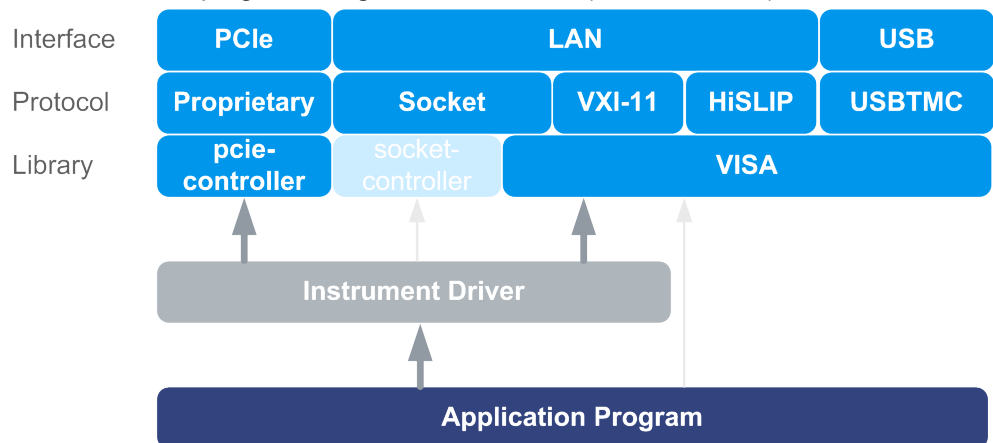


Figure 10-3: Remote control program using instrument driver (VISA available)

Protocol	Remote Control Program
Socket	<code>rssgu_init ("TCPIP:rssgu100a100010::5025::SOCKET", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>
VXI-11	<code>rssgu_init ("TCPIP:rssgu100a100010::inst0::INSTR", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>
HiSLIP	<code>rssgu_init ("TCPIP:rssgu100a100010::hislip0::INSTR", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>
USBTMC	<code>rssgu_init ("USB::0x0aad::0x00ce::1000010::INSTR", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>
PCIe	<code>rssgu_init ("PCIe::0x162f::0x132e::1000010::INSTR", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>

- Remote control program using instrument driver (VISA not available)

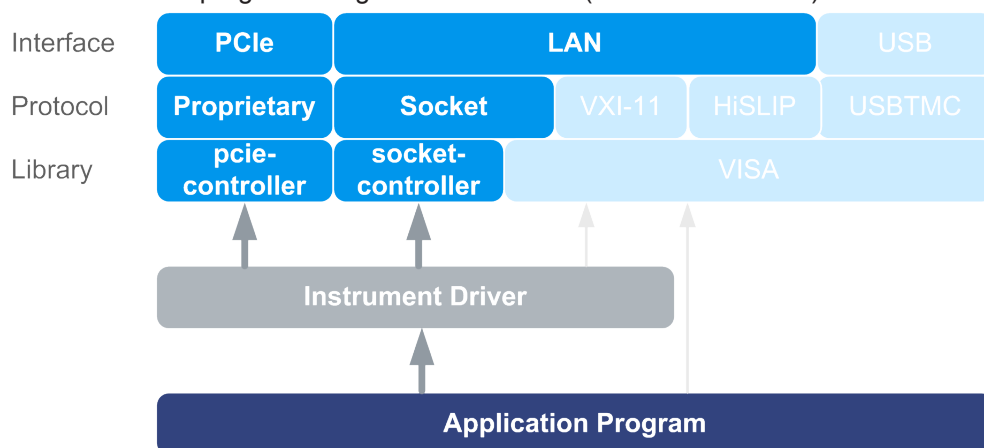


Figure 10-4: Remote control program using instrument driver (VISA not available)

Protocol	Remote Control Program
Socket	<code>rssgu_init ("TCPIP:rssgu100a100010::5025::SOCKET", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>
PCIe	<code>rssgu_init ("PCIe::0x162f::0x132e::1000010::INSTR", ...)</code> <code>rssgu_SetFrequency (... , 2e9)</code>

### 10.1.2 LAN Interface

To be integrated in a LAN, the instrument is equipped with a LAN interface, consisting of a connector, a network interface card and protocols.

For remote control via a network, the PC and the instrument must be connected via the LAN interface to a common network with TCP/IP network protocol. They are connected using a RJ45 cable (shielded or unshielded twisted-pair category 5). The TCP/IP network protocol and the associated network services are preconfigured on the instru-



ment. Software for instrument control and (for specified protocols only) the VISA program library must be installed on the controller.



### Identifying instruments in a network

If several instruments are connected to the network, each instrument has its own IP address and associated resource string. The controller identifies these instruments by the resource string.

#### 10.1.2.1 VISA Resource Strings

The VISA resource string is required to establish a communication session between the controller and the instrument in a LAN. The resource string is a unique identifier, composed of the specific IP address of the instrument and some network and VISA-specific keywords.

```
TCPIP::host address[::LAN device name][::INSTR]
```

- **TCPIP** designates the network protocol used
- **host address** is the IP address or host name of the device  
See also [Chapter 6.4.3, "Finding Out the Default Hostname of the Instrument"](#), on page 61.
- **[::LAN device name]** defines the protocol and the instance number of a subinstrument:
- **[::INSTR]** indicates the instrument resource class (optional)

The **IP address** (host address/computer name) is used by the programs to identify and control the instrument. It is automatically assigned by the DHCP server the first time the device is registered on the network. Alternatively, you can also assign its **LAN device name**.

You can find the IP address in the "SGMA-GUI > Instrument Name > Setup > Remote" dialog, and also adjust it manually, if necessary.

See below the characteristics of the VISA resource strings for the corresponding interface protocols. The highlighted characters are crucial.

#### HiSLIP

```
TCPIP::host address::hislip0[::INSTR]
```

- **hislip0** HiSLIP device name, designates that the interface protocol HiSLIP is used (mandatory)

**hislip0** is composed of `[::HiSLIP device name[,HiSLIP port]]` and must be assigned.

For details of the HiSLIP protocol, refer to [Chapter 10.1.2.2, "HiSLIP Protocol"](#), on page 115.

#### VXI-11

```
TCPIP::host address[::inst0][::INSTR]
```

- **[::inst0]** LAN device name, indicates that the VXI-11 protocol is used (optional)

**inst0** currently selects the VXI-11 protocol by default and can be omitted.

For details of the VXI-11 protocol, refer to [Chapter 10.1.2.3, "VXI-11 Protocol"](#), on page 116

### Socket communication

TCPIP::::port::

- **port** determines the used port number
- **SOCKET** indicates the raw network socket resource class

Socket communication requires the specification of the port (commonly referred to as port number) and of "SOCKET" to complete the VISA resource string with the associated protocol used.

The registered port for socket communication is port 5025.

See also [Chapter 10.1.2.4, "Socket Communication"](#), on page 116.

### Example:

- Instrument has the IP address *10.113.11.91*; the valid resource string using VXI-11 protocol is:

```
TCPIP::10.113.11.91::INSTR
```

- The DNS host name is *rssgu100a100021*; the valid resource string is:

```
TCPIP::rssgu100a100021::hislip0 (HiSLIP)
```

```
TCPIP::rssgu100a100021::inst0 (VXI-11)
```

- A raw socket connection can be established using:

```
TCPIP::10.113.11.91::5025::SOCKET
```

## 10.1.2.2 HiSLIP Protocol

The HiSLIP (**H**igh **S**peed **L**AN **I**nstrument **P**rotocol) is the successor protocol for VXI-11 for TCP-based instruments specified by the IVI foundation. The protocol uses two TCP sockets for a single connection - one for fast data transfer, the other for non-sequential control commands (e.g. `Device Clear` or `SRQ`).

HiSLIP has the following characteristics:

- High performance as with raw socket network connections
- Compatible IEEE 488.2 support for Message Exchange Protocol, Device Clear, Serial Poll, Remote/Local, Trigger, and Service Request
- Uses a single IANA registered port (4880), which simplifies the configuration of firewalls
- Supports simultaneous access of multiple users by providing versatile locking mechanisms
- Usable for IPv6 or IPv4 networks



Using VXI-11, each operation is blocked until a VXI-11 device handshake returns. However, using HiSLIP, data is sent to the device using the "fire and forget" method with immediate return. Thus, a successful return of a VISA operation such as `viWrite()` does not guarantee that the instrument has finished or started the requested command, but is delivered to the TCP/IP buffers.

For more information see also the application note: [1MA208: Fast Remote Instrument Control with HiSLIP](#).

### 10.1.2.3 VXI-11 Protocol

The VXI-11 standard is based on the ONC RPC (Open Network Computing Remote Procedure Call) protocol which in turn relies on TCP/IP as the network/transport layer. The TCP/IP network protocol and the associated network services are preconfigured. TCP/IP ensures connection-oriented communication, where the order of the exchanged messages is adhered to and interrupted links are identified. With this protocol, messages cannot be lost.

### 10.1.2.4 Socket Communication

An alternative way for remote control of the software is to establish a simple network communication using sockets. The socket communication, also referred to as "Raw Ethernet communication", does not require a VISA installation on the remote controller side.

The simplest way to establish socket communication is to use the built-in telnet program. The telnet program is part of every operating system and supports communication with the software on a command-by-command basis.

Socket connections are established on a specially defined port. The socket address is a combination of the IP address or the host name of the instrument and the number of the port configured for remote-control. All instruments use port number 5025 for this purpose. The port is configured for communication on a command-to-command basis and for remote control from a program running on a connected PC.

## 10.1.3 USB Interface

For remote control via USB connection, the PC and the instrument must be connected via the USB interface. A USB connection requires the VISA library to be installed. VISA detects and configures the R&S instrument automatically when the USB connection is established. You do not have to install a separate driver.

### USB resource string

The syntax of the used USB resource string is:

`USB::<vendor ID>::<product ID>::<serial number>[:INSTR]`, where:

- **USB** denotes the used interface
- **<vendor ID>** is the manufacturer ID for Rohde&Schwarz

- **<product ID>** is the product identification of the R&S instrument
- **<serial number>** is the individual serial number on the rear of the instrument
- **[::INSTR]** indicates the instrument resource class (optional)

You can retrieve the USB resource string from the "SGMA-GUI > Instrument Name > Setup > Remote" dialog.

**Example:**

```
USB::0x0AAD::0x00ce::100021::INSTR
```

0x0AAD is the vendor ID for Rohde&Schwarz

0x00ce is the product ID for the R&S SGU

100021 is the serial number of the particular instrument

### 10.1.4 PCI Express Interface

A PCI Express (PCIe) connector is provided on the rear panel of the instrument.

Refer to [Chapter 10.3, "Advanced Remote Control Using PCIe"](#), on page 120 for a description of how to set up a remote control connection via PCIe and the permitted cables.

Via PCI Express some commands can be sent to the instrument with optimized speed (memory-mapped remote control), e.g. frequency or level settings. This allows minimum setup time.

**PCIe resource string**

The syntax of the used PCIe resource string is:

```
PCIe::<vendor ID>::<product ID>::<serial number>[::INSTR], where:
```

- **PCIe** denotes the used interface
- **<vendor ID>** is the manufacturer ID for Rohde&Schwarz
- **<product ID>** is the product identification of the R&S instrument
- **<serial number>** is the individual serial number on the rear of the instrument
- **[::INSTR]** indicates the instrument resource class (optional)

You can retrieve the PCIe resource string from the "SGMA-GUI > Instrument Name > Setup > Remote" dialog.

**Example:**

```
PCIe::0x162f::0x132e::100021::INSTR
```

0x162f is the vendor ID for Rohde&Schwarz

0x132e is the product ID for the R&S SGU

100021 is the serial number of the particular instrument

## 10.2 Starting a Remote Control Session

The instrument and the controller have to be connected with a suitable cable and switched on.

A remote control program must open a connection to the instrument, before it can send commands to and receive device responses from the instrument.



### Instrument address

To operate the instrument via remote control, it must be addressed using the defined interface address.

See [Chapter 10.1.2, "LAN Interface"](#), on page 113, [Chapter 10.1.3, "USB Interface"](#), on page 116 or [Chapter 10.1.4, "PCI Express Interface"](#), on page 117 for details.

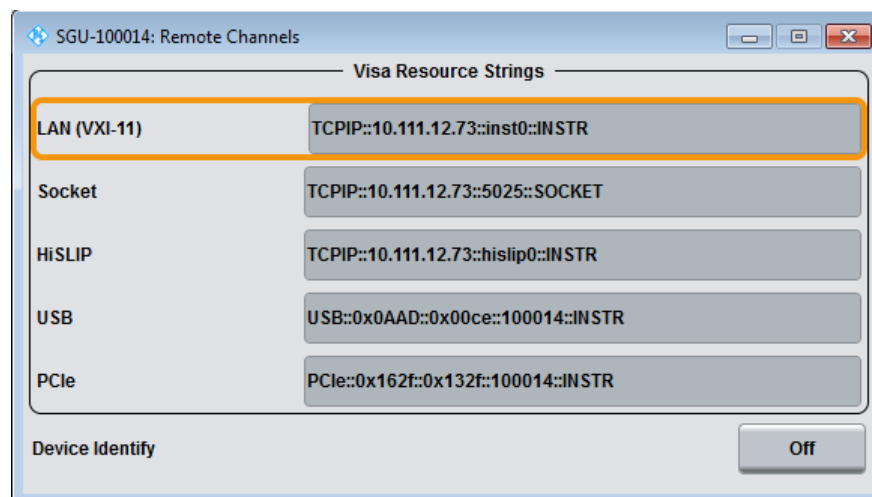


The VISA resource strings are indicated in the "SGMA-GUI main panel > Instrument name > Setup > Remote Channels" dialog.

### 10.2.1 How to Find the VISA Resource String

To find the VISA resource strings of your instrument:

- ▶ Select "SGMA-GUI main panel > Instrument name > Setup > Remote Channels".



The "Remote Channel Settings" dialog shows all specified resource strings of the supported remote control interfaces.

## 10.2.2 Example: Remote Control over LAN Using Socket Communication

This section provides an example on how to establish a remote control connection over telnet protocol and a simple sockets-based program example that can be further developed (see also [Chapter B, "Telnet program examples"](#), on page 216).

Basic knowledge of programming and operation of the controller are assumed. A description of the interface commands can be obtained from the relevant manuals.



Refer to the Getting Started manual for an example on how to set up remote control connection over LAN using VXI-11 protocol.

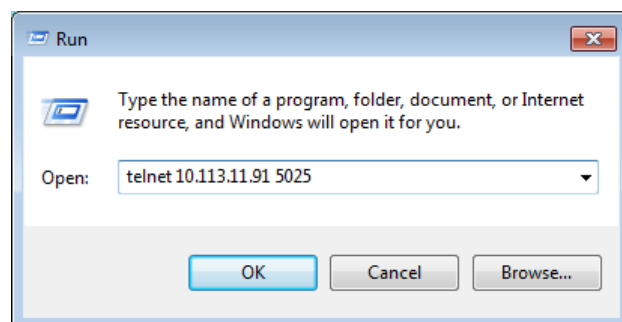
### To set up a Telnet connection

To control the software, only a telnet program is required. The telnet program is part of every operating system.

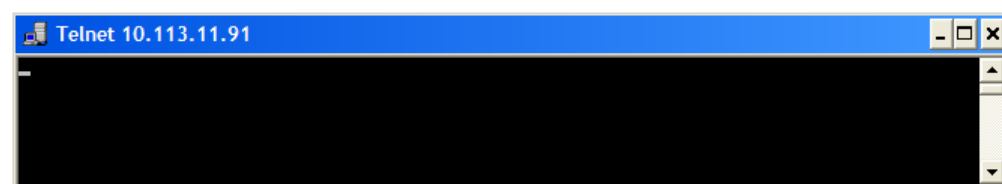
1. To establish a Telnet connection with the R&S SGU, start the telnet program and enter the socket address.

The socket address is a combination of the IP address or the host name of the R&S SGU and the number of the port configured for remote-control via telnet.

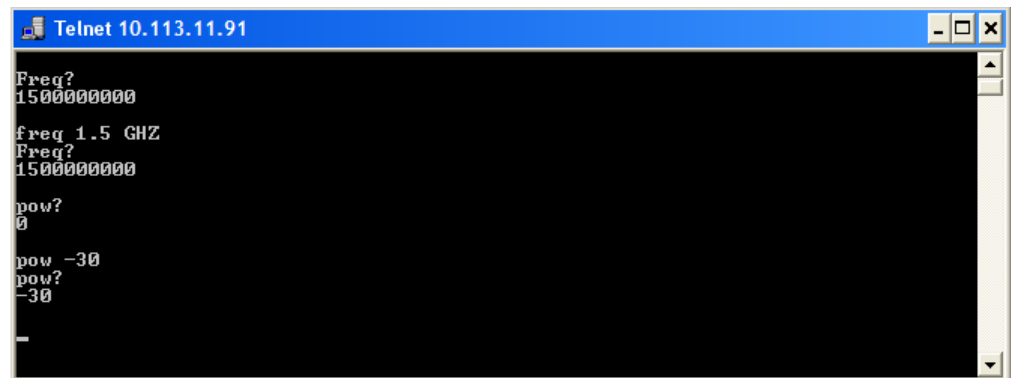
**Tip:** The R&S SGU uses the port number 5025 for remote connection via Telnet.



The connection to the instrument is set up and remote-control commands can be sent.



2. Even if the cursor is not visible on the screen, enter blind a remote-control command and confirm with Enter.



```
Telnet 10.113.11.91
Freq?
1500000000
freq 1.5 GHz
Freq?
1500000000
pow?
0
pow -30
pow?
-30
```

## 10.3 Advanced Remote Control Using PCIe

The PCIe bus is a high-speed serial bus, composed of point-to-point serial links. A pair of serial links, one transmitting and one receiving link, make up a lane.

### Fast settings

The PCIe interface can be utilized not only to transfer text messages e.g. SCPI commands but also to carry register based remote control messages. The latter mode is called fast settings mode. The specially for this purpose provided instrument's driver is mandatory for the instrument control with fast settings. This instrument driver contains special functions for fast setup.



To use the advantage of the fast settings, the following prerequisites must be fulfilled:

- Using the PCIe interface is mandatory (see also [Chapter 10.3.1, "Setting Up a Remote Control Connection via PCIe"](#), on page 120)
- The fast settings must be enabled with the function `rssgu_useFastSettings` (see also [Chapter 10.3.5, "Enabling Fast Settings"](#), on page 124).

The instrument driver automatically uses the fast settings method whenever possible - currently only for the parameters frequency, level, RF state, modulator state - and sends SCPI messages in all other cases.

Remote control programs written for PCIe will, without modifications, also run if one of the other control channels, LAN or USB is used.

### 10.3.1 Setting Up a Remote Control Connection via PCIe

To set up a remote control connection via PCIe, perform the following steps:

1. Download the drivers, see [10.3.2](#).
2. Configure the controller, see [10.3.3](#)

3. Connect the controller and the instrument, see [10.3.4](#)
4. Enable fast settings, see [10.3.5](#).

### 10.3.2 Download the Drivers

All required driver files are available for download on the product page at:

<http://www.rohde-schwarz.com/product/SGU100A.html> > "Downloads" > "Drivers"

Provided are the following files:

- LabWindows/CVI, Linux/OSX driver `rssgu (InstrumentDriver)`  
C source code files which provide a functional application programming interface (API) to R&S SGU instruments. Required if you want to control an instrument via PCIe.
- Low-Level SGU drivers  
Archive file that contains the following:
  - `KernelDriver`  
C source code files from which you can build a Linux kernel mode driver for the R&S SGU PCIe remote control interface.
  - `SguDriverDemo`  
C source code module for a demo program using the instrument driver API.
  - `SharedLibraries-Dlls`  
Shared libraries (Dlls) for remote control channels Socket and PCIe. To be used with the instrument driver.
- `VXIplug&play x64/x86 driver rssgu`

Download the required archive and extract the files on a remote PC.

### 10.3.3 Configuring the Controller

This section lists the steps necessary to configure a controller with Linux or Windows operating system.

#### 10.3.3.1 Building and Installing the Hardware Driver

The hardware driver defines the way to communicate with the instrument via PCIe interface.



For Windows operating systems, the hardware driver is installed automatically together with the installation of the R&S SGMA-GUI software.

See also section "Installation of R&S SGMA-GUI Software" in the getting started manual.

---

For Linux operating system, the source code of the driver is included in the `Low-Level SGU drivers` file.



To build and install this driver, root authority is required.

1. Copy folder `KernelDriver` to your `hdd`
2. Go to directory `host`.
3. On the command line, enter `make`.  
The driver `sgshost.ko` is automatically built.
4. Enter `make install`.  
Device nodes `sguX` are created under the folder `/dev` (X from 0 to 31).  
The module `sguhost` is loaded.
5. Enter `lsmod` to verify the module.

### 10.3.3.2 Making Shared Libraries Accessible

Two library files per operating system are included in `SharedLibraries-Dlls` file:

- For Linux operating system  
`libsocketcontroller.so` and `libpciecontroller.so`
- For Windows operating system  
`SocketController.dll` and `PCIEController.dll`

These libraries act as the dynamic link libraries for programs using the socket or PCIe interface.

#### Linux operating system

- ▶ To make the libraries accessible, perform one of the following:
  - a) Append the environment variable `LD_LIBRARY_PATH` with the path of these two files e.g. by changing the `/etc/environment` file.
  - b) Move these two files to `/usr/lib` or `/lib` directory.

#### Windows operating system

- ▶ To make the libraries accessible, perform one of the following:
  - a) Copy these two files to the folder of your executable.
  - b) Copy these two files to the `WINDOWS\system32` folder.

### 10.3.3.3 Building a Program

The help file `rssgu_vxi.chm` shows all functions of the instrument which you can use in your own remote control program.

An example file is provided (`SguDriverDemo.c`), too.

#### Building the example program (Linux)

1. Copy folders `InstrumentDriver` and `SguDriverDemo` to your hard disk.

2. Go to folder `Build`
3. On the command line, enter `cmake ..`
4. Enter `make`

Folder `Build` contains the executable `SguDriverDemo`.

### Building the example program (Windows)

1. Copy folders `InstrumentDriver` and `SguDriverDemo` to your hard disk.
2. Open `SguDriverDemo.vcproj` with Visual Studio.
3. Build the program.

### Running the example program

- ▶ On the command line, enter `./SguDriverDemo RESOURCESTRING [cmd]`.

Where

- `RESOURCESTRING` is the (VISA) resource string of your instrument, e.g.  
`TCPIP::ipaddress::5025::SOCKET` or `PCIE::0x162f::0x132e::serialno::INSTR`.  
 Where `ipaddress` is the IP address or hostname of your instrument and `serialno` is its serial number.
- `cmd` is an optional command (see table).

The following table list the available commands.

Command	Description
<code>?</code>	Usage
<code>q</code>	Quit
<code>f value</code>	Set frequency
<code>f?</code>	Query frequency
<code>l value</code>	Set level
<code>l?</code>	Query level
<code>r value</code>	Set RF state (value = 0   1   ON   OFF)
<code>r?</code>	Query RF state

If you enter an additional optional command, `SguDriverDemo` executes it and enters a loop waiting for further commands.

### Example:

```
TCPIP::10.111.11.44::5025::SOCKET ?
```

Lists the available commands.

### 10.3.4 Connecting the Controller and the Instrument

A PCIe connector is provided on the rear panel of the instrument.

#### NOTICE

##### Risk of device failure

The R&S SGU is equipped with a single lane PCIe interface that supports hot plugging. Do not connect an external PC to the PCIe connector of the instrument during operation if this external PC does not support hot-plugging!



##### Permitted PCIe cables

PCIe extension cables must fulfill the following requirements:

- **Single lane connectors**
- **Max. cable length of 5 m.**

For example: OSS-PCIe-CBL-x1 cable from One Stop Systems or 74576-000x cable from Molex.

##### Connecting an external PC that does not support hot-plugging

1. Switch off the external PC and the instrument.  
See also [Chapter 2.1.5, "Switching the Instrument On and Off"](#), on page 17.
2. Connect the instrument and the controller with the suitable cable.
3. Switch on the instrument.
4. Wait until the instrument has completed the booting (the "POWER" LED on the instrument's front panel is constantly on).
5. Switch on the external PC.

##### Connecting an R&S SGS and an R&S SGU

If you use the R&S SGU as an upconverter to the R&S SGS, the R&S SGS acts as a controller to the R&S SGU. For a description of how to connect the instruments refer to [Chapter 5.2, "Setups for Connecting an R&S SGS and an R&S SGU"](#), on page 39.

### 10.3.5 Enabling Fast Settings

- ▶ To enable the special PCI express feature fast settings, enable the function `rssgu_UseFastSettings` (`ViSession instrumentHandle`, `ViBoolean fastEnabled`, `ViBoolean asynchronousEnabled`) included in the instrument driver.

Settings for some parameters like level and frequency accelerate.

To disable the fast settings, call the function `rssgu_UseFastSettings` with argument `fastEnabled=false`.

## 10.4 Advanced Remote Control Using Fast Socket

### Fast settings

The socket interface can be utilized not only to transfer text messages e.g. SCPI commands but also to carry register based remote control messages. The latter mode is called fast settings mode. The fast socket communication is based on the Ethernet protocol which does not support routing. Therefore a controller PC can only control devices within its own network segment using the fast socket method.



To use the advantage of the fast settings, the following prerequisites must be fulfilled:

- On Windows operating systems, the fast socket driver must be installed.
- The application program must be run with root/administrator rights.
- The fast settings must be enabled with the function `rssgu_useFastSettings` (see also [Chapter 10.3.5, "Enabling Fast Settings"](#), on page 124).

The instrument driver automatically uses the fast settings method whenever possible, currently for the parameters frequency, level, RF state, I/Q modulator state, crest factor, host frequency, host level, apply settings. In all other cases, SCPI messages are sent.

### 10.4.1 Setting Up a Remote Control Connection via Fast Socket

Download the required archive and extract the files on a remote PC, as described in [Chapter 10.3.2, "Download the Drivers"](#), on page 121.

#### Windows operating systems

To set up a remote control connection via fast socket for Windows operating systems, perform the following steps:

1. Connect the controller and the instrument, see [Chapter 2.3.2, "Connecting a Remote PC via LAN"](#), on page 22.
2. Install the protocol driver to the controller, see [Chapter 10.4.2, "Installing the Protocol Driver"](#), on page 126.
3. On the controller start the driver by using one of the following:
  - a) Start the Windows console user interface as an administrator.  
Execute the command `net start SGMANDISPROT`.
  - b) Use a program for opening the driver.  
See for example the example file `SguDriverDemo.c`.

4. Start the application with administrator rights.
5. Enable fast settings, see [Chapter 10.4.3, "Enabling Fast Settings"](#), on page 126.

#### Linux operating systems

To set up a remote control connection via fast socket for Linux operating systems, perform the following steps:

1. Connect the controller and the instrument, see [Chapter 2.3.2, "Connecting a Remote PC via LAN"](#), on page 22.
2. Start the application as root.
3. Enable fast settings, see [Chapter 10.4.3, "Enabling Fast Settings"](#), on page 126.

### 10.4.2 Installing the Protocol Driver

The protocol driver defines the way to communicate with the instrument via the LAN fast socket interface.

For Linux operating system, no special driver is needed.

For Windows operating systems, the `SGMANDISPROT` driver is required. The protocol driver is installed automatically together with the installation of the R&S SGMA-GUI software. It is also provided in the `Low-Level_SGU_drivers` file.

To install the driver manually on a Windows operating system:

1. Open "Control Panel > Network and Sharing Center".
2. Select the network adapter on which you want to install the driver and click it.  
The "Local Area Connection Status" dialog opens.
3. Click "Properties" to open the "Local Area Connection Properties" dialog.
4. Click "Install" to open the "Select Network Feature Type" dialog.
5. Select "Protocol" and select "Add".
6. In the "Select Network Protocol" dialog, select "Have Disk".  
Navigate to the directory where the driver is saved and click "OK" to install the driver.

### 10.4.3 Enabling Fast Settings

- ▶ To enable the fast settings for the fast socket, call function `rssgu_UseFastSettings` (`ViSession instrumentHandle`, `ViBoolean fastEnabled`, `ViBoolean asynchronousEnabled`) included in the instrument driver.

Settings for some parameters like level and frequency accelerate.

To disable the fast settings, call the function `rssgu_UseFastSettings` with argument `fastEnabled=false`.

## 10.5 Using the R&S SGMA-GUI to Monitor the Remote Control Operation

The R&S SGMA-GUI can be used to monitor the behavior of one or more instruments while they are remote controlled.

A typical configuration consists of one monitor, controller(s) and instrument(s), where the monitor is the remote PC on which the R&S SGMA-GUI is installed and the controller is the remote PC on which the application program runs.

Simultaneous control of an instrument from a controller and a monitor may lead to collisions whenever both the controller and the monitor utilize the same remote channel. These collisions are indicated by an error message in the Info line, e.g. "Query interrupted" or "Resource locked". Simultaneous monitoring and control over the same remote channel is only possible, if the used protocols support `viLock()`/`viUnlock()` and the remote program use these functions.

The [Table 10-2](#) shows whether a collision-free communication over a particular combination of remote channels is possible or not and if there are any restrictions.

**Table 10-2: Cross-reference between used remote channels and collision-free communication**

Monitor/ Controller	LAN (VXI-11)	LAN (HiSLIP)	USB	LAN (Socket)	PCIe
LAN (VXI-11)	OK*	OK	OK	OK	OK
LAN (HiSLIP)	OK	OK	OK	OK	OK
USB	OK	OK	<code>viLock/viUnlock</code>	OK	OK
LAN (Socket)	OK	OK	OK	X	OK
PCIe	OK	OK	OK	OK	X

Where:

- **OK:** communication possible, no collisions  
\*) the R&S SGMA-GUI always uses the LAN device name `instr1`, see also [Chapter 10.1.2.3, "VXI-11 Protocol"](#), on page 116.
- **X:** communication is not possible without collisions
- `viLock/viUnlock`: communication is only possible, if the remote control commands are enclosed in a `viLock () - viUnlock ()` pair.



The R&S SGMA-GUI uses the `viLock()`/`viUnlock()` functions.

The figure below shows an example of configuration where the monitor and the controller are two different computers, connected to the same instrument over two different hardware interfaces.

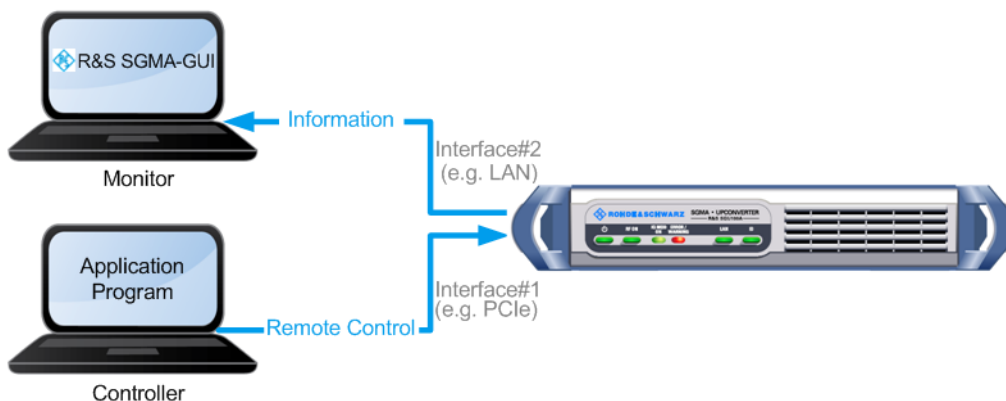


Figure 10-5: Example of setup for remote control monitoring

### Connecting and configuring the monitoring PCs



In the "Setup > Security > Security Settings" dialog, check the state of the LAN and USB interfaces and enable them if necessary.

1. Connect the monitoring PC to the instrument.  
**Note:** Choose the hardware interface considering the limitations described in [Table 10-2](#).
2. Configure the instrument in the R&S SGMA-GUI, see [Chapter 6.4.2, "Handling Instruments in the R&S SGMA-GUI"](#), on page 58.
3. In the "SGMA-GUI > Setup > Instruments > Edit Instruments" dialog, disable "Exclusive Access".  
**Note:** The two functions "Exclusive Access" and monitoring are mutually exclusive.
4. Send remote control commands from the controller to the instrument, open the corresponding dialogs in the R&S SGMA-GUI and observe the status of the parameters.

# 11 Remote Control Commands

In the following, all remote-control commands will be presented in detail with their parameters and the ranges of the numerical values.

## Conventions used in SCPI Command Descriptions

Note the following conventions used in the remote command descriptions:

- **Command usage**  
If not specified otherwise, commands can be used both for setting and for querying parameters.  
If a command can be used for setting or querying only, or if it initiates an event, the usage is stated explicitly.
- **Parameter usage**  
If not specified otherwise, a parameter can be used to set a value and it is the result of a query.  
Parameters required only for setting are indicated as **Setting parameters**.  
Parameters required only to refine a query are indicated as **Query parameters**.  
Parameters that are only returned as the result of a query are indicated as **Return values**.
- **Conformity**  
Commands that are taken from the SCPI standard are indicated as **SCPI confirmed**. All commands used by the R&S SGU follow the SCPI syntax rules.
- **Asynchronous commands**  
A command which does not automatically finish executing before the next command starts executing (overlapping command) is indicated as an **Asynchronous command**.
- **Reset values (\*RST)**  
Default parameter values that are used directly after resetting the instrument (\*RST command) are indicated as \*RST values, if available.
- **Default unit**  
This is the unit used for numeric values if no other unit is provided with the parameter.
- **Manual operation**  
If the result of a remote command can also be achieved in manual operation, a link to the description is inserted.

## 11.1 Programming Examples

This chapter provides simple programming examples for the R&S SGU. The purpose of the examples is to present **all** commands for a given task. In real applications, one would rather reduce the examples to an appropriate subset of commands.

The programming examples have been tested with a software tool which provides an environment for the development and execution of remote tests. To keep the examples



as simple as possible, only the "clean" SCPI syntax elements are reported. Non-executable command lines (e.g. comments) start with two // characters.

At the beginning of most remote control programs, an instrument (p)reset is recommended to set the R&S SGU to a defined state. The commands \*RST and SYSTem:PRESet are equivalent for this purpose. \*CLS also resets the status registers and clears the output buffer.

It is also recommended to lock the instrument for remote control from the selected controller prior to further configuration. Use the LOCK command for this purpose.

### 11.1.1 Performing General Tasks for Instrument Setup

In the following example we assume that a remote PC is connected to the instrument, the remote PC and the instrument are switched on and a connection between them is established.

```
// *****
// Reset the instrument first
// *****

*RST; *CLS
// :SYSTem:PRESet
// :REStart
// :SYSTem:FPReset

// *****
// Lock the instrument to the controller
// *****

:LOCK? 12345
// Lock the instrument to avoid interference by other controllers
// Use an arbitrary number
// Response: 1
// Request granted, i.e. the instrument is locked
// Abort program if request is refused

// *****
// Launch diagnostic
// *****

:DIAGNostic:POINt:CATalog?
// Response: : D_TEMP_UP20,D_TEMP_CPU
:DIAGNostic:MEASure:POINt? 'D_TEMP_UP20'

// *****
// Query the entries in the error queue
// *****

SYSTem:SERRor?
```

```

// Query static errors
// SYSTem:ERRor:CODE:NEXT?
// SYSTem:ERRor:COUNT?
// SYSTem:ERRor:NEXT?
// STATus:QUEue:NEXT?
// SYSTem:ERRor:CODE:ALL?
SYSTem:ERRor:ALL?
// Query error queue

// *****
// Query system information
// *****

:SYSTem:VERSion?
:SYSTem:OSYStem?

// *****
// Activate eco mode
// *****

:SYSTem:EMODe EM1

// *****
// Unlock the instrument
// *****

:UNL 12345

```

### 11.1.2 Generating an I/Q Modulated Signal

In the following example we assume that a remote PC is connected to the instrument, the remote PC and the instrument are switched on and a connection between them is established. An external analog signal is provided at the I and Q connectors of the instrument.

```

// *****
// Reset the instrument first
// *****

*RST; *CLS

// *****
// Lock the instrument to the controller
// *****

:LOCK? 12345
// Lock the instrument to avoid interference by other controllers
// Use an arbitrary number
// Response: 1

```

```

// Request granted, i.e. the instrument is locked
// Abort program if request is refused

// *****
// Set RF frequency and level
// *****

:SOURce:FREQuency:CW 2 GHz
:SOURce:POWer:-10dBm
:SOURce:POWer:PEP?

// *****
// Define and enable impairments
// Enable modulation
// *****

:SOURce:IQ:STATe ON
:SOURce:IQ:IMPairment:STATe ON

:SOURce:IQ:IMPairment:LEAKage:I -1
:SOURce:IQ:IMPairment:LEAKage:Q 1
:SOURce:IQ:IMPairment:IQRatio: 1
:SOURce:IQ:IMPairment:QUADrature:ANGLE 2
:SOURce:IQ:CREStfactor 0.05

// *****
// Enable output of the generated signal at the RF connector
// *****

:OUTPut:STATe ON
:OUTPut:STATe:PON UNCH

// *****
// Query LO frequency and power values and set LO
// *****

:LOSCillator:FREQuency?
:LOSCillator:POWer?

// Set frequency and power on the local oscillator as required

// *****
// Switch on the signal
// *****

:SETTings:APPLY

// *****
// Unlock the instrument
// *****

```

```
:UNL 12345
```

### 11.1.3 Advanced Task for Optimizing Performance

In the following example we assume that a remote PC is connected to the instrument, the remote PC and the instrument are switched on and a connection between them is established.

```
// *****
// Reset the instrument first
// *****

*RST; *CLS
// :SYSTem:PRESet
// :REStart
// :SYSTem:FPReset

// *****
// Lock the instrument to the controller
// *****

:LOCK? 12345
// Lock the instrument to avoid interference by other controllers
// Use an arbitrary number
// Response: 1
// Request granted, i.e. the instrument is locked
// Abort program if request is refused

// *****
// Query the level that can be set without adjustments of the attenuator
// *****

:OUTPut:AFIXed:RANGe:LOWer?
:OUTPut:AFIXed:RANGe:UPPer?

// *****
// Optimizing the quality characteristics of the RF signal
// *****

:SOURce:POWer:LMOde LNOise
// optimize the signal to low noise ratio
:SOURce:POWer:SCHaracteristic AUTO
// ensure highest dynamic range
:SOURce:POWer:LEVel:IMMediate:AMPLitude -30dBm
:SOURce:POWer:LIMit:AMPLitude 30dBm

:OUTPut:STATe:PON UNCHanged
```

```

// *****
// Query local oscillator frequency and power values and set LO
// *****

:LOSCillator:FREQuency?
:LOSCillator:POWer?

// Set frequency and power on the local oscillator as required

// *****
// Switch on the signal
// *****

:SETTings:APPLY

// *****
// Unlock the instrument
// *****

:UNL 12345

```

#### 11.1.4 Adjusting Network and Remote Channel Settings

In the following example we assume that a remote PC is connected to the instrument, the remote PC and the instrument are switched on and a connection between them is established.

```

// *****
// Reset the instrument first
// *****

*RST; *CLS

// *****
// Lock the instrument to the controller
// *****

:LOCK? 12345
// Lock the instrument to avoid interference by other controllers
// Use an arbitrary number
// Response: 1
// Request granted, i.e. the instrument is locked
// Abort program if request is refused

// *****
// Query the VISA resource strings
// *****

```

```

:SYSTem:COMMunicate:NETWork:RESource?
// Response: TCPIP::10.113.10.187::INSTR
:SYSTem:COMMunicate:SOCKeT:RESource?
// Response: TCPIP:10.113.10.187::5025::SOCKET
:SYSTem:COMMunicate:USB:RESource?
// Response: USB::0x0AAD::0x00ce::100021::INSTR
:SYSTem:COMMunicate:PCIexpress:RESource?
// Response: PCIe::0x162f::0x132f::100002::INSTR

// *****
// Query network settings
// *****

:SYSTem:COMMunicate:NETWork:COMMON:HOSTName?
// Response: rssgu100a100002
:SYSTem:COMMunicate:NETWork:IPAddress:MODE?
// Response: AUTO
:SYSTem:COMMunicate:NETWork:IPAddress?
// Response: 10.113.10.187
:SYSTem:COMMunicate:NETWork:IPAddress:SUBNet:MASK?
// Response: 255.255.0.0
:SYSTem:COMMunicate:NETWork:IPAddress:GATeway?
// Response: 10.113.0.1

// *****
// Unlock the instrument
// *****

:UNL 12345

```

## 11.2 Common Commands

Common commands are described in the IEEE 488.2 (IEC 625-2) standard. These commands have the same effect and are employed in the same way on different devices. The headers of these commands consist of "\*" followed by three letters. Many common commands are related to the Status Reporting System.

Available common commands:

*CLS.....	136
*ESE.....	136
*ESR?.....	136
*IDN?.....	136
*IST?.....	137
*OPC.....	137
*OPT?.....	137
*PRE.....	137
*PSC.....	137
*RCL.....	138

*RST.....	138
*SAV.....	138
*SRE.....	138
*STB?.....	139
*TRG.....	139
*WAI.....	139

---

### \*CLS

Clear status

Sets the status byte (STB), the standard event register (ESR) and the `EVENT` part of the `QUESTIONABLE` and the `OPERATION` registers to zero. The command does not alter the mask and transition parts of the registers. It clears the output buffer.

**Usage:**                   Setting only

---

### \*ESE <Value>

Event status enable

Sets the event status enable register to the specified value. The query returns the contents of the event status enable register in decimal form.

**Parameters:**

<Value>                   Range:     0 to 255

---

### \*ESR?

Event status read

Returns the contents of the event status register in decimal form and subsequently sets the register to zero.

**Return values:**

<Contents>               Range:     0 to 255

**Usage:**                   Query only

---

### \*IDN?

Identification

Returns the instrument identification.

**Return values:**

<ID>                       "Rohde&Schwarz,<device type>,<serial number>,<firmware version>"

**Example:**               Rohde&Schwarz,SGU,  
1407.6004k02/000000,3.1.17.1-03.01.158

**Usage:**                   Query only

---

**\*IST?**

Individual status query

Returns the contents of the IST flag in decimal form. The IST flag is the status bit which is sent during a parallel poll.

**Return values:**

<ISTflag>            0 | 1

**Usage:**                Query only

---

**\*OPC**

Operation complete

Sets bit 0 in the event status register when all preceding commands have been executed. This bit can be used to initiate a service request. The query form writes a "1" into the output buffer as soon as all preceding commands have been executed. This is used for command synchronization.

---

**\*OPT?**

Option identification query

Queries the options included in the instrument. For a list of all available options and their description refer to the data sheet.

**Return values:**

<Options>            The query returns a list of options. The options are returned at fixed positions in a comma-separated string. A zero is returned for options that are not installed.

**Usage:**                Query only

---

**\*PRE <Value>**

Parallel poll register enable

Sets parallel poll enable register to the indicated value. The query returns the contents of the parallel poll enable register in decimal form.

**Parameters:**

<Value>                Range:     0 to 255

---

**\*PSC <Action>**

Power on status clear

Determines whether the contents of the `ENABLE` registers are preserved or reset when the instrument is switched on. Thus a service request can be triggered when the instrument is switched on, if the status registers ESE and SRE are suitably configured. The query reads out the contents of the "power-on-status-clear" flag.



**Parameters:**

<Action>	0   1
<b>0</b>	The contents of the status registers are preserved.
<b>1</b>	Resets the status registers.

**\*RCL** <Number>

## Recall

Loads the instrument settings from an intermediate memory identified by the specified number. The instrument settings can be stored to this memory using the command [\\*SAV](#) with the associated number.

It also activates the instrument settings which are stored in a file and loaded using the `MMEemory:LOAD <number>, <file_name.extension>` command.

**\*RST**

## Reset

Sets the instrument to a defined default status. The default settings are indicated in the description of commands.

The command is equivalent to `SYSTEM:PRESet`.

**Usage:**                   Setting only

**\*SAV** <Number>

## Save

Stores the current instrument settings under the specified number in an intermediate memory. The settings can be recalled using the command [\\*RCL](#) with the associated number.

To transfer the stored instrument settings in a file, use the command `:MMEemory:STORe:STATe`.

**\*SRE** <Contents>

## Service request enable

Sets the service request enable register to the indicated value. This command determines under which conditions a service request is triggered.

**Parameters:**

<Contents>	Contents of the service request enable register in decimal form. Bit 6 (MSS mask bit) is always 0.
Range:	0 to 255

---

**\*STB?**

Status byte query

Reads the contents of the status byte in decimal form.

**Usage:** Query only

---

**\*TRG**

Trigger

Triggers all actions waiting for a trigger event. In particular, \*TRG generates a manual trigger signal. This common command complements the commands of the TRIGger subsystem.

**Usage:** Event

---

**\*WAI**

Wait to continue

Prevents servicing of the subsequent commands until all preceding commands have been executed and all signals have settled (see also command synchronization and \*OPC).

**Usage:** Event

---

## 11.3 General Commands

:REMOte:OPMode.....	139
:REStart.....	140
:STANdby.....	140
:LOCK?.....	140
:UNLock.....	140

---

**:REMOte:OPMode <OpMode>**

Sets the remote operation mode of the instrument.

**Parameters:**

&lt;OpMode&gt; STDalone | EXTension

**STDalone**

The instrument acts standalone.

**EXTension**

The instrument is controlled by another Rohde&amp;Schwarz instrument. This parameter is used by the SGMA-GUI to disable settings when the instrument is in extension mode.

**\*RST:** STDalone

---

**:REStart**

Restarts the instrument.

**Usage:** Event

---

**:STANdby**

Switches the instrument to the standby state. To return the instrument into the ready state, send the SCPI command `:REStart`.

**Usage:** Event

---

**:LOCK? <Lock Request Id>**

Sends a lock request ID which uniquely identifies the controller of the instrument.

**Parameters:**

<Lock Request Id> Number

**0**

test query to check whether the instrument is locked

**Controller ID**

request lock from the controller with the specified Controller ID

**Return values:**

<Value> Number

**0**

request refused; the instrument is already locked to another <Lock Request Id>, i.e. to another controller

**1**

request granted

**Example:** `:LOCK? 12345`

Response: 1

`:UNL 12345`

**Usage:** Query only

**Manual operation:** See "[Exclusive Access](#)" on page 51

---

**:UNLock <Unlock Id>**

Unlocks an instrument locked to a controller with Controller ID = <Unlock Id>.

**Setting parameters:**

<Unlock Id> Number

Unlock ID which uniquely identifies the controller of the instrument. The value must match the Controller ID <Lock Request Id> set with the command `:LOCK?`.

**Usage:** Setting only

**Manual operation:** See ["Exclusive Access"](#) on page 51

## 11.4 Preset Commands

The following preset actions are available:

- Activation of the default state of all internal instrument functions (`*RST` on page 138). Functions that concern the integration of the instrument into a measurement setup are not changed, e.g. TCP/IP address or remote operating mode.
- Activation of the original state of delivery (factory reset, `:SYSTem:FPReset` on page 141). Only functions that are protected by a password remain unchanged as well as the passwords themselves.

---

### **:SOURce<hw>:PRESet**

#### **:SYSTem:PRESet**

Triggers an instrument reset. It has the same effect as:

- The `*RST` command
- The "SGMA-GUI > Instrument Name > Preset" function

For an overview of the settings affected by the preset function, see [Chapter 7.7, "Preset"](#), on page 84.

**Example:**

```
SYST:PRES
```

All instrument settings (also the settings that are not currently active) are reset to their default values.

**Usage:**

Setting only

---

### **:SYSTem:FPReset**

The command triggers an instrument reset to the original state of delivery. Only functions that are protected by a password remain unchanged.

The factory preset function resets nearly all instrument settings. In addition to the regular preset a "Factory Preset" resets also the following values:

- Power on settings ("Level" dialog)
- Network settings including hostname ("Setup > Network Setting" dialog)
- Remote Channel settings ("Setup > Remote Channel" dialog)

For an overview of the settings affected by the factory preset function, see [Chapter 8.9, "Factory Preset"](#), on page 98.

**Example:**

```
SYST:FPR
```

all instrument settings (also those that are not currently active) are reset to the factory values.

**Usage:**

Event

**Manual operation:** See ["Execute Factory Preset"](#) on page 98

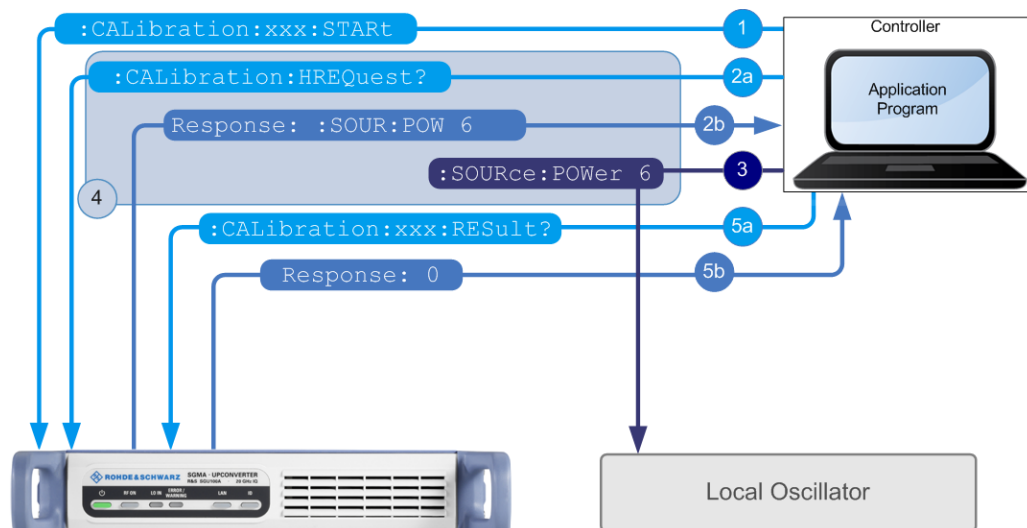
## 11.5 CALibration Subsystem

The CALibration system contains the commands needed for calibrating the R&S SGU.

R&S SGU cannot be calibrated on its own. Therefore a connection with a signal generator (local oscillator (LO)) is needed. If you use a compatible R&S signal generator, then the calibration process will be completed automatically after starting the calibration process. Otherwise you have to follow the steps described in "[Calibration process of the R&S SGU](#)" on page 142. We assume that a remote PC is connected to the instruments, the remote PC and the instruments are switched on and a connection between them is established.

The selftest of an R&S SGU also requires a similar instrumental setup. You can perform the selftest and read its results using the commands `:TEST:ALL:START` and `:TEST:ALL:RESULT?`.

### Calibration process of the R&S SGU



**Figure 11-1: Calibration process of the R&S SGU. No physical connections between the instruments are shown in this graphic.**

In order to complete the calibration process you have to complete the following steps:

1. Start an adjustment request with the SCPI command `:CALibration:xxx:START`, where `xxx` stands for `IQModulator`, `IQModulator:LOCal` or `LEVel`.
2. `:CALibration:HREQuest?`
  - a) Query R&S SGU for the required LO settings with the SCPI command `:CALibration:HREQuest?`.
  - b) Interpret the response of the query. The response is returned in the form of a SCPI command. For example a response `:SOUR:POW 6` asks for a power of 6 dBm. For a list of all possible responses see `:CALibration:HREQuest?` on page 144.

3. Set the LO according to the required settings.
4. Repeat steps 2 and 3 until the value of step 2b is :CALibration:HREQ:STOP.
5. :CALibration:xxx:RESult?  
xxx stands for IQModulator, IQModulator:LOCAl or LEVel
  - a) Query the result of the adjustment request with the SCPI command :CALibration:xxx:RESult?.
  - b) The query returns either 0 or 1 signifying pass or fail.

The instrument is calibrated and can be further used.

How the described process may take place is shown in [Table 11-1](#). If you use a compatible R&S signal generator the whole process will be completed automatically.

**Table 11-1: Programming example of a calibration process**

Local Oscillator/ Controller	R&S SGU Response	Interpretation
1):CALibration:LEVel:START	-	R&S SGU starts the Level Adjustment.
2):CALibration:HREQuest?	:PROG:CREate Level Adjustment	To do: create a progress bar with a caption "Level Adjustment".
3):CALibration:HREQuest?	:OUTP:STATe 1	To do: activate the RF output of the LO.
4):CALibration:HREQuest?	:PROG:UPDate 5	The progress of the level adjustment is 5 %.
5):CALibration:HREQuest?	:SOUR:FREQ 15e9; :SOUR:POW -10.0	To do: set the frequency of the LO to 15GHZ and its level to -10dBm
6):CALibration:HREQuest?	:SOUR:POW 5	To do: set the level of the LO to 5dBm.
7):CALibration:HREQuest?	:PROG:UPDate 20	The progress of the level adjustment is 20 %.
8):CALibration:HREQuest?	:SOUR:POW 20	To do: set the level of the LO to 5dBm.
9):CALibration:HREQuest?	:PROG:UPDate 100	The progress of the level adjustment is 100 %.
10):CALibration:HREQuest?	:PROG:REMOve	To do: delete the progress bar.
11):CALibration:HREQuest?	:OUTP:STATe 0	To do: deactivate the RF output of the LO.
12):CALibration:HREQuest?	:CAL:HREQ:STOP	End of the calibration process.

:CALibration:HREQuest?.....	144
:CALibration:IQModulator:START.....	144
:CALibration:IQModulator:RESult?.....	145
:CALibration:IQModulator:TEMPerature?.....	145
:CALibration:IQModulator:LOCAl:START.....	145
:CALibration:IQModulator:LOCAl:RESult?.....	145
:CALibration:LEVel:START.....	145
:CALibration:LEVel:RESult?.....	146
:CALibration:LEVel:TEMPerature?.....	146

**:CALibration:HREQuest?**

Queries the settings required from the instrument during a calibration or a selftest.

See "[Calibration process of the R&S SGU](#)" on page 142 for a step by step description of the calibration process.

**Return values:**

<Command>	string
	All of the commands described below return the values in the parameter's default unit.
<b>:VERsion &lt;Number&gt;</b>	Shows the command set version with which the instrument is compliant
<b>:OUTP:STATe &lt;Number&gt;</b>	Shows the state required of the local oscillator
<b>:SOUR:FREQ &lt;Number&gt;</b>	Shows the frequency required of the local oscillator
<b>:SOUR:POW&lt;Number&gt;</b>	Shows the power required of the external local oscillator
<b>:PROG:CREate &lt;Text&gt;</b>	Asks the controller to create a progress bar
<b>:PROG:REName &lt;Text&gt;</b>	Asks the controller to rename the progress bar
<b>:PROG:REMove</b>	Asks the controller to delete the most recently created progress bar
<b>:PROG:UPDate &lt;Number&gt;</b>	Shows the current progress value in percent
<b>:NOP/:NO DATA</b>	Intermediate message. No action is required
<b>:CAL:HREQ:STOP</b>	End of the calibration procedure

**Example:** See [Table 11-1](#).

**Usage:** Query only

**:CALibration:IQModulator:START**

Starts an internal I/Q adjustment. Query the result of the adjustment with the SCPI command `:CALibration:IQModulator:RESult?`.

See "[Calibration process of the R&S SGU](#)" on page 142 for a step by step description of the calibration process.

**Usage:** Event

---

**:CALibration:IQModulator:RESult?**

Queries the result of the internal I/Q adjustment. Start the adjustment with the SCPI command `:CALibration:IQModulator:START`.

**Return values:**

<Result> 0 | 1 | RUNning | STOPped

**Usage:** Query only

---

**:CALibration:IQModulator:TEMPerature?**

Queries the delta temperature since the last adjustment of the IQ modulator.

**Return values:**

<Temperature> string

**Usage:** Query only

---

**:CALibration:IQModulator:LOCal:START**

Starts an adjustment for the I/Q modulator of the current frequency. The I/Q modulator is adjusted with respect to carrier leakage, I/Q imbalance and quadrature. Query the result of the adjustment with the SCPI command `:CALibration:IQModulator:LOCal:RESult?`.

See "[Calibration process of the R&S SGU](#)" on page 142 for a step by step description of the calibration process.

**Usage:** Event

---

**:CALibration:IQModulator:LOCal:RESult?**

Queries the result of the I/Q modulation adjustment for the current frequency. Start the adjustment with the SCPI command `:CALibration:IQModulator:LOCal:START` on page 145.

**Return values:**

<Result> 0 | 1 | RUNning | STOPped

**Usage:** Query only

---

**:CALibration:LEVel:START**

Starts an internal level adjustment. Query the result of the adjustment with the SCPI command `:CALibration:LEVel:RESult?`.

See "[Calibration process of the R&S SGU](#)" on page 142 for a step by step description of the calibration process.

**Usage:** Event

---



**:CALibration:LEVel:RESult?**

Queries the result of the internal level adjustment. Start the adjustment with the SCPI command `:CALibration:LEVel:START`.

**Return values:**

<Result>                    0 | 1 | RUNning | STOPped

**Usage:**                    Query only

**:CALibration:LEVel:TEMPerature?**

Queries the delta temperature since the last level adjustment.

**Return values:**

<Temperature>            string

**Usage:**                    Query only

## 11.6 CONNector Subsystem

`:CONNector:TRIGger:OMODE`.....146

**:CONNector:TRIGger:OMODE <Mode>**

Sets the operating mode of the trigger connector.

**Parameters:**

<Mode>                    SVALid | SNValid | PEMSource

**SVALid|SNValid**

signal valid /not valid

**PEMSource**

external pulse modulator source

**Manual operation:** See "[Trigger Connector Mode](#)" on page 82

## 11.7 DIAGnostic Subsystem

`:DIAGnostic:POINt:CATalog?`..... 146

`:DIAGnostic[:MEASure]:POINt?`..... 147

**:DIAGnostic:POINt:CATalog?**

Queries the test points available in the instrument.

For description of the test points, see the service manual.

**Example:**                    See [Chapter 11.1.1, "Performing General Tasks for Instrument Setup"](#), on page 130.

**Usage:** Query only

---

**:DIAGnostic[:MEASure]:POINT? <Name>**

Triggers a voltage or a temperature measurement at the specified test point and returns the measured value.

Use the command `:DIAGnostic:POINT:CATalog?` to retrieve a list of the available test points.

For description of the test points, see the service manual.

**Query parameters:**

<Name> string

**Return values:**

<Value> number  
Default unit: V or °C

**Example:** See [Chapter 11.1.1, "Performing General Tasks for Instrument Setup"](#), on page 130.

**Usage:** Query only

## 11.8 Fast Speed Commands

This section describes special commands that allow a fast frequency and level setting.

[:FFASt](#)..... 147  
[:PFASt](#)..... 147

---

**:FFASt <Freq>**

Special command to set the RF output frequency with minimum latency. No unit (e.g. Hz) allowed.

Bypasses the status system so command `*OPC?` cannot be appended.

**Parameters:**

<Freq> float

**Example:** `FFASt 1275000000`

---

**:PFASt <Pow>**

Special command to set the RF output level with minimum latency at the RF output connector. This value does not consider a specified offset. No unit (e.g. dBm) allowed.

Bypasses the status system so command `*OPC?` cannot be appended.

**Parameters:**

<Pow> float

**Example:** `:PFASt -20`

## 11.9 FORMat Subsystem

The `FORMat` subsystem contains the commands which determine the format of the data that the R&S SGU returns to the controller. This affects all query commands which return a list of numerical data or block data. Reference is made to this in the descriptions of the commands.

<code>:FORMat:BORDER</code> .....	148
<code>:FORMat[:DATA]</code> .....	148
<code>:FORMat:SREGister</code> .....	149

---

### **:FORMat:BORDER** <Border>

Determines the sequence of bytes within a binary block. This only affects blocks which use the IEEE754 format internally.

**Parameters:**

<Border>                    `NORMal` | `SWAPped`

**NORMal**

The instrument expects (with setting commands) and sends (with queries) the least significant byte of each IEEE754 floating-point number first and the most significant byte last.

**SWAPped**

The instrument expects (with setting commands) and sends (with queries) the most significant byte of each IEEE754 floating-point number first and the least significant byte last.

\*RST:            `NORMal`

**Example:**            `FORM:BORD SWAP`

The data is transferred with the most significant bit first.

---

### **:FORMat[:DATA]** <Data>

Determines the data format which the R&S SGU uses to return data. When data is transferred from the control computer to the instrument, the instrument detects the data format automatically. In this case, the value set here is irrelevant.

**Parameters:**

<Data>	ASCIi   PACKed
	<b>ASCIi</b> Numerical data is transferred as plain text separated by commas.
	<b>PACKed</b> Numerical data is transferred as binary block data. The format within the binary data depends on the command. The various binary data formats are explained in the description of the parameter types.
	*RST:       ASCIi

**Example:**

FORM ASC  
The data is transferred as ASCII data.

**:FORMat:SREGister** <Format>

Determines the numerical format which is returned when the status registers are queried.

**Parameters:**

<Format>	ASCIi   BINary   HEXadecimal   OCTal
	<b>ASCIi</b> The register content is returned as a decimal number.
	<b>BINary</b> The register content is returned as a binary number. #B is placed in front of the number.
	<b>HEXadecimal</b> The register content is returned as a hexadecimal number. #H is placed in front of the number.
	<b>OCTal</b> The register content is returned as an octal number. #Q is placed in front of the number.
	*RST:       ASCIi

**Example:**

FORM:SREG HEX  
The register content is returned as a hexadecimal number.

## 11.10 MMEMory Subsystem

The MMEMory subsystem (**Mass Memory**) contains the commands for managing files and directories as well as for loading and storing complete instrument settings in files.

The files are stored on the internal flash memory of the instrument or on external USB memory devices.

The default directory is determined using the command `MMEMory:CDIR`.



Use the command `:SYSTem:MMEMory:PATH:USER?` to query the path of the directory for user-defined data.



The `/opt` directory is a protected and therefore a not accessible system directory. The files on this directory contain data that must not be changed. Therefore, this directory should not be accessed, since reconstruction of the system partition will lead to data loss.

### 11.10.1 File Naming Conventions

To enable files in different file systems to be used, the following file naming conventions should be observed.

The file name can be of any length and is case-sensitive, meaning it is distinguished between uppercase and lowercase letters.

The file and the optional file extension are separated by a dot. All letters and numbers are permitted (numbers are, however, not permitted at the beginning of the file name). If possible, special characters should not be used. The use of the slashes "\" and "/" should be avoided since they are used in file paths. A number of names are reserved for the operating system, e.g. `CLOCK$`, `CON`, `AUX`, `COM1 . . . COM4`, `LPT1 . . . LPT3`, `NUL` and `PRN`.

In the R&S SGU all files in which lists and settings are stored are given a characteristic extension. The extension is separated from the actual file name by a dot (see [Chapter 11.10.2, "Extensions for User Files"](#), on page 151 for an overview of the file types).

The two characters "\*" and "?" function as "wildcards", meaning they are used for selecting several files. The "?" character represents exactly one character, while the "\*" character represents all characters up to the end of the file name. "\*. \*" therefore stands for all files in a directory.

When used in conjunction with the commands, the parameter `<file_name>` is specified as a string parameter with quotation marks. It can contain either the complete path including the drive, only the path and the file name, or only the file name. The file name must include the file extension. The same applies for the parameters `<directory_name>` and `<path>`.

Depending on how much information is provided, either the values specified in the parameter or the values specified with the command `MMEM:CDIR` (default directory) are used for the path and the drive settings in the commands.

Before the instrument settings can be stored in a file, they have to be stored in an intermediate memory using common command `*SAV <number>`. The specified number is subsequently used in the `:MMEMory:STORe:STATe` on page 157 command. Also, subsequently to loading a file with instrument settings with command `:MMEMory:LOAD:STATe` on page 156, these settings have to be activated with the common command `*RCL <number>`.

## 11.10.2 Extensions for User Files

The following table lists all available file extensions for user files.

**Table 11-2: Automatically assigned file extensions in the instrument**

Function	Contents	File suffix
R&S SGMA-GUI Save As/Open	Software settings	*.savrcl

## 11.10.3 Examples

In these examples, the current instrument setting is stored in the file `test.savrcltxt` in the directory `/var/user/..`

### Storing and Loading Current Settings

1. Store the current setting in an intermediate memory with the number 4. This setting can be called using command `*RCL` and the associated number of the memory, for example `*RCL 4`.  
`*SAV 4`
2. To store the settings in a file in a specific directory, specify the complete path.  
`MMEM:STOR:STAT 4, "/var/user/test.savrcltxt"`
3. To store the settings in a file in the default drive, set the default drive and specify only the file name.  
`MMEM:CDIR '/var/user/'*SAV 4`  
`MMEM:STOR:STAT 4, "test.savrcltxt"`
4. Load the file `test.savrcltxt` in the user directory.  
`MMEM:LOAD:STAT 4, '/var/user/test.savrcltxt'`
5. Activate the instrument setting of the file `test.savrcltxt`.  
`*RCL 4`

### Working with Files and Directories

1. Read out all files in the specified directory.  
`MMEM:CAT? '/usb/user'`  
  
**Response:** `127145265,175325184,"test,DIR,0","temp,DIR,0",  
"readme.txt,ASC,1324","state.savrcltxt,STAT,5327",  
"waveform.wv,BIN,2342"`  
  
the directory `/usb/user` contains the subdirectories `test` and `temp` as well as the files `readme.txt`, `state.savrcltxt` and `waveform.wv` which have different file types.  
  
**Tip:** To query only the subdirectories of the current or specified directory, perform:  
`MMEM:DCAT? '/usb/user'`  
  
**Response:** `'test', 'temp'`



**Return values:**

<UsedDiskSpace>	Byte size of all files in the directory.
<FreeDiskSpace>	Remaining disk space in bytes.
<FileInfo>	<NameFileN>,<SuffixFileN>,<SizeFileN> List of files, separated by commas <b>&lt;NameFileN&gt;</b> Name of the file. <b>&lt;SuffixFileN&gt;</b> Type of the file. Possible suffixes are: ASCii, BINary, DIRectory <b>&lt;SizeFileN&gt;</b> Size of the file in bytes.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Query only

**:MMEMory:CATalog:LENGth? <Path>**

Returns the number of files in the current or in the specified directory.

**Query parameters:**

<Path>	string String parameter to specify the directory. If the directory is omitted, the command queries the content of the current directory, queried with <code>:MMEMory:CDIRectory</code> command.
--------	--

**Return values:**

<FileCount>	integer Number of files.
-------------	-----------------------------

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Query only

**:MMEMory:CDIRectory <Directory>**

Changes the default directory for mass memory storage. The directory is used for all subsequent `MMEM` commands if no path is specified with them.

**Parameters:**

<Directory>	<directory_name> String containing the path to another directory. The path can be relative or absolute. To change to a higher directory, use two dots '..' .
-------------	--

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** SCPI confirmed



---

**:MMEMory:COPY** <SourceFile>[,<DestinationFile>]

Copies an existing file to a new file. Instead of just a file, this command can also be used to copy a complete directory together with all its files.

**Setting parameters:**

<SourceFile>            string  
String containing the path and file name of the source file

<DestinationFile>    string  
String containing the path and name of the target file. The path can be relative or absolute.  
If <DestinationFile> is not specified, the <SourceFile> is copied to the current directory, queried with the **:MMEMory:CDIRectory** command.

**Note:** Existing files with the same name in the destination directory are overwritten without an error message.

**Example:**            See "[Working with Files and Directories](#)" on page 151.

**Usage:**              Setting only  
SCPI confirmed

---

**:MMEMory:DATA** <Filename>, <BinaryBlock>

**:MMEMory:DATA?** <Filename>

The setting command writes the block data <BinaryBlock> to the file identified by <Filename>.

**Tip:** Use this command to read/transfer stored instrument settings or waveforms directly from/to the instrument.

**Parameters:**

<BinaryBlock>        #<number><length\_entry><data>  
#: Hash sign; always comes first in the binary block  
<number>: the first digit indicates how many digits the subsequent length entry has  
<length\_entry>: indicates the number of subsequent bytes  
<data>: binary block data for the specified length.  
For files with a size with more than nine digits (gigabytes), the instrument allows the syntax # (<Length>), where <Length> is the file size in decimal format.

**Parameters for setting and query:**

<Filename>            string  
String parameter to specify the name of the file.

**Example:** `MMEMory:DATA '/var/user/test.txt',#15hallo`  
 Writes the block data to the file `test.txt`.  
 The digit 1 indicates a length entry of one digit; the digit 5 indicate a length of the binary data (`hallo`) in bytes.  
`MMEMory:DATA? '/var/user/test.txt'`  
 Sends the data of the file `test.txt` from the instrument to the controller in the form of a binary block.  
 Response: `#15hallo`

**Usage:** SCPI confirmed

### **:MMEMory:DCATalog? <path>**

Returns the subdirectories of a particular directory.

#### **Query parameters:**

<path> String parameter to specify the directory. If the directory is omitted, the command queries the content of the current directory, queried with `:MMEMory:CDIRectory` command.

#### **Return values:**

<Catalog> <file\_entry>  
 Names of the subdirectories separated by colons. The first two strings are related to the parent directory.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Query only

### **:MMEMory:DCATalog:LENGth? [<Path>]**

Returns the number of subdirectories in the current or specified directory.

#### **Query parameters:**

<Path> String parameter to specify the directory. If the directory is omitted, the command queries the contents of the current directory, to be queried with `:MMEMory:CDIRectory` command.

#### **Return values:**

<DirectoryCount> integer  
 Number of parent and subdirectories.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Query only

### **:MMEMory:DELete <Filename>**

Removes a file from the specified directory.

**Setting parameters:**

<Filename> string  
String parameter to specify the name and directory of the file to be removed.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Event  
SCPI confirmed

**:MEMory:HFRee?**

Returns the used and available memory in Kb.

**Return values:**

<TotalPhysMemKb> integer  
Total physical memory.

<ApplicMemKb> integer  
Application memory.

<HeapUsedKb> integer  
Used heap memory.

<HeapAvailableKb> integer  
Available heap memory.

**Usage:** Query only

**:MMEMory:LOAD:STATe <SavRclStateNumb>, <file\_name>**

Loads the specified file stored under the specified name in an internal memory.

After the file has been loaded, the instrument setting must be activated using an \*RCL command.

**Setting parameters:**

<SavRclStateNumb> Determines to the specific <number> to be used with the \*RCL command, e.g. \*RCL 4.

<file\_name> String parameter to specify the file name with extension \*.savrc1.txt.

**Example:** See "[Storing and Loading Current Settings](#)" on page 151.

**Usage:** Setting only

**:MMEMory:MDIRectory <Directory>**

Creates a subdirectory for mass memory storage in the specified directory. If no directory is specified, a subdirectory is created in the default directory. This command can also be used to create a directory tree.

**Setting parameters:**

<Directory> string  
String parameter to specify the new directory.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Event

**:MMEMory:MOVE** <SourceFile>, <DestinationFile>

Moves an existing file to a new location or, if no path is specified, renames an existing file.

**Setting parameters:**

<SourceFile> string  
String parameter to specify the name of the file to be moved.

<DestinationFile> string  
String parameters to specify the name of the new file.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Event  
SCPI confirmed

**:MMEMory:MSIS** <Msis>

Defines the drive or network resource (in the case of networks) for instruments with windows operating system, using `msis` (MSIS = Mass Storage Identification String).

**Note:** Instruments with Linux operating system ignore this command, since Linux does not use drive letter assignment.

**Usage:** SCPI confirmed

**:MMEMory:RDIrectory** <Directory>

Removes an existing directory from the mass memory storage system. If no directory is specified, the subdirectory with the specified name is deleted in the default directory.

**Setting parameters:**

<Directory> string  
String parameter to specify the directory to be deleted.

**Example:** See "[Working with Files and Directories](#)" on page 151.

**Usage:** Event

**:MMEMory:STORE:STATE** <savrcl\_state\_nr>, <file\_name>

Stores the current instrument setting in the specified file.

The instrument setting must first be stored in an internal memory with the same number using the common command \*SAV.

**Setting parameters:**

<savrcl\_state\_nr> Corresponds to the specific <number> defined with the \*SAV command, e.g. \*SAV 4.

<file\_name> String parameter to specify the file name with extension \*.savrcltxt.

**Example:** See "Storing and Loading Current Settings" on page 151.

**Usage:** Event

## 11.11 OUTPut Subsystem

:OUTPut:AMODE.....	158
:OUTPut[:STATe].....	158
:OUTPut[:STATe]:PON.....	159
:OUTPut:AFIXed:RANGe:LOWer?.....	159
:OUTPut:AFIXed:RANGe:UPPer?.....	159
:OUTPut<hw>:PROTection:CLEar.....	159

---

### :OUTPut:AMODE <AMode>

Sets the mode of the attenuator (**A**ttenuator **MO**De) at the RF output.

**Parameters:**

<AMode> AUTO | FIXed

**AUTO**

The attenuator is switched automatically. The level settings are made in the full range.

**FIXed**

The level settings are made without switching the attenuator. When this operating mode is switched on, the attenuator is fixed to its current position and the resulting variation range is defined.

\*RST: AUTO

**Manual operation:** See "Mode" on page 74

---

### :OUTPut[:STATe] <State>

Activates/deactivates the RF output.

**Parameters:**

<State> 0 | 1 | OFF | ON

**Example:** See Chapter 11.1.2, "Generating an I/Q Modulated Signal", on page 131.

**Manual operation:** See "RF On/Off" on page 57

---

**:OUTPut[:STATe]:PON <Mode>**

Selects the state which the RF output takes when the instrument is switched on.

**Parameters:**

<Mode> OFF | UNCHanged

**OFF**

When the instrument is switched on, the output is deactivated .

**UNCHanged**

When the instrument is switched on, the output remains in the same state as it was before the instrument was switched off.

\*RST: UNCHanged

**Example:** See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131 .

**Manual operation:** See "[Power-On State](#)" on page 75

---

**:OUTPut:AFIXed:RANGe:LOWer?**

Queries the minimum level which can be set without the attenuator being adjusted.

**Return values:**

<Lower> float

Default unit: dBm

**Example:** See [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133.

**Usage:** Query only

**Manual operation:** See "[Level Range](#)" on page 74

---

**:OUTPut:AFIXed:RANGe:UPPer?**

Queries the maximum level which can be set without the attenuator being adjusted.

**Return values:**

<Upper> float

Default unit: dBm

**Example:** See [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133 .

**Usage:** Query only

**Manual operation:** See "[Level Range](#)" on page 74

---

**:OUTPut<hw>:PROTection:CLEar**

Resets the protective circuit after it has been tripped. The state of the output is again determined by `OUTPut:STATe`.

**Example:**            `OUTP:PROT:CLE`  
resets the protective circuit for RF output.

**Usage:**             Event

## 11.12 SOURce Subsystem

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---

### **[\[:SOURce\]:SETTings:APPLY\[:IMMediate\]](#)**

Applies the signal settings and outputs the signal.

See [Chapter 11.14, "SOURce:Local Oscillator Subsystem"](#), on page 163 for a description of the setting process.

**Usage:**             Event

**Manual operation:** See ["Confirm External LO Settings"](#) on page 83

---

### **[\[:SOURce\]:FREQuency\[:CW|FIXed\] <Cw>](#)**

Sets the RF frequency at the RF output connector of the instrument.

#### **Parameters:**

<Cw>                    float  
                           Range:     1E+6 to 40E+9  
                           Increment: 1E-3  
                           \*RST:     1E+9

**Example:**            See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131.

**Manual operation:** See ["Frequency"](#) on page 57

---

### **[\[:SOURce\]:TRAits<ch>](#)**

Queries for a list of values for the corresponding trait. The following values values are available for the channel number:

- 1: queries the upper edge frequencies for the frequency bands
- 2: queries the upconverter frequency multiplication factors for each band
- 3: queries if the bypass mode is active for each band
- 4: queries the pulsmodulation performed in LO for each band
- 5: queries the AM signal allowed for each band
- 6: queries the PM / PhiM signal allowed for each band

**[:SOURce]:TRAits:COUNT?**

Queries the number of trait lists.

**Return values:**

<Count> float

**Usage:** Query only

## 11.13 SOURce:IQ Subsystem

The IQ Impairment remote commands are available only for R&S SGU-B120V/-B140V.

<a href="#">[:SOURce]:IQ:STATE</a> .....	161
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<a href="#">[:SOURce]:IQ:IMPAirment:QUADrature[:ANGLE]</a> .....	162
<a href="#">[:SOURce]:IQ:IMPAirment:STATE</a> .....	162
<a href="#">[:SOURce]:IQ:CREStfactor</a> .....	163

**[:SOURce]:IQ:STATE <State>**

Switches the I/Q modulation on and off.

**Parameters:**

<State> 0 | 1 | OFF | ON  
\*RST: 0

**Example:** See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131.

**Options:** R&S SGU-B120V/-B140V

**Manual operation:** See ["Mod State"](#) on page 57

**[:SOURce]:IQ:IMPAirment:IQRatio <IqRatio>**

Sets the ratio of I modulation to Q modulation (gain "imbalance"). The input may be either in dB or %. An input in percent is rounded to the closest valid value in dB. A query returns the value in dB.

**Parameters:**

<IqRatio> float  
Range: -1 to 1  
Increment: 1E-3  
\*RST: 0

**Example:** See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131.

**Options:** R&S SGU-B120V/-140V



**Manual operation:** See ["Gain Imbalance"](#) on page 81

**[:SOURce]:IQ:IMPairment:LEAKage:I** <I>  
**[:SOURce]:IQ:IMPairment:LEAKage:Q** <Q>

Sets the carrier leakage amplitude for the I-/Q-signal component.

**Parameters:**

<Q> float  
 Range: -5 to 5  
 Increment: 0.01  
 \*RST: 0  
 Default unit: PCT

**Example:** See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131.

**Options:** R&S SGU-B120V/-B140V

**Manual operation:** See ["Offset"](#) on page 80

**[:SOURce]:IQ:IMPairment:QUADrature[:ANGLE]** <Angle>

Sets the quadrature offset for the digital I/Q signal.

**Parameters:**

<Angle> float  
 Range: -8 to 8  
 Increment: 0.01  
 \*RST: 0  
 Default unit: DEG

**Example:** See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131.

**Options:** R&S SGU-B120V/-B140V

**Manual operation:** See ["Quadrature Offset"](#) on page 81

**[:SOURce]:IQ:IMPairment:STATe** <State>

Activates/deactivates the impairment or correction values LEAKage, QUADrature and IQRatio for the baseband signal prior to input to the I/Q modulator.

**Parameters:**

<State> 0 | 1 | OFF | ON  
 \*RST: 0

**Example:** See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#), on page 131.

**Options:** R&S SGU-B120V/-B140V

**Manual operation:** See ["State"](#) on page 80

---

**[[:SOURce]:IQ:CREStfactor <Crest>**

Sets the crest factor of the I/Q modulation signal.

**Parameters:**

<Crest>                      float  
                                   Range:        0 to 35  
                                   Increment: 0.01  
                                   \*RST:        0  
                                   Default unit: dB

**Example:**                    See [Chapter 11.1.2, "Generating an I/Q Modulated Signal"](#),  
 on page 131

**Manual operation:**    See ["Crest Factor"](#) on page 79

## 11.14 SOURce:Local Oscillator Subsystem

### R&S SGU as an extension to a compatible R&S signal generator

If a R&S SGU is connected to a compatible R&S signal generator the R&S SGU acts as an extension to the signal generator extending its frequency range. In this setup a controller does not need to access the R&S SGU directly. Instead, the signal generator acts as a controller to the R&S SGU and depending on the required output signal parameters performs all required settings automatically.

For example, if the signal generator is set to an output frequency of 15 GHz it passes this value on to the R&S SGU. On reception of the new frequency R&S SGU blanks its output and computes the necessary settings for the local oscillator (signal generator). Next, the signal generator queries R&S SGU for the required frequency and level values of the local oscillator, which answers with for example 7.5 GHz and -10 dBm. The signal generator applies these settings to its own oscillator hardware and confirms that the required signal is now present at its output connector by sending the apply command to the R&S SGU. The R&S SGU unblanks its own output thus finishing the cycle.

### R&S SGU as an upconverter for any signal generator

If, on the other hand, the R&S SGU is connected to an incompatible signal generator the controller has to perform the above steps instead of the signal generator. We assume that a remote PC (controller) is connected to both the R&S SGU and the signal generator (local oscillator). When changing any parameters which affect the output signal of the combined system of local oscillator and R&S SGU the controller has to follow these steps:

#### Setting the signal of the R&S SGU

1. Set the parameters of the R&S SGU like frequency and level as needed.

2. Query the local oscillator frequency and the local oscillator level from R&S SGU with the SCPI commands `[ :SOURce ] :LOSCillator:FREQuency?` and `[ :SOURce ] :LOSCillator:POWer?`.
3. Interpret the result and apply the required changes to the LO.
4. Send the SCPI command `[ :SOURce ] :SETTings:APPLy [ :IMMediate ]` to R&S SGU to output the signal.

See [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133 for an example.

<code>[ :SOURce ] :LOSCillator:FREQuency?</code> .....	164
<code>[ :SOURce ] :LOSCillator:POWer?</code> .....	164

---

### `[ :SOURce ] :LOSCillator:FREQuency?`

Queries the frequency of the local oscillator input signal.

See [Chapter 11.14, "SOURce:Local Oscillator Subsystem"](#), on page 163 for a description of the setting process.

#### Return values:

<Frequency>	float
	Range: 1E+6 to 20E+9
	Increment: 1E-3
	*RST: 1E+9

**Usage:** Query only

**Manual operation:** See ["Frequency"](#) on page 83

---

### `[ :SOURce ] :LOSCillator:POWer?`

Queries the level of the local oscillator input signal.

See [Chapter 11.14, "SOURce:Local Oscillator Subsystem"](#), on page 163 for a description of the setting process.

#### Return values:

<Amplitude>	float
	Range: -120 to 25
	Increment: 0.01
	*RST: -10

**Usage:** Query only

**Manual operation:** See ["Level"](#) on page 83

## 11.15 SOURce:POWer Subsystem

<code>[:SOURce]:POWer:ALC[:STATe]</code> .....	165
<code>[:SOURce]:POWer:ALC:DSENSitivity</code> .....	165
<code>[:SOURce]:POWer:ALC:SONCe</code> .....	165
<code>[:SOURce]:POWer:ATTenuation:RFOff:MODE</code> .....	165
<code>[:SOURce]:POWer:ATTenuation:SOVer[:OFFSet]</code> .....	166
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<code>[:SOURce]:POWer:RANGe:LOWer?</code> .....	168
<code>[:SOURce]:POWer:RANGe:UPPer?</code> .....	168

---

### `[:SOURce]:POWer:ALC[:STATe]` <State>

Activates/deactivates the automatic level control.

**Parameters:**

<State>                    1 | OFFTable | ONTable | ON  
 \*RST:                    ONTable

**Manual operation:**    See "[State](#)" on page 76

---

### `[:SOURce]:POWer:ALC:DSENSitivity` <Sensitivity>

Sets the sensitivity of the power detector.

**Parameters:**

<Sensitivity>            OFF | LOW | MED | HIGH  
 \*RST:                    OFF

---

### `[:SOURce]:POWer:ALC:SONCe`

Briefly activates automatic level control for correction purposes.

**Usage:**                    Event

**Manual operation:**    See "[Readjust](#)" on page 73

---

### `[:SOURce]:POWer:ATTenuation:RFOff:MODE` <Mode>

Selects the state which the attenuator assumes when the instrument is switched on.

**Parameters:**

<Mode>                    MAX | FIXed  
 \*RST:                    MAX

**Manual operation:** See ["RF-Off-Mode"](#) on page 74

---

**[:SOURce]:POWer:ATTenuation:SOVer[:OFFSet] <Offset>**

Sets the switch-over offset value of the attenuator.

**Parameters:**

<Offset> float  
\*RST: 0

**Manual operation:** See ["SATT Switch-Over Offset"](#) on page 74

---

**[:SOURce]:POWer:LMODe <LevMode>**

Selects the level mode.

**Parameters:**

<LevMode> NORMal | LNOise | LDISTortion  
**NORMal**  
automatic selection of the best settings  
**LNOISE**  
settings for lowest noise  
**LDISTortion**  
settings for lowest distortions  
\*RST: NORMal

**Example:** see [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133

**Manual operation:** See ["Mode"](#) on page 72

---

**[:SOURce]:POWer:SCHaracteristic <Characteristic>**

Selects the characteristic for the level setting.

**Parameters:**

<Characteristic> AUTO | UNINterrupted | CVSWr | USER | MONotone  
UNINterrupted: Uninterrupted Level setting, CVSWr: Constant-VSWR, MONotone: Strictly Monotone  
\*RST: AUTO

**Example:** see [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133

**Manual operation:** See ["Setting Characteristic"](#) on page 72

---

**[:SOURce]:POWer[:LEVel][:IMMediate][:AMPLitude] <Amplitude>**

Sets the RF level at the RF output connector of the instrument.

**Parameters:**

<Amplitude> float  
 Range: -120 to 25  
 Increment: 0.01  
 \*RST: -10

**Example:** See [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133.

**Manual operation:** See ["Level/Level Offset"](#) on page 57

**[ :SOURce]:POWer[:LEVel][:IMMEdiate]:OFFSet <Offset>**

Specifies the constant level offset of a downstream attenuator/amplifier. If a level offset is entered, the level entered with `[ :SOURce]:POWer:POWer` no longer corresponds to the RF output level.

The following correlation applies:

`:POWer = RF output level + POWer:OFFSet.`

Entering a level offset does not change the RF output level, but rather the query value of `:POWer`.

Only dB is permitted as the unit here. The linear units (V, W, etc.) are not permitted.

**Parameters:**

<Offset> float  
 Range: -100 to 100  
 Increment: 0.1  
 \*RST: 0

**Manual operation:** See ["Offset"](#) on page 72

**[ :SOURce]:POWer:LIMit[:AMPLitude] <Amplitude>**

Sets the upper limit of the RF signal power.

The value is not affected by an instrument preset and \*RST function. This parameter is influenced only by the factory preset (`SYST:FPR`) and its factory value is equal to the upper limit.

**Parameters:**

<Amplitude> float  
 Range: -300 to 30  
 Increment: 0.01  
 Default unit: dBm

**Manual operation:** See ["Limit"](#) on page 73

**[ :SOURce]:POWer:PEP?**

Queries the RF signal's peak envelope power at the DUT.

**Return values:**

<PEP> float  
 Range: -120 to 25  
 Increment: 0.01  
 \*RST: -10

**Example:** see [Chapter 11.1.3, "Advanced Task for Optimizing Performance"](#), on page 133

**Usage:** Query only

**Manual operation:** See ["PEP"](#) on page 57

**[:SOURce]:POWer:POWer <Power>**

Sets the level at the RF output connector.

This value does not consider a specified offset. The command `[ :SOURce ] :POWer [ :LEVel ] [ :IMMediate ] :OFFSet` sets the level of the "Level" display, that means the level containing offset.

**Parameters:**

<Power> float  
 Range: -120 to 25  
 Increment: 0.01  
 \*RST: -10

**Example:** `POW:POW 15`  
 sets the RF level at output to 15 dBm.

**Manual operation:** See ["Level/Level Offset"](#) on page 57

**[:SOURce]:POWer:RANGe:LOWer?****[:SOURce]:POWer:RANGe:UPPer?**

Queries the minimum/maximum level range in the current level mode

**Return values:**

<Upper> float  
 Range: -300 to 30  
 Increment: 0.01  
 \*RST: 30

**Usage:** Query only

**Manual operation:** See ["Level Range"](#) on page 73

## 11.16 SOURce:PULM Subsystem

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<a href="#">[:SOURce&lt;hw&gt;]:PULM:POLarity.....</a>	169

**[:SOURce<hw>]:PULM:STATe <State>**

Activates the pulse modulation.

**Parameters:**

<State>                    0 | 1 | OFF | ON  
 \*RST:                    0

**Example:**                    PULM:STAT ON  
 activates pulse modulation.

**Manual operation:**    See "State" on page 82

**[:SOURce<hw>]:PULM:POLarity <Polarity>**

Sets the polarity of the pulse modulator signal. This command is effective only for an external modulation signal.

**Parameters:**

<Polarity>                    NORMal | INVerted

**NORMal**

The RF signal is suppressed during the pulse pause.

**INVerted**

The RF signal is suppressed during the pulse.

\*RST:                    NORMal

**Example:**                    PULM:POL INV  
 selects inverted polarity.

**Manual operation:**    See "Polarity" on page 82

## 11.17 STATus Subsystem

This system contains the commands for the status reporting system. See also [Chapter A.5, "Status Reporting System"](#), on page 206 for detailed information.

\*RST on page 138 has no effect on the status registers.

**Value ranges**

- Queries return the current value of the respective register, which permits a check of the device status.  
Return values: A decimal value in the range 0 to 32767 ( $=2^{15}-1$ )
- The configuration commands set the respective register thus determining which status changes of the R&S SGU cause the status registers to be changed.  
Setting values: A decimal value in the range 0 to 32767 ( $=2^{15}-1$ )

:STATus:OPERation:CONDition..... 170  
 :STATus:OPERation:ENABLE..... 170  
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:STATus:PRESet.....	171
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:STATus:QUEStionable:NTRansition.....	172
:STATus:QUEStionable:PTRansition.....	172
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---

#### :STATus:OPERation:CONDition <Condition>

Sets the content of the CONDition part of the STATus:OPERation register. This part contains information on the action currently being performed in the instrument. The content is not deleted after being read out because it indicates the current hardware status.

##### Parameters:

<Condition>                    string

##### Example:

```
:STATus:OPERation:CONDition?
queries the Status:Operation:Condition register.
```

---

#### :STATus:OPERation:ENABle <Enable>

Sets the bits of the ENABle part of the STATus:OPERation register. This setting determines which events of the Status-Event part are forwarded to the sum bit in the status byte. These events can be used for a service request.

##### Parameters:

<Enable>                        string

##### Example:

```
:STAT:OPER:ENAB 32767
all events are forwarded to the sum bit of the status byte.
```

---

#### :STATus:OPERation[:EVENT] <Event>

Queries the content of the EVENT part of the STATus:OPERation register. This part contains information on the actions performed in the instrument since the last readout. The content of the EVENT part is deleted after being read out.

##### Parameters:

<Event>                         string

##### Example:

```
:STAT:OPER:EVENT?
queries the STATus:OPERation:EVENT register.
```

**:STATus:OPERation:NTRansition** <Ntransition>

Sets the bits of the NTRansition part of the STATus:OPERation register. If a bit is set, a transition from 1 to 0 in the condition part causes an entry to be made in the EVENT part of the register. The disappearance of an event in the hardware is thus registered, for example the end of an adjustment.

**Parameters:**

<Ntransition>            string

**Example:**

`:STAT:OPER:NTR 0`

a transition from 1 to 0 in the condition part of the Status:Operation register does not cause an entry to be made in the EVENT part.

**:STATus:OPERation:PTRansition** <Ptransition>

Sets the bits of the PTRansition part of the STATus:OPERation register. If a bit is set, a transition from 0 to 1 in the condition part causes an entry to be made in the EVENT part of the register. A new event in the hardware is thus registered, for example the start of an adjustment.

**Parameters:**

<Ptransition>            string

**Example:**

`:STAT:OPER:PTR 32767`

all transitions from 0 to 1 in the condition part of the Status:Operation register cause an entry to be made in the EVENT part.

**:STATus:PRESet** <Preset>

Resets the status registers. All PTRansition parts are set to FFFFh (32767), i.e. all transitions from 0 to 1 are detected. All NTRansition parts are set to 0, i.e. a transition from 1 to 0 in a CONDition bit is not detected. The ENABLE parts of STATus:OPERation and STATus:QUEStionable are set to 0, i.e. all events in these registers are not passed on.

**Parameters:**

<Preset>                string

**Example:**

`STAT:PRES`

resets the status registers.

**:STATus:QUEStionable:CONDition** <Condition>

Queries the content of the CONDition part of the STATus:QUEStionable register. This part contains information on the action currently being performed in the instrument. The content is not deleted after being read out since it indicates the current hardware status.

**Parameters:**

<Condition>            string

**Example:** `:STATus:QUEStionable:CONDition?`  
queries the Status:Questionable:Condition register.

#### **:STATus:QUEStionable:ENABle <Enable>**

Sets the bits of the ENABle part of the STATus:QUEStionable register. This setting determines which events of the Status-Event part are enabled for the sum bit in the status byte. These events can be used for a service request.

**Parameters:**

<Enable>                    string

**Example:** `STAT:OPER:ENAB 1`  
problems when performing an adjustment cause an entry to be made in the sum bit.

#### **:STATus:QUEStionable[:EVENT] <Event>**

Queries the content of the EVENT part of the STATus:QUEStionable register. This part contains information on the actions performed in the instrument since the last readout. The content of the EVENT part is deleted after being read out.

**Parameters:**

<Event>                    string

**Example:** `STAT:QUES:EVEN?`  
queries the Status:Questionable:Event register.

#### **:STATus:QUEStionable:NTRansition <Ntransition>**

Sets the bits of the NTRansition part of the STATus:QUEStionable register. If a bit is set, a transition from 1 to 0 in the condition part causes an entry to be made in the EVENT part of the register.

**Parameters:**

<Ntransition>            string

**Example:** `STAT:OPER:NTR 0`  
a transition from 1 to 0 in the condition part of the Status:Questionable register does not cause an entry to be made in the EVENT part

#### **:STATus:QUEStionable:PTRansition <PTransition>**

Sets the bits of the PTRansition part of the STATus:QUEStionable register. If a bit is set, a transition from 1 to 0 in the condition part causes an entry to be made in the EVENT part of the register.

**Parameters:**

<PTransition>            string

**Example:**                    :STAT:OPER:PTR 32767  
all transitions from 0 to 1 in the condition part of the Status:Questionable register cause an entry to be made in the EVENT part

---

### :STATus:QUEue[:NEXT]?

Queries the oldest entry in the error queue and then deletes it. Positive error numbers denote device-specific errors, and negative error numbers denote error messages defined by SCPI. If the error queue is empty, 0 ("No error") is returned.

The command is identical to :SYSTem:ERRor[:NEXT]? on page 176.

#### Return values:

<Next>                       string

#### Example:

:STATus:QUEue?  
queries the oldest entry in the error queue.  
Response: 0, 'no error'  
no errors have occurred since the error queue was last read out

**Usage:**                     Query only

## 11.18 SYSTem Subsystem

The SYSTem subsystem contains a series of commands for general functions which do not directly affect signal generation.

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---

### :SYSTem:EMODe <Mode>

Enables and selects the eco mode.

#### Parameters:

<Mode>                    OFF | EM1  
                              \*RST:        OFF

**Example:**                See [Chapter 11.1.1, "Performing General Tasks for Instrument Setup"](#), on page 130.

---

### :SYSTem:ERRor:ALL?

Queries the error/event queue for all unread items and removes them from the queue. The response is a comma separated list of error number and a short description of the error in FIFO order.

Positive error numbers are instrument-dependent. Negative error numbers are reserved by the SCPI standard.

#### Return values:

<All>                      string  
                              List of: Error/event\_number,"Error/event\_description>[:Device-dependent info]"  
                              If the queue is empty, the response is 0, "No error"

**Example:**                SYST:ERR:ALL?  
                              queries all entries in the error queue.  
                              Response: 0, 'no error'  
                              No errors have occurred since the error queue was last read out.

**Usage:**                    Query only

---

### :SYSTem:ERRor:CODE:ALL?

Queries all entries in the error queue and then deletes them. Only the error numbers are returned and not the entire error text.

**Return values:**

<All> string  
**0**  
 "No error", i.e. the error queue is empty  
**positive value**  
 Positive error numbers denote device-specific errors  
**negative value**  
 Negative error numbers denote error messages defined by SCPI.

**Example:**

SYST:ERR:CODE:ALL  
 queries all entries in the error queue.  
 Response: 0  
 no errors have occurred since the error queue was last read out.

**Usage:**

Query only

**:SYSTem:ERRor:CODE[:NEXT]?**

Queries the oldest entry in the error queue and then deletes it. Only the error number is returned and not the entire error text.

**Return values:**

<Next> string  
**0**  
 "No error", i.e. the error queue is empty  
**positive value**  
 Positive error numbers denote device-specific errors  
**negative value**  
 Negative error numbers denote error messages defined by SCPI.

**Example:**

SYST:ERR:CODE  
 queries the oldest entry in the error queue.  
 Response: 0  
 No errors have occurred since the error queue was last read out.

**Usage:**

Query only

**:SYSTem:ERRor:COUNt?**

Queries the number of entries in the error queue. If the error queue is empty, '0' is returned.

**Return values:**

<Count> string

**Example:**

SYST:ERR:COUN  
 queries the number of entries in the error queue.  
 Response: 1  
 One error has occurred since the error queue was last read out.

**Usage:** Query only

---

### **:SYSTem:ERRor[:NEXT]?**

Queries the error/event queue for the oldest item and removes it from the queue. The response consists of an error number and a short description of the error.

Positive error numbers are instrument-dependent. Negative error numbers are reserved by the SCPI standard.

**Return values:**

<Next> string  
 Error/event\_number,"Error/event\_description">[;Device-dependent info]"  
 If the queue is empty, the response is 0, "No error"

**Example:**

SYST:ERR?  
 queries the oldest entry in the error queue.  
 Response: 0, 'no error'  
 No errors have occurred since the error queue was last read out.

**Usage:** Query only

---

### **:SYSTem:SERRor?**

Returns a list of all errors existing at the time when the query is started. This list corresponds to the display on the info page under manual control.

**Return values:**

<Serror> string

**Example:**

SYST:SERR  
 queries all errors existing in the error queue.

**Example:**

Response: -221, 'Settings conflict', 153,  
 'Input voltage out of range'  
 The two returned errors have occurred since the error queue was last queried.

**Usage:** Query only

---

### **:SYSTem:VERSion?**

Queries the SCPI version the instrument's command set complies with.

**Return values:**

<Version> string

**Example:**

SYST:VERS  
 queries the SCPI version.  
 Response: "1996"  
 The instrument complies with the SCPI version from 1996.

**Usage:** Query only

---

**:SYSTEM:COMMunicate:NETWork:IPADdress <IpAddress>**

Sets the IP address.

**Parameters:**

<IpAddress>            string  
Range:            0.0.0.0. to ff.ff.ff.ff

**Example:**            SYSTEM:COMMunicate:NETWork:IPADdress '7.8.9.10'  
sets the IP address of the instrument.

**Manual operation:** See "[IP Address](#)" on page 96

---

**:SYSTEM:COMMunicate:NETWork:IPADdress:MODE <Mode>**

Selects manual or automatic setting of the IP address.

**Parameters:**

<Mode>                AUTO | STATic  
\*RST:                AUTO

**Example:**            SYSTEM:COMMunicate:NETWork:IPADdress:MODE AUTO  
the IP address is assigned automatically (DHCP)

**Manual operation:** See "[Address Mode](#)" on page 96

---

**:SYSTEM:COMMunicate:NETWork:MACaddress <MacAddress>**

Queries the MAC address of the network adapter.

**Parameters:**

<MacAddress>        string

**Example:**            SYST:COMM:NETW:MAC  
queries the MAC address.

---

**:SYSTEM:COMMunicate:NETWork:REStart**

Restarts the network connection to the instrument, terminates the connection and sets it up again.

**Example:**            SYSTEM:COMMunicate:NETWork:REStart

**Usage:**                Event

---

**:SYSTEM:COMMunicate:NETWork:STATus?**

Queries the network configuration state.

**Return values:**

<State>                0 | 1 | OFF | ON

**Usage:**                Query only

---



---

**:SYSTem:COMMunicate:NETWork[:COMMON]:HOSTname <Hostname>**

Sets the individual host name of the R&S SGU.

**Note:** it is recommended that you do not change the host name in order to avoid problems with the network connection. However, if you change the host name be sure to use an unique name.

The host name is a protected parameter, To change it, first disable protection level 1 with command `:SYSTem:PROTect<ch>[:STATe]` on page 181.

**Parameters:**

<Hostname>                    string

**Example:**

```
SYSTem:PROTect1:STATe OFF,123456
SYSTem:COMMunicate:NETWork:HOSTname 'SIGGEN'
sets the individual computer name of the R&S SGU.
```

**Manual operation:** See "[Hostname](#)" on page 95

---

**:SYSTem:COMMunicate:NETWork[:IPADdress]:GATeway <Gateway>**

Sets the IP address of the default gateway.

**Parameters:**

<Gateway>                    string  
Range:            0.0.0.0 to ff.ff.ff.ff

**Example:**

```
SYSTem:COMMunicate:NETWork:IPADdress:GATeway
'1.2.3.4'
sets the IP address of the default gateway.
```

**Manual operation:** See "[Default Gateway](#)" on page 96

---

**:SYSTem:COMMunicate:NETWork[:IPADdress]:SUBNet:MASK <Mask>**

Sets the subnet mask.

**Parameters:**

<Mask>                        string

**Example:**

```
SYSTem:COMMunicate:NETWork:IPADdress:SUBNet:
MASK '255.255.0.0'
determines the subnet mask.
```

**Manual operation:** See "[Subnet Mask](#)" on page 96

---

**:SYSTem:COMMunicate:NETWork:RESource?**

Queries the VISA resource string, used for remote control of the instrument with VXI-11 protocol.

**Return values:**

<Resource>                    string

**Example:** SYSTem:COMMunicate:NETWork:RESource?  
Response: "TCPIP::192.1.2.3::INSTR"

**Usage:** Query only

**Manual operation:** See "[Visa Resource Strings](#)" on page 97

---

#### :SYSTem:COMMunicate:HISLip:RESource?

Queries the VISA resource string, used for remote control of the instrument with HiSLIP protocol.

**Return values:**  
<Resource> string

**Example:** SYSTem:COMMunicate:HISLip:RESource?  
Response: "TCPIP::192.1.2.3::hislip0::INSTR"

**Usage:** Query only

**Manual operation:** See "[Visa Resource Strings](#)" on page 97

---

#### :SYSTem:COMMunicate:PClexpress:RESource?

Queries the visa resource string for remote control via the PCIe interface.

**Return values:**  
<Resource> string

**Usage:** Query only

**Manual operation:** See "[Visa Resource Strings](#)" on page 97

---

#### :SYSTem:COMMunicate:SOCKet:RESource?

Queries the visa resource string for remote control via LAN interface, using TCP/IP socket protocol.

**Return values:**  
<Resource> string

**Example:** SYSTem:COMMunicate:SOCKet:RESource?  
Response: "TCPIP::10.113.1.150::5025::SOCKET"

**Usage:** Query only

**Manual operation:** See "[Visa Resource Strings](#)" on page 97

---

#### :SYSTem:COMMunicate:USB:RESource?

Queries the visa resource string for remote control via the USB interface.

**Return values:**  
<Resource> string

**Example:** `SYSTem:COMMunicate:USB:RESource?`  
 queries the VISA resource string for remote control via the USB interface.  
 Response: "USB::72::000000::INSTR"

**Usage:** Query only

**Manual operation:** See "[Visa Resource Strings](#)" on page 97

---

#### **:SYSTem:COMMunicate:SERial:RESource?**

Queries the visa resource string for the serial remote control interface. This string is used for remote control of the instrument.

**Return values:**

<Resource> string

**Example:** `SYSTem:COMMunicate:SERial:RESource?`  
 queries the VISA resource string.  
 Response: "ASRL1::INSTR"

**Usage:** Query only

---

#### **:SYSTem:COMMunicate:SERial:BAUD <Baud>**

Sets the baudrate for the serial remote control interface.

**Parameters:**

<Baud> 2400 | 4800 | 9600 | 19200 | 38400 | 57600 | 115200  
 \*RST: 115200

**Example:** `SYSTem:COMMunicate:SERial:BAUD 115200`  
 determines 115200 baudrate.

---

#### **:SYSTem:COMMunicate:SERial:PARity <Parity>**

Sets the parity for the serial remote control interface.

**Parameters:**

<Parity> NONE | ODD | EVEN  
 \*RST: NONE

**Example:** `SYST:COMM:SER:PAR NONE`  
 selects parity NONE.

---

#### **:SYSTem:COMMunicate:SERial:SBITs <SBits>**

Sets the number of stop bits for the serial remote control interface.

**Parameters:**

<SBits> 1 | 2  
 \*RST: 1

**Example:**               SYST:COMM:SER:SBIT 2  
selects 2 stop bits.

### **:SYSTem:HARDware:ASSEMBly<dir>:SNUMber?**

Queries the list of hardware module serial numbers.

**Suffix:**  
<dir>                    1 | 2  
Defines the section: 1 = common assembly, 2 = RF assembly.

**Return values:**  
<SNumber>               string

**Example:**               SYSTem:HARDware:ASSEMBly1:SNUMber?

**Usage:**                Query only

**Manual operation:**   See "[Assembly](#)" on page 87

### **:SYSTem:MMEMory:PATH:USER?**

Queries the user directory, that means the directory the instrument stores user files on.

**Return values:**  
<PathUser>               string

**Example:**               SYSTem:MMEMory:PATH:USER?  
Response: "/var/user/"

**Usage:**                Query only

### **:SYSTem:OSYSstem?**

Queries the operating system of the instrument.

**Return values:**  
<OperSystem>             string

**Example:**               SYSTem:OSYSstem?  
Response: "Linux"

**Usage:**                Query only

### **:SYSTem:PROtect<ch>[:STATe] <State>[, <Key>]**

Activates/deactivates the specified protection level.

**Parameters:**  
<State>                   select  
\*RST:                    1

**Setting parameters:****<Key>** integer

The respective functions are disabled when the protection level is activated. No password is required for activation. A password must be entered to deactivate the protection level. The password for the first level is 123456.

**Example:**

```
SYSTem:PROTect1:STATe ON
activates protection level 1.
SYSTem:PROTect1:STATe OFF,123456
deactivates protection level 1.
```

**:SYSTem:STARtup:COMPLete?**

Queries if the startup of the instrument is completed.

**Return values:**

**<Complete>** 0 | 1 | OFF | ON  
\*RST: 0

**Example:**

```
SYST:STAR:COMP?
// 1
// the startup of the instrument is completed
```

**Usage:** Query only

## 11.19 TEST Subsystem

The TEST system contains the commands for performing the routines. R&S SGU cannot perform the selftest on its own. Therefore a connection with a signal generator is needed. If you use a compatible R&S signal generator, then the calibration process will be completed automatically after starting the calibration process. Otherwise you have to follow the steps described in "[Calibration process of the R&S SGU](#)" on page 142. In the given example, replace the `:CALibration:xxx:STARt` SCPI command with `:TEST:ALL:STARt` and `:CALibration:xxx:RESult` with `:TEST:ALL:RESult`. We assume that a remote PC is connected to the instruments, the remote PC and the instruments are switched on and a connection between them is established.

The self tests returns a "0" if the test is performed successfully, otherwise a value other than "0" is returned. None of the commands of this system has a \*RST value.

### NOTICE

**Improper use can destroy the assembly**

The respective hardware assembly responds directly to the `:TEST:DIRect` command; any safety mechanisms are bypassed. The command is intended for servicing purposes and should be used only by the Rohde & Schwarz service personnel.

<code>:TEST:ALL:START</code> .....	183
<code>:TEST:ALL:RESult?</code> .....	183
<code>:TEST:KEYBoard[:STATe]</code> .....	183

**:TEST:ALL:START**

Starts a selftest. Use the command `:TEST:ALL:RESult?` to query the result.

Use `:CALibration:HREQuest?` to query for settings required by the instrument.

**Usage:** Event

**:TEST:ALL:RESult?**

Queries the result of the performed selftest. Start the selftest with `:TEST:ALL:START`.

**Return values:**

<Result> 0 | 1 | RUNning | STOPped  
\*RST: STOPped

**Example:** See [Chapter 11.1.1, "Performing General Tasks for Instrument Setup"](#), on page 130.

**Usage:** Query only

**:TEST:KEYBoard[:STATe] <State>**

Enables/disables the keyboard and the LED test state.

**Parameters:**

<State> 0 | 1 | OFF | ON  
\*RST: OFF

## 11.20 UNIT Subsystem

The `UNIT` subsystem contains the commands specifying which units are valid if no unit is indicated in a command. These settings are valid for the entire instrument.

**:UNIT:ANGLE <Angle>**

Sets the default angle unit for remote control. Does not influence the manual control parameter units and the display.

**Parameters:**

<Angle> DEGRee | RADian  
\*RST: RADian

**Example:** `UNIT:ANGL DEG`  
sets DEG as a default unit for all commands which determine angle values.

**:UNIT:POWer** <Power>

Defines the default unit for power parameters. This setting affects the GUI, as well as all remote control commands that determine power values.

**Parameters:**

<Power> V | DBUV | DBM  
\*RST: DBM

**Example:**

UNIT:POW V  
sets V as a default unit for all commands which determine power values.

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## 12 Maintenance

The instrument does not need periodic maintenance. Only cleaning the instrument is essential.

Follow the instructions in the service manual and the safety instructions when exchanging modules or ordering spare parts. The order number for spare parts is included in the service manual. The service manual includes further information particularly on troubleshooting, repair, exchange of modules (including battery exchange, adjustment of the OCXO oscillator) and alignment.

The address of our support center and a list of all Rohde & Schwarz service centers can be found at the beginning of this manual.

### 12.1 Cleaning

The outside of the instrument can be cleaned sufficiently using a soft, lint-free dust cloth. Make sure that the fan openings are not obstructed.

---

**⚠ WARNING****Shock hazard**

Before cleaning the instrument, make sure that the instrument is switched off and disconnected from all power supplies.

---

**NOTICE****Instrument damage caused by cleaning agents**

Cleaning agents contain substances that may damage the instrument. For example, cleaning agents that contain a solvent may damage the front panel labeling, plastic parts, or the display.

Never use cleaning agents such as solvents (thinners, acetone, etc), acids, bases, or other substances.

The outside of the instrument can be cleaned sufficiently using a soft, lint-free dust cloth.

---

**NOTICE****Risk of instrument damage due to obstructed fans**

If the instrument is operated in dusty areas, the fans may become obstructed by dust or other particles in the process of time. Make sure to check and, if necessary, clean the fans regularly to ensure they operate properly at all times. If the instrument is run with obstructed fans for a longer period, it may become overheated which may cause damage.

## 12.2 Storing and Packing

The storage temperature range of the instrument is given in the data sheet. If the instrument is to be stored for a longer period of time, it must be protected against dust.

Repack the instrument as it was originally packed when transporting or shipping. The two protective foam plastic parts prevent the control elements and connectors from being damaged. The antistatic packing foil avoids any undesired electrostatic charging to occur.

If you do not use the original packaging, use a sturdy cardboard box of suitable size and provide for sufficient padding to prevent the instrument from slipping inside the package. Wrap antistatic packing foil around the instrument to protect it from electrostatic charging.

## 13 Error Messages and Troubleshooting

This chapter describes the error messages of the R&S SGU. The error messages are output in the "Info" line on the screen and entered in the error/event queue of the status reporting system.

A great variety of different messages such as status messages, error messages, warnings or information are displayed in the header field of the screen. Some error messages require that the error must be eliminated before correct instrument operation can be ensured. The "Info" window with a list of current messages and a detailed description of each message can be opened with the "Info" button (see also [Chapter 6.2.1, "Info Dialog"](#), on page 53).

### 13.1 Status Information

The status messages are displayed in the Info line of the R&S SGMA-GUI main panel. The status information gives the user an overview of the main operating states and settings of the instrument. The states are indicated for information only and do not necessitate any action by the user.

#### Status Information displayed in the Info line

##### **AttFixed**

Attenuator fixed mode is active.

The uninterrupted level settings are made in a fixed range without attenuator switching. The variation range is set automatically when this mode is activated. The range is displayed with the parameter "SGMA-GUI > Instrument Name > Level > Attenuator Fixed Range".

### 13.2 Error Messages

Messages indicate errors in the instrument. They are displayed in the info line in different colors depending on their importance and display duration. Errors (e.g. no calibration data) are displayed in red, information (e.g. file not found) and warnings in black. Warnings indicate less significant errors (e.g. the instrument operates outside specified data).

See also [Chapter 6.2.1, "Info Dialog"](#), on page 53 and [Chapter 6.2.2, "Understanding the Messages in the Info Bar"](#), on page 55.

#### 13.2.1 Volatile messages

Volatile messages report automatic settings in the instrument (e.g. switching off of incompatible types of modulation) or on illegal entries that are not accepted by the

instrument (e.g. range violations). They are displayed in the info line on a yellow background. They are displayed on top of status information or permanent messages.

Volatile messages do not normally demand user actions and disappear automatically after a brief period of time. They are stored in the history, however.

SCPI command: `:SYSTem:ERRor:ALL?` and `:SYSTem:ERRor[:NEXT]?`.

### 13.2.2 Permanent messages

Permanent messages are displayed if an error occurs that impairs further instrument operation, e.g. a hardware fault. The error signaled by a permanent message must be eliminated before correct instrument operation can be ensured.

The message is displayed until the error is eliminated. It covers the status display in the info line. After error elimination, the message automatically disappears and is also recorded in the history.

SCPI command: `:SYSTem:SERRor?`

## 13.3 SCPI-Error Messages

The SCPI error messages are the same in all SCPI instruments. Detailed information and an overview of all error messages as defined in SCPI standard can be found in the corresponding documentation.

The errors are assigned negative numbers. The error text being entered into the error/event queue or being displayed is printed in bold face on the left together with the error code. Below the error text, there is an explanation as to the respective error.

## 13.4 Device-Specific Error Messages

The following table contains all error messages specific for the instrument in alphabetical order, as well as an explanation of the error situation. The positive error codes mark the errors specific of the instrument.

The device-specific error messages set bit 3 in the ESR register.



The index provides a list of the error messages sorted according to their error codes.

---

Error Code	Error	Description	Remedy
180	Adjustment failed	Adjustment could not be executed	The adjustment data have to be generated first by an internal or external adjustment or to be loaded into the device.
182	Adjustment data missing	Adjustment data are missing.	The adjustment data have to be generated first by an internal or external adjustment or to be loaded into the instrument.
183	Adjustment data invalid	Adjustment data are invalid and must be restored.	The adjustment data have to be generated again by an internal or external adjustment or to be loaded into the instrument.
200	Cannot access hardware	The data transmission to a module was unsuccessful.	The module is not installed, not properly installed or missing.
201	Hardware revision out of date	A later version of certain parts of the instrument is necessary to execute the function selected.	The driver does not support the installed version of a module.
202	Cannot access the EEPROM	A error occurs when writing or reading a EEPROM.	The EEPROM might be defect and has to be replaced.
203	Invalid EEPROM data		
204	Driver initialization failed	Initialization of a driver fails when booting the instrument firmware.	The driver is not compatible with the hardware or software configuration of the instrument.
241	No current list	There is no list selected.	To execute the required operation, a list has to be selected in the related dialog. If no list is available, a new list must be created.
242	Unknown list type specified	The list type selected is not valid for the required operation.  For instance, the file extension for mapping files is *.map. It is not possible to enter another file extension when selecting a list.	Check the selected list type.
460	Cannot open file	The selected file can not be opened.	Check the path and file name.
461	Cannot write file	The file can not be written.	Check if the file is read-only.
462	Cannot read file	The file can not be read.	Check if the file contents are compatible with the file type.
463	Filename missing	The required operation cannot be executed because the file name is not specified.	A file name has to be entered when creating a new list.
464	Invalid filename extension	The file extension is not valid for the required operation.	Check the file extension.  For instance, the file extension for the mapping files is *.map. It is not possible to enter another file extension when storing a list.

<b>Error Code</b>	<b>Error</b>	<b>Description</b>	<b>Remedy</b>
465	File contains invalid data	The selected file contains data that is not valid for the file type.	Check the file extension. The file extension determines the data that is valid for this file type. If the file extension is changed the lists are no longer recognized and the data are therefore invalid.
468	Cannot find directory	Required folder cannot be found.	Check drive and path.
469	No files found	Folder is empty	



# Annex

## A Remote Control Basics

This chapter provides basic information on operating an instrument via remote control.

### A.1 Messages

The messages transferred on the data lines are divided into the following categories:

- **Interface messages**  
Interface messages are transmitted to the instrument on the data lines, with the attention line being active (LOW). They are used to communicate between the controller and the instrument. Interface messages can only be sent by instruments that have GPIB bus functionality. For details see the sections for the required interface.
- **Instrument messages**  
Instrument messages are employed in the same way for all interfaces, if not indicated otherwise in the description. Structure and syntax of the instrument messages are described in [Chapter A.3, "SCPI Command Structure"](#), on page 195. A detailed description of all messages available for the instrument is provided in the chapter "Remote Control Commands".  
There are different types of instrument messages, depending on the direction they are sent:
  - Commands
  - Instrument responses

#### Commands

Commands (program messages) are messages the controller sends to the instrument. They operate the instrument functions and request information. The commands are subdivided according to two criteria:

- According to the effect they have on the instrument:
  - **Setting commands** cause instrument settings such as a reset of the instrument or setting the frequency.
  - **Queries** cause data to be provided for remote control, e.g. for identification of the instrument or polling a parameter value. Queries are formed by directly appending a question mark to the command header.
- According to their definition in standards:
  - **Common commands**: their function and syntax are precisely defined in standard IEEE 488.2. They are employed identically on all instruments (if implemented). They refer to functions such as management of the standardized status registers, reset and self-test.
  - **Instrument control commands** refer to functions depending on the features of the instrument such as frequency settings. Many of these commands have also been standardized by the SCPI committee. These commands are marked as

"SCPI confirmed" in the command reference chapters. Commands without this SCPI label are device-specific; however, their syntax follows SCPI rules as permitted by the standard.

### Instrument responses

Instrument responses (response messages and service requests) are messages the instrument sends to the controller after a query. They can contain measurement results, instrument settings and information on the instrument status.

## A.2 LAN Interface Messages

In the LAN connection, the interface messages are called low-level control messages. These messages can be used to emulate interface messages of the GPIB bus.

Command	Long term	Effect on the instrument
&ABO	Abort	Aborts processing of the commands just received.
&DCL	Device Clear	Aborts processing of the commands just received and sets the command processing software to a defined initial state. Does not change the instrument setting.
&GTL	Go to Local	Transition to the "local" state (manual control). (The instrument automatically returns to remote state when a remote command is sent UNLESS &NREN was sent before.)
&GTR	Go to Remote	Enables automatic transition from local state to remote state by a subsequent remote command (after &NREN was sent).
&GET	Group Execute Trigger	Triggers a previously active instrument function (e.g. a sweep). The effect of the command is the same as with that of a pulse at the external trigger signal input.
&LLO	Local Lockout	Disables transition from remote control to manual control by means of the front panel keys.
&NREN	Not Remote Enable	Disables automatic transition from local state to remote state by a subsequent remote command. (To re-activate automatic transition use &GTR.)
&POL	Serial Poll	Starts a serial poll.

## A.3 SCPI Command Structure

SCPI commands consist of a so-called header and, in most cases, one or more parameters. The header and the parameters are separated by a "white space" (ASCII code 0 to 9, 11 to 32 decimal, e.g. blank). The headers may consist of several mnemonics (keywords). Queries are formed by appending a question mark directly to the header.

The commands can be either device-specific or device-independent (common commands). Common and device-specific commands differ in their syntax.

### A.3.1 Syntax for Common Commands

Common (=device-independent) commands consist of a header preceded by an asterisk (\*) and possibly one or more parameters.

#### Examples:

*RST	RESET	Resets the instrument.
*ESE	EVENT STATUS ENABLE	Sets the bits of the event status enable registers.
*ESR?	EVENT STATUS QUERY	Queries the contents of the event status register.
*IDN?	IDENTIFICATION QUERY	Queries the instrument identification string.

### A.3.2 Syntax for Device-Specific Commands



Not all commands used in the following examples are necessarily implemented in the instrument.

For demonstration purposes only, assume the existence of the following commands for this section:

- DISPLAY[:WINDow<1...4>]:MAXimize <Boolean>
- FORMat:READings:DATA <type>[,<length>]
- HCOpy:DEvIce:COLOr <Boolean>
- HCOpy:DEvIce:CMAP:COLOr:RGB <red>,<green>,<blue>
- HCOpy[:IMMediate]
- HCOpy:ITEM:ALL
- HCOpy:ITEM:LABel <string>
- HCOpy:PAGE:DIMensions:QUADrant [<N>]
- HCOpy:PAGE:ORIENTATION LANDscape | PORTRait
- HCOpy:PAGE:SCALE <numeric value>
- MMEMory:COpy <file\_source>,<file\_destination>
- SENSE:BANDwidth|BWIDth[:RESolution] <numeric\_value>
- SENSE:FREQuency:STOP <numeric value>
- SENSE:LIST:FREQuency <numeric\_value>{,<numeric\_value>}

### Long and short form

The mnemonics feature a long form and a short form. The short form is marked by upper case letters, the long form corresponds to the complete word. Either the short form or the long form can be entered; other abbreviations are not permitted.

#### Example:

`HCOPY:DEVIce:COLor ON` is equivalent to `HCOP:DEV:COL ON`.



### Case-insensitivity

Upper case and lower case notation only serves to distinguish the two forms in the manual, the instrument itself is case-insensitive.

---

### Numeric suffixes

If a command can be applied to multiple instances of an object, e.g. specific channels or sources, the required instances can be specified by a suffix added to the command. Numeric suffixes are indicated by angular brackets (<1...4>, <n>, <i>) and are replaced by a single value in the command. Entries without a suffix are interpreted as having the suffix 1.

#### Example:

Definition: `HCOPY:PAGE:DIMensions:QUADrant [<N>]`

Command: `HCOP:PAGE:DIM:QUAD2`

This command refers to the quadrant 2.



### Different numbering in remote control

For remote control, the suffix may differ from the number of the corresponding selection used in manual operation. SCPI prescribes that suffix counting starts with 1. Suffix 1 is the default state and used when no specific suffix is specified.

Some standards define a fixed numbering, starting with 0. If the numbering differs in manual operation and remote control, it is indicated for the corresponding command.

---

### Optional mnemonics

Some command systems permit certain mnemonics to be inserted into the header or omitted. These mnemonics are marked by square brackets in the description. The instrument must recognize the long command to comply with the SCPI standard. Some commands are considerably shortened by these optional mnemonics.

#### Example:

Definition: `HCOPY[:IMMEDIATE]`

Command: `HCOP:IMM` is equivalent to `HCOP`



### Optional mnemonics with numeric suffixes

Do not omit an optional mnemonic if it includes a numeric suffix that is relevant for the effect of the command.

#### Example:

Definition: `DISPlay[:WINDow<1...4>]:MAXimize <Boolean>`

Command: `DISP:MAX ON` refers to window 1.

In order to refer to a window other than 1, you must include the optional `WINDow` parameter with the suffix for the required window.

`DISP:WIND2:MAX ON` refers to window 2.

### Parameters

Parameters must be separated from the header by a "white space". If several parameters are specified in a command, they are separated by a comma (.). For a description of the parameter types, refer to [Chapter A.3.3, "SCPI Parameters"](#), on page 199.

#### Example:

Definition: `HCOPy:DEVice:CMAP:COLor:RGB <red>,<green>,<blue>`

Command: `HCOP:DEV:CMAP:COL:RGB 3,32,44`

## Special characters

	<p><b>Parameters</b></p> <p>A vertical stroke in parameter definitions indicates alternative possibilities in the sense of "or". The effect of the command differs, depending on which parameter is used.</p> <p><b>Example:</b></p> <p>Definition: <code>HCOPY:PAGE:ORIENTATION LANDscape   PORTRait</code></p> <p>Command <code>HCOPY:PAGE:ORI LAND</code> specifies landscape orientation</p> <p>Command <code>HCOPY:PAGE:ORI PORT</code> specifies portrait orientation</p> <p><b>Mnemonics</b></p> <p>A selection of mnemonics with an identical effect exists for several commands. These mnemonics are indicated in the same line; they are separated by a vertical stroke. Only one of these mnemonics needs to be included in the header of the command. The effect of the command is independent of which of the mnemonics is used.</p> <p><b>Example:</b></p> <p>Definition: <code>SENSE:BANDwidth BWIDTH[:RESolution] &lt;numeric_value&gt;</code></p> <p>The two following commands with identical meaning can be created:</p> <p><code>SENS:BAND:RES 1</code></p> <p><code>SENS:BWID:RES 1</code></p>
[]	<p>Mnemonics in square brackets are optional and may be inserted into the header or omitted.</p> <p><b>Example:</b> <code>HCOPY[:IMMEDIATE]</code></p> <p><code>HCOP:IMM</code> is equivalent to <code>HCOP</code></p>
{ }	<p>Parameters in curly brackets are optional and can be inserted once or several times, or omitted.</p> <p><b>Example:</b> <code>SENSe:LIST:FREQuency &lt;numeric_value&gt;{,&lt;numeric_value&gt;}</code></p> <p>The following are valid commands:</p> <p><code>SENS:LIST:FREQ 10</code></p> <p><code>SENS:LIST:FREQ 10,20</code></p> <p><code>SENS:LIST:FREQ 10,20,30,40</code></p>

### A.3.3 SCPI Parameters

Many commands are supplemented by a parameter or a list of parameters. The parameters must be separated from the header by a "white space" (ASCII code 0 to 9, 11 to 32 decimal, e.g. blank). Allowed parameters are:

- Numeric values
- Special numeric values
- Boolean parameters
- Text
- Character strings
- Block data

The parameters required for each command and the allowed range of values are specified in the command description.

### Numeric values

Numeric values can be entered in any form, i.e. with sign, decimal point and exponent. Values exceeding the resolution of the instrument are rounded up or down. The mantissa may comprise up to 255 characters, the exponent must lie inside the value range -32000 to 32000. The exponent is introduced by an "E" or "e". Entry of the exponent alone is not allowed. In the case of physical quantities, the unit can be entered.

Allowed unit prefixes are G (giga), MA (mega), MOHM and MHZ (also allowed), K (kilo), M (milli), U (micro) and N (nano). If the unit is missing, the basic unit is used.

**Example:** `SENS:FREQ:STOP 1.5GHz = SENS:FREQ:STOP 1.5E9`

### Units

For physical quantities, the unit can be entered. Allowed unit prefixes are:

- G (giga)
- MA (mega), MOHM, MHZ
- K (kilo)
- M (milli)
- U (micro)
- N (nano)

If the unit is missing, the basic unit is used.

### Example:

`SENSe:FREQ:STOP 1.5GHz = SENSe:FREQ:STOP 1.5E9`

Some settings allow relative values to be stated in percent. According to SCPI, this unit is represented by the `PCT` string.

### Example:

`HCOP:PAGE:SCAL 90PCT`

### Special numeric values

The texts listed below are interpreted as special numeric values. In the case of a query, the numeric value is provided.

- **MIN/MAX**  
MINimum and MAXimum denote the minimum and maximum value.
- **DEF**  
DEFault denotes a preset value which has been stored in the EPROM. This value conforms to the default setting, as it is called by the `*RST` command.
- **UP/DOWN**  
UP, DOWN increases or reduces the numeric value by one step. The step width can be specified via an allocated step command for each parameter which can be set via UP, DOWN.
- **INF/NINF**

INFinity, Negative INFinity (NINF) represent the numeric values 9.9E37 or -9.9E37, respectively. INF and NINF are only sent as instrument responses.

- **NAN**

Not A Number (NAN) represents the value 9.91E37. NAN is only sent as a instrument response. This value is not defined. Possible causes are the division of zero by zero, the subtraction of infinite from infinite and the representation of missing values.

**Example:**

Setting command: `SENSe:LIST:FREQ MAXimum`

Query: `SENS:LIST:FREQ?`, Response: `3.5E9`



**Queries for special numeric values**

The numeric values associated to `MAXimum`/`MINimum`/`DEFault` can be queried by adding the corresponding mnemonics to the command. They must be entered following the quotation mark.

Example: `SENSe:LIST:FREQ? MAXimum`

Returns the maximum numeric value as a result.

**Boolean Parameters**

Boolean parameters represent two states. The "ON" state (logically true) is represented by "ON" or a numeric value 1. The "OFF" state (logically untrue) is represented by "OFF" or the numeric value 0. The numeric values are provided as the response for a query.

**Example:**

Setting command: `HCOpy:DEV:COL ON`

Query: `HCOpy:DEV:COL?`

Response: `1`

**Text parameters**

Text parameters observe the syntactic rules for mnemonics, i.e. they can be entered using a short or long form. Like any parameter, they have to be separated from the header by a white space. In the case of a query, the short form of the text is provided.

**Example:**

Setting command: `HCOpy:PAGE:ORientation LANDscape`

Query: `HCOp:PAGE:ORI?`

Response: `LAND`

**Character strings**

Strings must always be entered in quotation marks (' or ").



**Example:**

```
HCOP:ITEM:LABel "Test1" or HCOP:ITEM:LABel 'Test1'
```

**Block data**

Block data is a format which is suitable for the transmission of large amounts of data. A command using a block data parameter has the following structure:

**Example:**

```
FORMat:READings:DATA #45168xxxxxxxx
```

The ASCII character # introduces the data block. The next number indicates how many of the following digits describe the length of the data block. In the example the 4 following digits indicate the length to be 5168 bytes. The data bytes follow. During the transmission of these data bytes all end or other control signs are ignored until all bytes are transmitted.

#0 specifies a data block of indefinite length. The use of the indefinite format requires a `NL^END` message to terminate the data block. This format is useful when the length of the transmission is not known or if speed or other considerations prevent segmentation of the data into blocks of definite length.

### A.3.4 Overview of Syntax Elements

The following table provides an overview of the syntax elements:

:	The colon separates the mnemonics of a command. In a command line the separating semicolon marks the uppermost command level.
;	The semicolon separates two commands of a command line. It does not alter the path.
,	The comma separates several parameters of a command.
?	The question mark forms a query.
*	The asterisk marks a common command.
'' ..	Quotation marks introduce a string and terminate it (both single and double quotation marks are possible).
#	The hash symbol introduces binary, octal, hexadecimal and block data. <ul style="list-style-type: none"> <li>• Binary: #B10110</li> <li>• Octal: #O7612</li> <li>• Hexa: #HF3A7</li> <li>• Block: #21312</li> </ul>
	A "white space" (ASCII-Code 0 to 9, 11 to 32 decimal, e.g. blank) separates the header from the parameters.

### A.3.5 Structure of a command line

A command line may consist of one or several commands. It is terminated by one of the following:

- a <New Line>
- a <New Line> with EOI
- an EOI together with the last data byte

Several commands in a command line must be separated by a semicolon ";". If the next command belongs to a different command system, the semicolon is followed by a colon.

**Example:**

```
MMEM:COPY "Test1", "MeasurementXY";:HCOP:ITEM ALL
```

This command line contains two commands. The first command belongs to the MMEM system, the second command belongs to the HCOP system.

If the successive commands belong to the same system, having one or several levels in common, the command line can be abbreviated. To this end, the second command after the semicolon starts with the level that lies below the common levels. The colon following the semicolon must be omitted in this case.

**Example:**

```
HCOP:ITEM ALL;:HCOP:IMM
```

This command line contains two commands. Both commands are part of the HCOP command system, i.e. they have one level in common.

When abbreviating the command line, the second command begins with the level below HCOP. The colon after the semicolon is omitted. The abbreviated form of the command line reads as follows:

```
HCOP:ITEM ALL;IMM
```

A new command line always begins with the complete path.

**Example:**

```
HCOP:ITEM ALL
```

```
HCOP:IMM
```

### A.3.6 Responses to Queries

A query is defined for each setting command unless explicitly specified otherwise. It is formed by adding a question mark to the associated setting command. According to SCPI, the responses to queries are partly subject to stricter rules than in standard IEEE 488.2.

- The requested parameter is transmitted without a header.  
**Example:** `HCOP:PAGE:ORI?`, **Response:** `LAND`
- Maximum values, minimum values and all other quantities that are requested via a special text parameter are returned as numeric values.  
**Example:** `SENSe:FREQuency:STOP? MAX`, **Response:** `3.5E9`

- Numeric values are output without a unit. Physical quantities are referred to the basic units or to the units set using the `Unit` command. The response `3.5E9` in the previous example stands for 3.5 GHz.
- Truth values (Boolean values) are returned as 0 (for OFF) and 1 (for ON).

**Example:**

Setting command: `HCOPY:DEV:COL ON`

Query: `HCOPY:DEV:COL?`

Response: 1

- Text (character data) is returned in a short form.

**Example:**

Setting command: `HCOPY:PAGE:ORIENTATION LANDscape`

Query: `HCOP:PAGE:ORI?`

Response: LAND

## A.4 Command Sequence and Synchronization

IEEE 488.2 defines a distinction between overlapped and sequential commands:

- A sequential command is one which finishes executing before the next command starts executing. Commands that are processed quickly are usually implemented as sequential commands. Sequential commands are not implemented in the instrument, however the execution time of most commands is so short that they act as sequential commands when sent in different command lines.
- An overlapping command is one which does not automatically finish executing before the next command starts executing. Usually, overlapping commands take longer to process and allow the program to do other tasks while being executed. If overlapping commands do have to be executed in a defined order, e.g. in order to avoid wrong measurement results, they must be serviced sequentially. This is called synchronization between the controller and the instrument.

Setting commands within one command line, even though they may be implemented as sequential commands, are not necessarily serviced in the order in which they have been received. In order to make sure that commands are actually carried out in a certain order, each command must be sent in a separate command line.



As a general rule, send commands and queries in different program messages.

### A.4.1 Preventing Overlapping Execution

To prevent an overlapping execution of commands, one of the commands `*OPC`, `*OPC?` or `*WAI` can be used. All three commands cause a certain action only to be carried out after the hardware has been set. By suitable programming, the controller can be forced to wait for the corresponding action to occur.

**Table A-1: Synchronization using \*OPC, \*OPC? and \*WAI**

Command	Action	Programming the controller
*OPC	Sets the Operation Complete bit in the ESR after all previous commands have been executed.	<ul style="list-style-type: none"> <li>Setting bit 0 in the ESE</li> <li>Setting bit 5 in the SRE</li> <li>Waiting for service request (SRQ)</li> </ul>
*OPC?	Stops command processing until 1 is returned. This is only the case after the Operation Complete bit has been set in the ESR. This bit indicates that the previous setting has been completed.	Sending *OPC? directly after the command whose processing should be terminated before other commands can be executed.
*WAI	Stops further command processing until all commands sent before *WAI have been executed.	Sending *WAI directly after the command whose processing should be terminated before other commands are executed.

Command synchronization using \*WAI or \*OPC? is a good choice if the overlapped command takes only little time to process. The two synchronization commands simply block overlapped execution of the command. Append the synchronization command to the overlapping command, for example:

```
SINGLE; *OPC?
```

For time consuming overlapped commands you can allow the controller or the instrument to do other useful work while waiting for command execution. Use one of the following methods:

#### **\*OPC with a service request**

1. Set the OPC mask bit (bit no. 0) in the ESE: \*ESE 1
2. Set bit no. 5 in the SRE: \*SRE 32 to enable ESB service request.
3. Send the overlapped command with \*OPC
4. Wait for a service request

The service request indicates that the overlapped command has finished.

#### **\*OPC? with a service request**

1. Set bit no. 4 in the SRE: \*SRE 16 to enable MAV service request.
2. Send the overlapped command with \*OPC?
3. Wait for a service request

The service request indicates that the overlapped command has finished.

#### **Event Status Register (ESE)**

1. Set the OPC mask bit (bit no. 0) in the ESE: \*ESE 1
2. Send the overlapped command without \*OPC, \*OPC? or \*WAI

3. Poll the operation complete state periodically (by means of a timer) using the sequence: \*OPC; \*ESR?

A return value (LSB) of 1 indicates that the overlapped command has finished.

## A.5 Status Reporting System

The status reporting system stores all information on the current operating state of the instrument, and on errors which have occurred. This information is stored in the status registers and in the error queue.

You can query both with the commands of the [STATus Subsystem](#).

### A.5.1 Hierarchy of the Status Registers

The [Figure A-1](#) shows the hierarchical structure of information in the status registers (ascending from left to right).

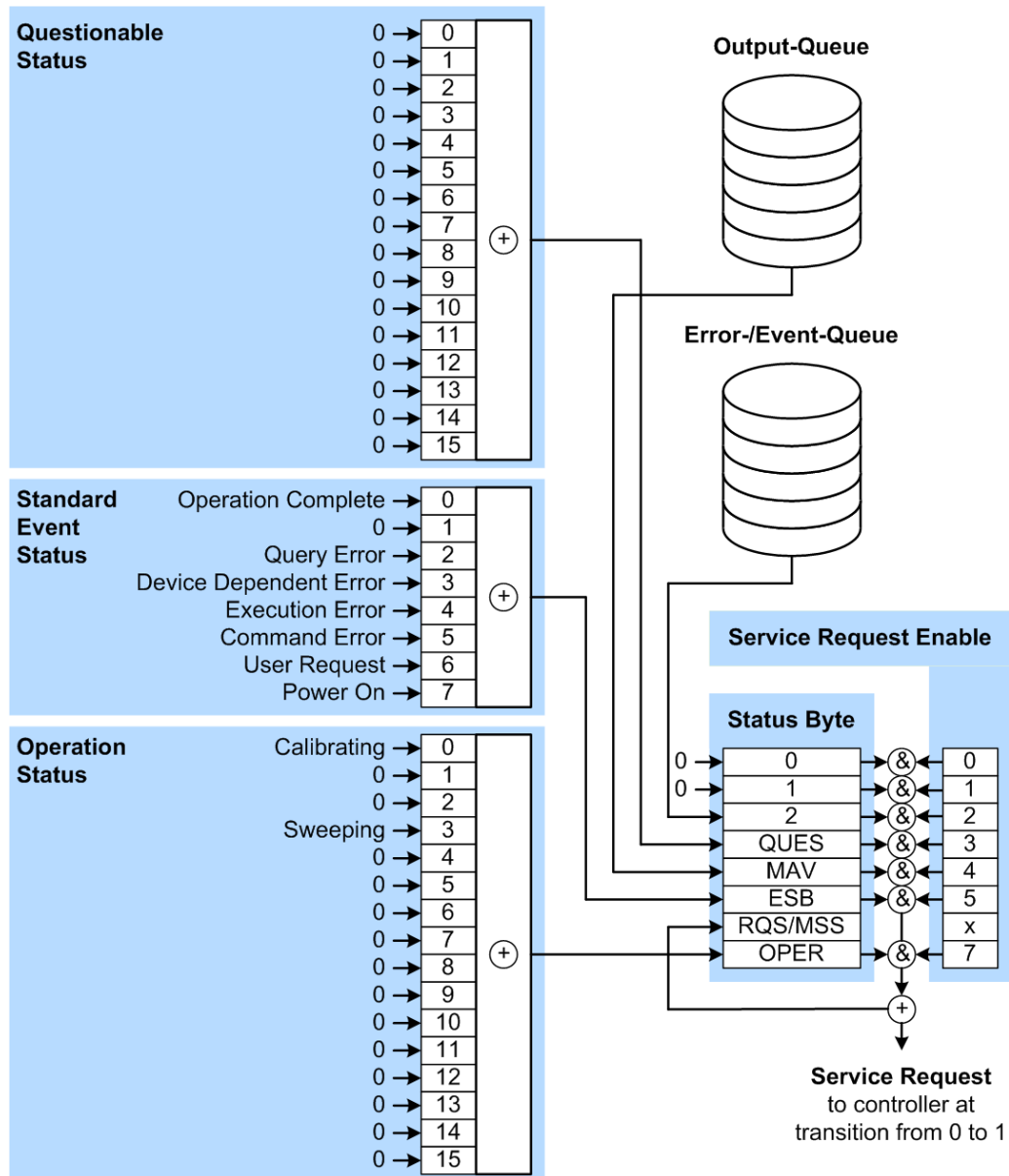


Figure A-1: Graphical overview of the status registers hierarchy

- OPER = Operation Status Summary Bit
- RQS/MSS = Service Request Generation
- ESB = Standard Event Status Summary Bit
- MAV = Message Available in Output Queue
- QUES = Questionable Status Summary Bit
- 2 = Error- /Event-Queue
- 1, 0 = not used

**Note:** This legend explains the abbreviations to the Status Byte Register.

The R&S SGU uses the following status registers:

- **Status Byte (STB)** and **Service Request Enable (SRE)**, see [Chapter A.5.3, "Status Byte \(STB\) and Service Request Enable Register \(SRE\)"](#), on page 210.

- **Standard Event Status**, i.e. the Event status Register (ESR) and the Event Status Enable (ESE), see [Chapter A.5.4, "Event Status Register \(ESR\) and Event Status Enable Register \(ESE\)"](#), on page 211.
- **Questionable Status and Operation Status**, the (SCPI status registers, see [Chapter A.5.2, "Structure of a SCPI Status Register"](#), on page 208, [Chapter A.5.5, "Questionable Status Register \(STATus:QUEStionable\)"](#), on page 211 and [Chapter A.5.6, "Operation Status Register \(STATus:OPERation\)"](#), on page 212.
- **Output-Queue**  
The output queue contains the messages the instrument returns to the controller. It is not part of the status reporting system but determines the value of the MAV bit in the STB and thus is represented in the overview.
- **Error- /Event-Queue**  
The error-/event-queue contains all errors and events that have occurred in the past. When reading the queue, the instrument starts with the first occurred error/ event.

All status registers have the same internal structure.



**SRE, ESE**

The service request enable register SRE can be used as ENABLE part of the STB if the STB is structured according to SCPI. By analogy, the ESE can be used as the ENABLE part of the ESR.

**A.5.2 Structure of a SCPI Status Register**

Each standard SCPI register consists of 5 parts. Each part has a width of 16 bits and has different functions. The individual bits are independent of each other, i.e. each hardware status is assigned a bit number which is valid for all five parts. Bit 15 (the most significant bit) is set to zero for all parts. Thus the contents of the register parts can be processed by the controller as positive integers.

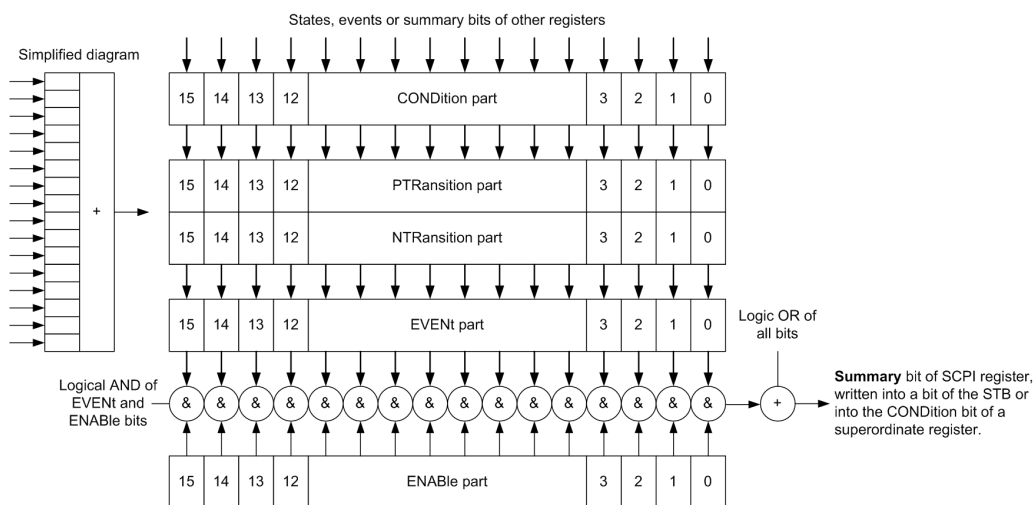


Figure A-2: The status-register model

### Description of the five status register parts

The five parts of a SCPI register have different properties and functions:

- **CONDition**

The `CONDition` part is written into directly by the hardware or the sum bit of the next lower register. Its contents reflect the current instrument status. This register part can only be read, but not written into or cleared. Its contents are not affected by reading.

- **PTRansition / NTRansition**

The two transition register parts define which state transition of the `CONDition` part (none, 0 to 1, 1 to 0 or both) is stored in the `EVENT` part.

The **Positive-TRansition** part acts as a transition filter. When a bit of the `CONDition` part is changed from 0 to 1, the associated `PTR` bit decides whether the `EVENT` bit is set to 1.

- `PTR` bit =1: the `EVENT` bit is set.
- `PTR` bit =0: the `EVENT` bit is not set.

This part can be written into and read as required. Its contents are not affected by reading.

The **Negative-TRansition** part also acts as a transition filter. When a bit of the `CONDition` part is changed from 1 to 0, the associated `NTR` bit decides whether the `EVENT` bit is set to 1.

- `NTR` bit =1: the `EVENT` bit is set.
- `NTR` bit =0: the `EVENT` bit is not set.

This part can be written into and read as required. Its contents are not affected by reading.

- **EVENT**

The `EVENT` part indicates whether an event has occurred since the last reading, it is the "memory" of the condition part. It only indicates events passed on by the transition filters. It is permanently updated by the instrument. This part can only be read by the user. Reading the register clears it. This part is often equated with the entire register.

- **ENABLE**

The `ENABLE` part determines whether the associated `EVENT` bit contributes to the sum bit (see below). Each bit of the `EVENT` part is "ANDed" with the associated `ENABLE` bit (symbol '&'). The results of all logical operations of this part are passed on to the sum bit via an "OR" function (symbol '+').

`ENABLE` bit = 0: the associated `EVENT` bit does not contribute to the sum bit

`ENABLE` bit = 1: if the associated `EVENT` bit is "1", the sum bit is set to "1" as well.

This part can be written into and read by the user as required. Its contents are not affected by reading.

### Sum bit

The sum bit is obtained from the `EVENT` and `ENABLE` part for each register. The result is then entered into a bit of the `CONDition` part of the higher-order register.



The instrument automatically generates the sum bit for each register. Thus an event can lead to a service request throughout all levels of the hierarchy.

### A.5.3 Status Byte (STB) and Service Request Enable Register (SRE)

The `STatus Byte` (STB) is already defined in IEEE 488.2. It provides a rough overview of the instrument status by collecting the pieces of information of the lower registers. A special feature is that bit 6 acts as the sum bit of the remaining bits of the status byte.

The STB is read using the command `*STB?` or a serial poll.

The `STatus Byte` (STB) is linked to the `Service Request Enable` (SRE) register. Each bit of the STB is assigned a bit in the SRE. Bit 6 of the SRE is ignored. If a bit is set in the SRE and the associated bit in the STB changes from 0 to 1, a service request (SRQ) is generated. The SRE can be set using the command `*SRE` and read using the command `*SRE?`.

**Table A-2: Meaning of the bits used in the status byte**

Bit No.	Meaning
0...1	Not used
2	Error Queue not empty The bit is set when an entry is made in the error queue. If this bit is enabled by the SRE, each entry of the error queue generates a service request. Thus an error can be recognized and specified in greater detail by polling the error queue. The poll provides an informative error message. This procedure is to be recommended since it considerably reduces the problems involved with remote control.
3	QUESTionable status register summary bit The bit is set if an <code>EVENT</code> bit is set in the <code>QUESTionable</code> status register and the associated <code>ENABLE</code> bit is set to 1. A set bit indicates a questionable instrument status, which can be specified in greater detail by querying the <code>STATus:QUESTionable</code> status register.
4	MAV bit (message available) The bit is set if a message is available in the output queue which can be read. This bit can be used to enable data to be automatically read from the instrument to the controller.
5	ESB bit Sum bit of the event status register. It is set if one of the bits in the event status register is set and enabled in the event status enable register. Setting of this bit indicates a serious error which can be specified in greater detail by polling the event status register.
6	MSS bit (master status summary bit) The bit is set if the instrument triggers a service request. This is the case if one of the other bits of this registers is set together with its mask bit in the service request enable register SRE.
7	<code>STATus:OPERation</code> status register summary bit The bit is set if an <code>EVENT</code> bit is set in the <code>OPERation</code> status register and the associated <code>ENABLE</code> bit is set to 1. A set bit indicates that the instrument is just performing an action. The type of action can be determined by querying the <code>STATus:OPERation</code> status register.

### A.5.4 Event Status Register (ESR) and Event Status Enable Register (ESE)

The ESR is defined in IEEE 488.2. It can be compared with the `EVENT` part of a SCPI register. The event status register can be read out using command `*ESR?`.

The ESE corresponds to the `ENABLE` part of a SCPI register. If a bit is set in the ESE and the associated bit in the ESR changes from 0 to 1, the ESB bit in the STB is set. The ESE register can be set using the command `*ESE` and read using the command `*ESE?`.

**Table A-3: Meaning of the bits used in the event status register**

Bit No.	Meaning
0	Operation Complete This bit is set on receipt of the command <code>*OPC</code> exactly when all previous commands have been executed.
1	Not used
2	Query Error This bit is set if either the controller wants to read data from the instrument without having sent a query, or if it does not fetch requested data and sends new instructions to the instrument instead. The cause is often a query which is faulty and hence cannot be executed.
3	Device-dependent Error This bit is set if a device-dependent error occurs. An error message with a number between -300 and -399 or a positive error number, which denotes the error in greater detail, is entered into the error queue.
4	Execution Error This bit is set if a received command is syntactically correct but cannot be performed for other reasons. An error message with a number between -200 and -300, which denotes the error in greater detail, is entered into the error queue.
5	Command Error This bit is set if a command is received, which is undefined or syntactically incorrect. An error message with a number between -100 and -200, which denotes the error in greater detail, is entered into the error queue.
6	User Request This bit is set when the instrument is switched over to manual control.
7	Power On (supply voltage on) This bit is set on switching on the instrument.

### A.5.5 Questionable Status Register (STATus:QUESTionable)

This register contains information on questionable instrument states. Such states may occur when the instrument is not operated in compliance with its specifications.

To read the register, use the query commands `STAT:QUEST:COND?` or `STAT:QUEST[:EVEN]?`.

*Table A-4: Meaning of the bits used in the questionable status register*

Bit No.	Meaning
0–15	Not used

## A.5.6 Operation Status Register (STATus:OPERation)

This condition part contains information on the actions currently being performed by the instrument, while the event part contains information on the actions performed by the instrument since the last readout of the register.

To read the register, use the query commands `STAT:OPER:COND?` or `STAT:OPER[:EVEN]?`.

*Table A-5: Meaning of the bits used in the operation status register*

Bit No.	Meaning
0	Calibrating The bit is set during the calibration phase.
1–2	Not used
3	Sweeping This bit is set during a sweep in automatic or single mode.
4–15	Not used

## A.5.7 Application of the Status Reporting System

The purpose of the status reporting system is to monitor the status of one or several devices in a measuring system. To do this and react appropriately, the controller must receive and evaluate the information of all devices. The following standard methods are used:

- **Service request** (SRQ) initiated by the instrument
- **Serial poll** of all devices in the bus system, initiated by the controller to find out who sent an SRQ and why
- Query of a **specific instrument status** by commands
- Query of the **error queue**

### A.5.7.1 Service Request

Under certain circumstances, the instrument can send a service request (SRQ) to the controller. Usually this service request initiates an interrupt at the controller, to which the control program can react appropriately. An SRQ is always initiated if one or several of bits 2, 4 or 5 of the status byte are set and enabled in the SRE. Each of these bits combines the information of the error queue or the output buffer. To use the possibilities of the service request effectively, all bits should be set to "1" in the enable registers SRE and ESE.

**Example:**

Use command `*OPC` to generate an SRQ .

`*ESE 1` - set bit 0 of ESE (Operation Complete)

`*SRE 32` - set bit 5 of SRE (ESB).

After its settings have been completed, the instrument generates an SRQ.

The SRQ is the only possibility for the instrument to become active on its own. Each controller program should set the instrument such that a service request is initiated in the case of malfunction. The program should react appropriately to the service request.

### A.5.7.2 Serial Poll

In a serial poll, just as with command `*STB`, the status byte of an instrument is queried. However, the query is realized via interface messages and is thus clearly faster.

The serial poll method is defined in IEEE 488.1 and used to be the only standard possibility for different instruments to poll the status byte. The method also works for instruments which do not adhere to SCPI or IEEE 488.2.

The serial poll is mainly used to obtain a fast overview of the state of several instruments connected to the controller.

### A.5.7.3 Query of an instrument status

Each part of any status register can be read using queries. There are two types of commands:

- The common commands `*ESR?`, `*IDN?`, `*IST?`, `*STB?` query the higher-level registers.
- The commands of the `STATus` system query the SCPI registers (`STATus:QUEStionable...`)

The returned value is always a decimal number that represents the bit pattern of the queried register. This number is evaluated by the controller program.

Queries are usually used after an SRQ in order to obtain more detailed information on the cause of the SRQ.

### A.5.7.4 Error Queue

Each error state in the instrument leads to an entry in the error queue. The entries of the error queue are detailed plain text error messages that can be looked up in the Error Log or queried via remote control using `SYSTEM:ERROR[:NEXT]?`. Each call of `SYSTEM:ERROR[:NEXT]?` provides one entry from the error queue. If no error messages are stored there any more, the instrument responds with 0, "No error".

The error queue should be queried after every SRQ in the controller program as the entries describe the cause of an error more precisely than the status registers. Especially in the test phase of a controller program the error queue should be queried regu-

larly since faulty commands from the controller to the instrument are recorded there as well.

### A.5.8 Reset Values of the Status Reporting System

The following table contains the different commands and events causing the status reporting system to be reset. None of the commands, except of \*RST and SYSTem:PRESet affect the functional instrument settings. In particular, DCL does not change the instrument settings.

**Table A-6: Resetting the status reporting system**

Event	Switching on supply voltage Power-On-Status-Clear		DCL, SDC  (Device Clear, Selected Device Clear)	*RST or SYSTem: PRESet	STATus: PRESet	*CLS
	0	1				
Clear STB, ESR	-	Yes	-	-	-	Yes
Clear SRE, ESE	-	Yes	-	-	-	-
Clear PPE	-	Yes	-	-	-	-
Clear error queue	Yes	Yes	-	-	-	Yes
Clear output buffer	Yes	Yes	Yes	1)	1)	1)
Clear command processing and input buffer	Yes	Yes	Yes	-	-	-

1) The first command in a command line that immediately follows a <PROGRAM MESSAGE TERMINATOR> clears the output buffer.

## A.6 General Programming Recommendations

### Initial instrument status before changing settings

Manual operation is designed for maximum possible operating convenience. In contrast, the priority of remote control is the "predictability" of the instrument status. Thus, when a command attempts to define incompatible settings, the command is ignored and the instrument status remains unchanged, i.e. other settings are not automatically adapted. Therefore, control programs should always define an initial instrument status (e.g. using the \*RST command) and then implement the required settings.

### Command sequence

As a general rule, send commands and queries in different program messages. Otherwise, the result of the query may vary depending on which operation is performed first (see also Preventing Overlapping Execution).

**Reacting to malfunctions**

The service request is the only possibility for the instrument to become active on its own. Each controller program should instruct the instrument to initiate a service request in case of malfunction. The program should react appropriately to the service request.

**Error queues**

The error queue should be queried after every service request in the controller program as the entries describe the cause of an error more precisely than the status registers. Especially in the test phase of a controller program the error queue should be queried regularly since faulty commands from the controller to the instrument are recorded there as well.

## B Telnet program examples

The following program example shows a simple `TcpClient` class that is intended to explain on how to get started with programming of sockets.

The example sets up a socket communication to R&S SGU and opens a simple user interface, very similar to the telnet, which allows input of commands. To enable real automation, further development of the program is required.

### TcpClient.h

```
#include <string>
//defines structs for socket handling
#include <netinet/in.h>
using namespace std;
typedef struct sockaddr_in SockAddrStruct;
typedef struct hostent      HostInfoStruct;
class TcpClient
{
public:
    TcpClient();
    ~TcpClient();
    void connectToServer( string &hostname, int port );
    void disconnect( );
    void transmit( string &txString );
    void receive( string &rxString );
    string getCurrentHostName( ) const;
    int    getCurrentPort( ) const;
private:
    string      currentHostName;
    int        currentPort;
    int        currentSocketDescr;
    SockAddrStruct serverAddress;
    HostInfoStruct * currentHostInfo;
    bool       clientIsConnected;
    int       receiveBufferSize;
};
```

### TcpClient.cpp

```
#include <string>
//defines structs for socket handling
#include <netinet/in.h>
using namespace std;
typedef struct sockaddr_in SockAddrStruct;
typedef struct hostent      HostInfoStruct;
class TcpClient
{
public:
    TcpClient();
```

```

~TcpClient();
void connectToServer( string &hostname, int port );
void disconnect( );
void transmit( string &txString );
void receive( string &rxString );
string getCurrentHostName( ) const;
int    getCurrentPort( ) const;
private:
    string          currentHostName;
    int             currentPort;
    int             currentSocketDescr;
    SockAddrStruct  serverAddress;
    HostInfoStruct * currentHostInfo;
    bool            clientIsConnected;
    int             receiveBufferSize;
};

#include <netdb.h>
#include <netinet/in.h>
#include <unistd.h>
#include "TcpClient.h"
TcpClient::TcpClient()
: currentHostName( "" )
, currentPort( 0 )
, currentSocketDescr( 0 )
, serverAddress ( )
, currentHostInfo( NULL )
, clientIsConnected( false )
, receiveBufferSize( 1024 )
{
}
TcpClient::~TcpClient()
{
    currentHostInfo = NULL;
}

void TcpClient::connectToServer( string &hostname, int port )
{
    currentHostInfo = gethostbyname( hostname.c_str( ) );
    if( currentHostInfo == NULL )
    {
        currentHostName = "";
        currentPort      = 0;
        currentHostInfo  = NULL;
        clientIsConnected = false;
        printf("error connecting host\n" );
    }
    currentHostName = hostname;
    currentPort     = port;
    currentSocketDescr = socket(AF_INET, SOCK_STREAM, 0);

```



```

if( currentSocketDescr == 0 )
{
    currentHostName = "";
    currentPort      = 0;
    currentHostInfo  = NULL;
    clientIsConnected = false;
    printf("can't create socket\n" );
}
serverAddress.sin_family = currentHostInfo->h_addrtype;
serverAddress.sin_port   = htons( currentPort );
memcpy( (char *) &serverAddress.sin_addr.s_addr,
currentHostInfo->h_addr_list[0], currentHostInfo->h_length );
if( connect( currentSocketDescr, ( struct sockaddr *) &serverAddress,
sizeof( serverAddress ) ) < 0 )
{
    throw string("can't connect server\n" );
}
clientIsConnected = true;
}
void TcpClient::disconnect( )
{
    if( clientIsConnected )
    {
        close( currentSocketDescr );
    }
    currentSocketDescr = 0;
    currentHostName    = "";
    currentPort        = 0;
    currentHostInfo    = NULL;
    clientIsConnected  = false;
}
void TcpClient::transmit( string &txString )
{
    if( !clientIsConnected )
    {
        throw string("connection must be established before any data can be sent\n");
    }
    char * transmitBuffer = new char[txString.length() +1];
    memcpy( transmitBuffer, txString.c_str(), txString.length() );
    transmitBuffer[txString.length()] = '\n'; //newline is needed!
    if( send( currentSocketDescr, transmitBuffer, txString.length() + 1, 0 ) < 0 )
    {
        throw string("can't transmit data\n");
    }
    delete [] transmitBuffer;
}
void TcpClient::receive( string &rxString )
{
    if( !clientIsConnected )
    {

```

```

    throw string("connection must be established before any data can be received\n");
}
char * receiveBuffer = new char[receiveBufferSize];
memset( receiveBuffer, 0, receiveBufferSize );
bool receiving = true;
while( receiving )
{
    int receivedByteCount = recv( currentSocketDescr,
    receiveBuffer, receiveBufferSize, 0 );
    if( receivedByteCount < 0 )
    {
        throw string("error while receiving data\n");
    }
    rxString += string( receiveBuffer );
    receiving = ( receivedByteCount == receiveBufferSize );
}
delete [] receiveBuffer;
}
string TcpClient::getCurrentHostName( ) const
{
    return currentHostName;
}
int TcpClient::getCurrentPort( ) const
{
    return currentPort;
}

```

### TelnetClient.cpp

```

#include <iostream>
#include "TcpClient.h"
void printUsage()
{
    cout<<"usage: EthernetRawCommand <server-ip> [scpi-command]"<<endl;
}
int main( int argc, char *argv[] )
{
    int errorCode          = 0; //no error
    bool useSingleCommand = false;
    string singleCommand  = "";
    string hostname       = "";
    int   port            = 5025;
    string input          = "";
    TcpClient client;
    switch( argc )
    {
        case 3:
            useSingleCommand = true;
            singleCommand     = argv[2];
        case 2:
    }
}

```

```

        hostname      = argv[1];
        break;
    default:
        printUsage();
        return(-1);
    }
    try
    {
        client.connectToServer( hostname, port );
        bool terminate = false;
        while( !terminate )
        {
            char buffer[1024];
            if( useSingleCommand )
            {
                input = singleCommand; //send string
            }
            else
            {
                cin.getline( buffer, 1024 );
                input = buffer;
                if( input == "end" )
                {
                    terminate = true;
                }
            }
            if( !terminate)
            {
                client.transmit( input ); //send string
                int qPos = input.find( "?", 0 );
                //receive string only when needed
                if( qPos > 0 )
                {
                    string rcStr = "";
                    client.receive( rcStr );
                    cout << rcStr << endl;
                }
            }
            if( useSingleCommand )
            {
                terminate = true;
            }
        }
    }catch( const string errorString )
    {
        cout<<errorString<<endl;
    }
    client.disconnect( );
    return errorCode;
}

```

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